



FEniCS Course

Lecture 12: Computing sensitivities

Contributors

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But often we are also interested the sensitivity with respect to certain parameters, for example

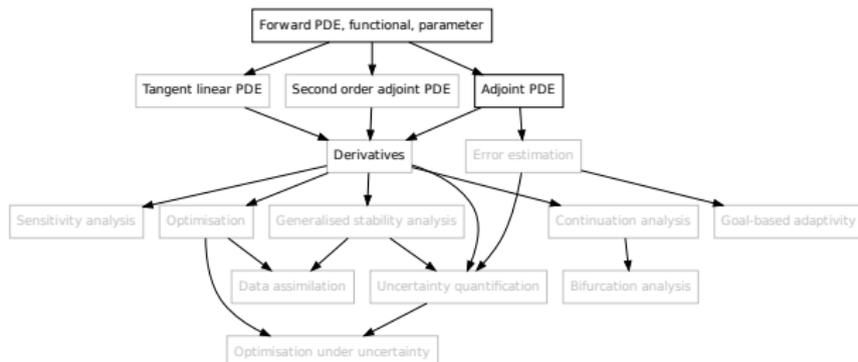
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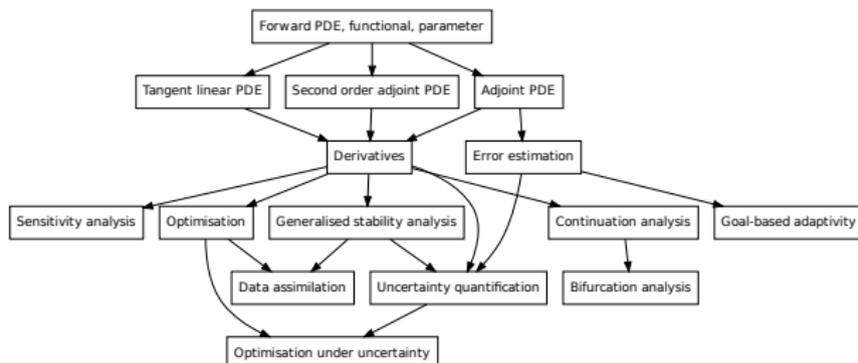


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Example

Consider the Poisson's equation

$$\begin{aligned} -\nu \Delta u &= m && \text{in } \Omega, \\ u &= 0 && \text{on } \partial\Omega, \end{aligned}$$

together with the *objective functional*

$$J(u) = \frac{1}{2} \int_{\Omega} \|u - u_d\|^2 dx,$$

where u_d is a known function.

Goal

Compute the sensitivity of J with respect to the *parameter* m : dJ/dm .

Comput. deriv. (i) General formulation

Given

- Parameter m ,
- PDE $F(u, m) = 0$ with solution u .
- Objective functional $J(u, m) \rightarrow \mathbb{R}$,

Goal

Compute dJ/dm .

Reduced functional

Consider u as an implicit function of m by solving the PDE.
With that we define the *reduced functional* R :

$$R(m) = J(u(m), m)$$

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Comput. deriv. (ii) Reduced functional

Reduced functional:

$$R(m) \equiv J(u(m), m).$$

Taking the derivative of with respect to m yields:

$$\frac{dR}{dm} = \frac{dJ}{dm} = \frac{\partial J}{\partial u} \frac{du}{dm} + \frac{\partial J}{\partial m}.$$

Computing $\frac{\partial J}{\partial u}$ and $\frac{\partial J}{\partial m}$ is straight-forward, but how handle $\frac{du}{dm}$?

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$$\frac{dF}{dm} = \frac{\partial F}{\partial u} \frac{du}{dm} + \frac{\partial F}{\partial m} = 0$$

Hence:

$$\frac{du}{dm} = - \left(\frac{\partial F}{\partial u} \right)^{-1} \frac{\partial F}{\partial m}$$

Final formula for functional derivative

$$\frac{dJ}{dm} = - \overbrace{\frac{\partial J}{\partial u} \left(\frac{\partial F}{\partial u} \right)^{-1} \frac{\partial F}{\partial m}}^{\text{adjoint PDE}} + \frac{\partial J}{\partial m},$$

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Dimensions of a finite dimensional example

$$\frac{dJ}{dm} = \underbrace{\left[-\frac{\partial J}{\partial u} \right] \times \left[\left(\frac{\partial F}{\partial u} \right)^{-1} \right] \times \left[\frac{\partial F}{\partial m} \right]}_{\text{discretised tangent linear PDE}} + \left[\frac{\partial J}{\partial m} \right]$$

discretised adjoint PDE

The tangent linear solution is a matrix of dimension $|u| \times |m|$ and requires the solution of m linear systems. The adjoint solution is a vector of dimension $|u|$ and requires the solution of one linear systems.

Adjoint approach

- 1 Solve the adjoint equation for λ

$$\frac{\partial F^*}{\partial u} \lambda = -\frac{\partial J^*}{\partial u}.$$

- 2 Compute

$$\frac{dJ}{dm} = \lambda^* \frac{\partial F}{\partial m} + \frac{\partial J}{\partial m}.$$

The computational expensive part is (1). It requires solving the (linear) adjoint PDE, and its cost is independent of the choice of parameter m .