



Adaptive Finite Element methods for incompressible fluid flow

Claes Johnson and Johan Hoffman

`claes@math.chalmers.se, hoffman@math.chalmers.se`

Chalmers Finite Element Center

3 lectures

1. Adaptive FE methods for incompr. fluid flow
2. Hydrodynamic stability
3. Subgrid modeling & multi adaptivity

Lecture 2: Hydrodynamic stability

Error propagation:

- A posteriori error estimates using duality
- Upper bound on solutions to the linearized dual NSE for computability

Perturbation growth:

- Bifurcation / Transition to turbulence
- Lower bound on perturbations for bifurcation / transition to take place

Computability

What quantities are computable? To what tolerance? To what cost?

That is: What quantities can be computed with a sufficiently small computational error?

Computability

$$\text{Computational error} \leq SC \|R(U)\|$$

Interpolation constant C , depends only on what finite elements used

The stability factor S depends on the solution of the linearized dual problem related to the problem and the quantity we are trying to approximate

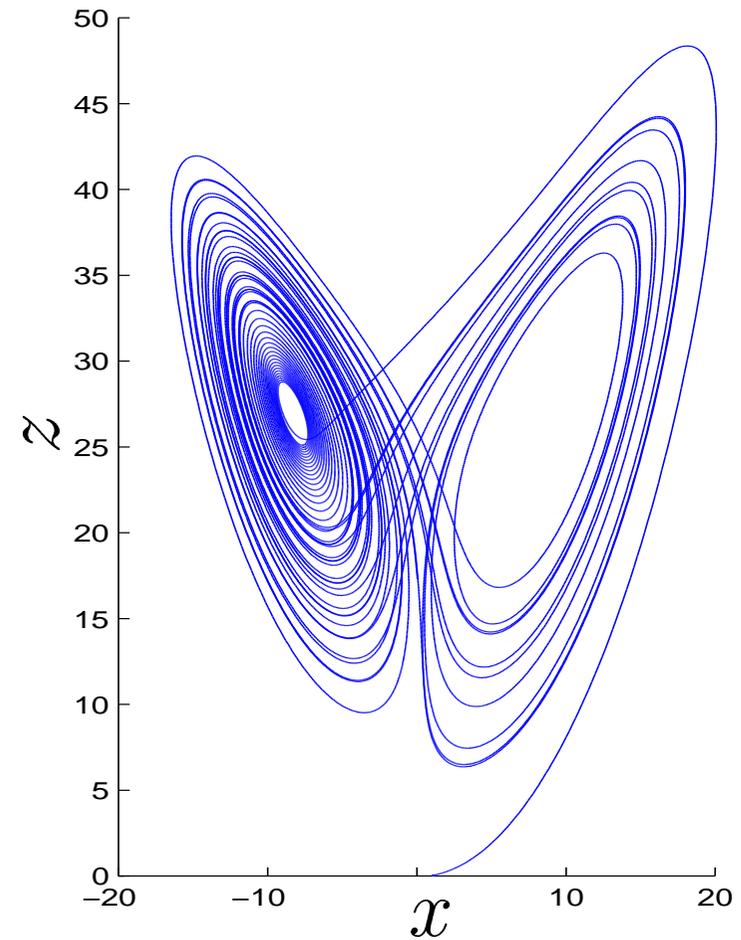
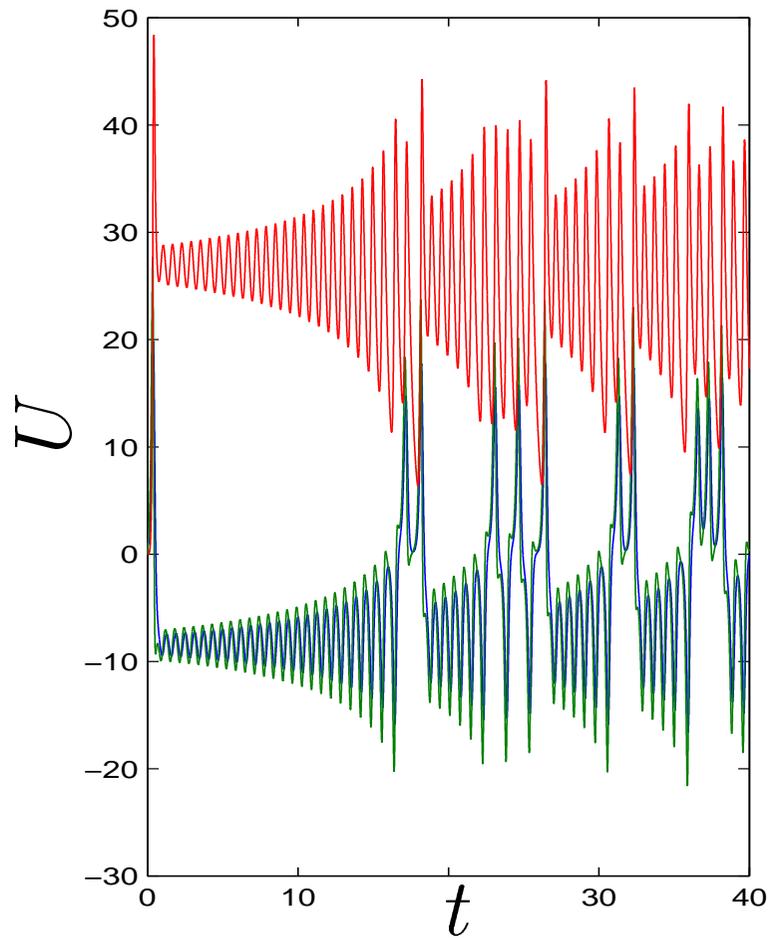
The Lorenz System (A.Logg)

$$\begin{cases} \dot{x} = \sigma(y - x), \\ \dot{y} = rx - y - xz, \\ \dot{z} = xy - bz, \end{cases}$$

where we, as usual, take $(x_0, y_0, z_0) = (1, 0, 0)$,
 $\sigma = 10$, $b = 8/3$ and $r = 28$.

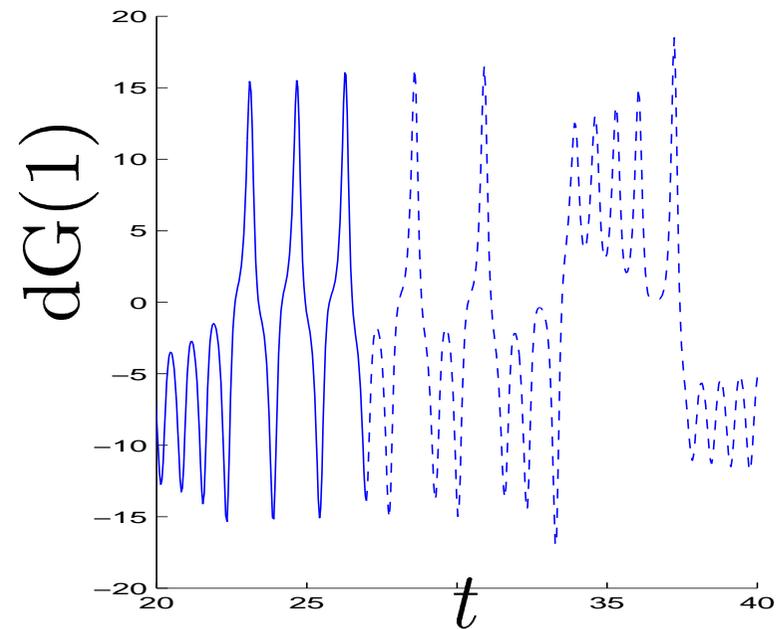
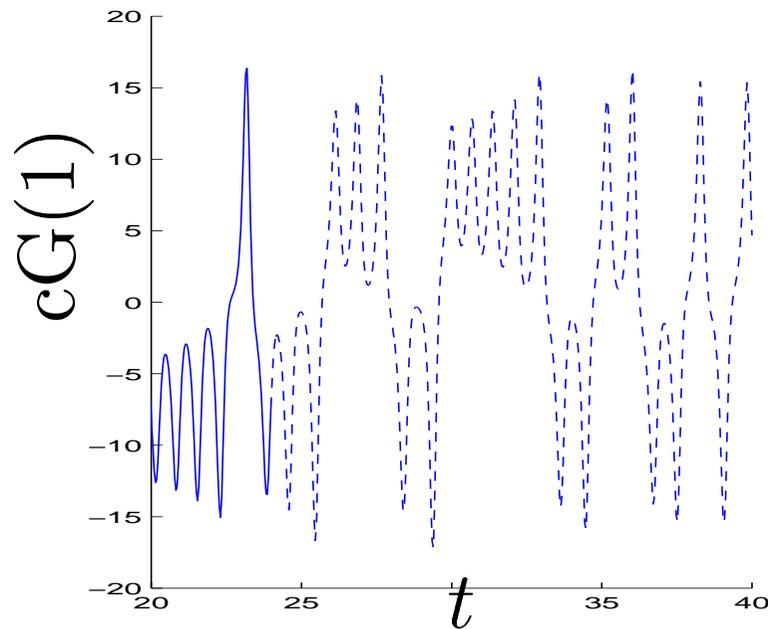
How far can we reach? (How long can we compute with small computational error?)

The Solution?



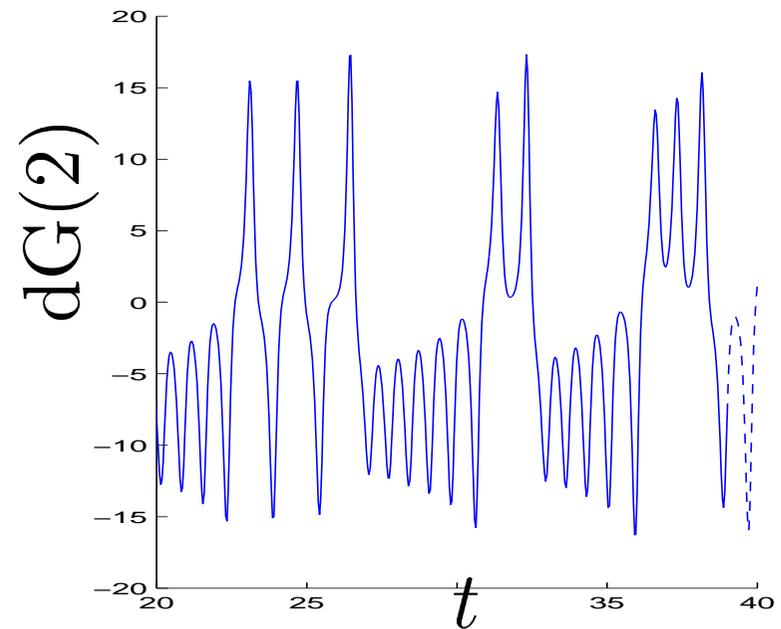
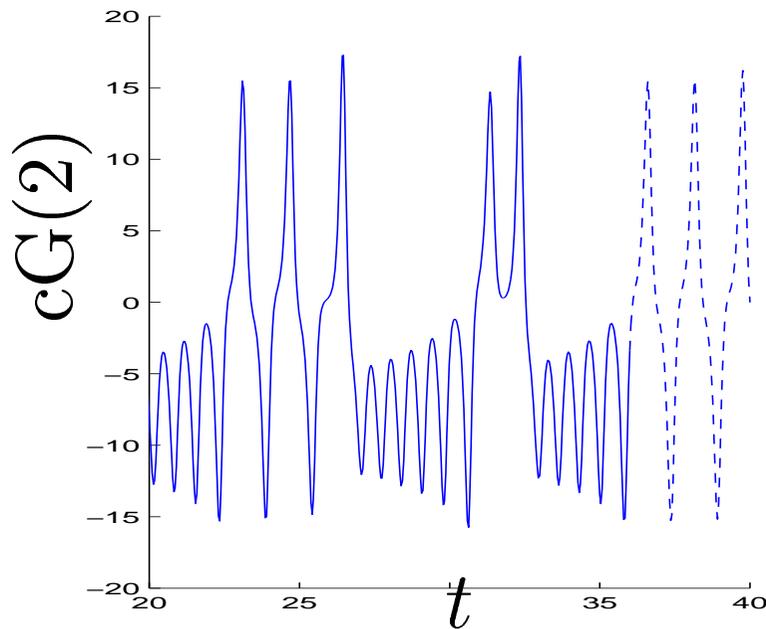
A Simple Experiment

- $T = 40$
- $k = 0.001$



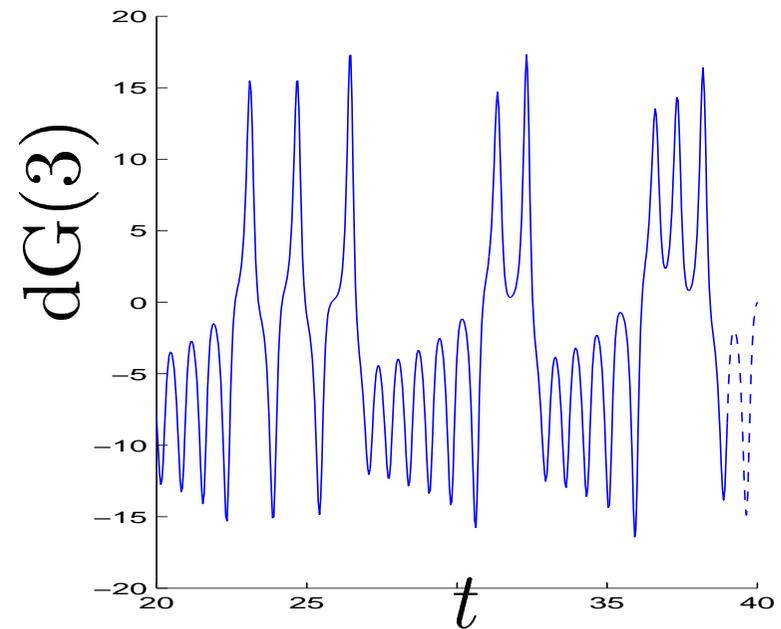
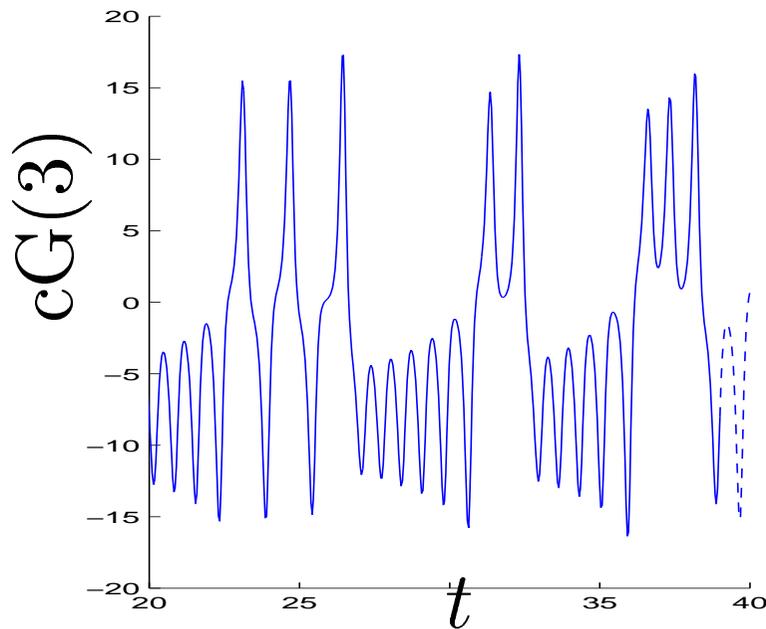
A Simple Experiment

- $T = 40$
- $k = 0.001$



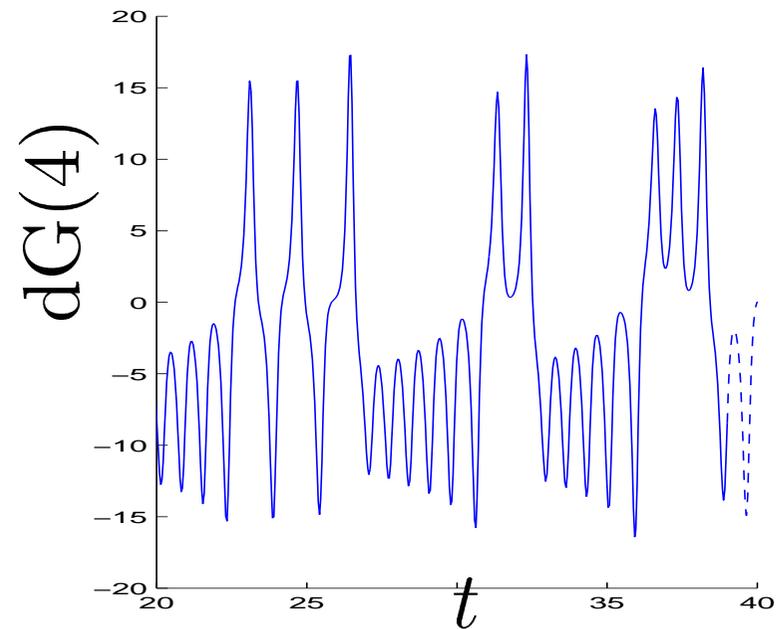
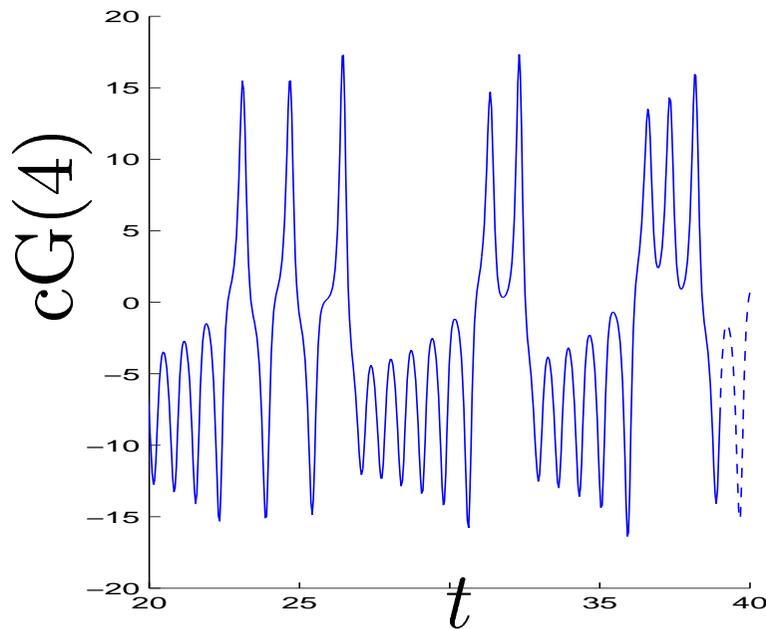
A Simple Experiment

- $T = 40$
- $k = 0.001$



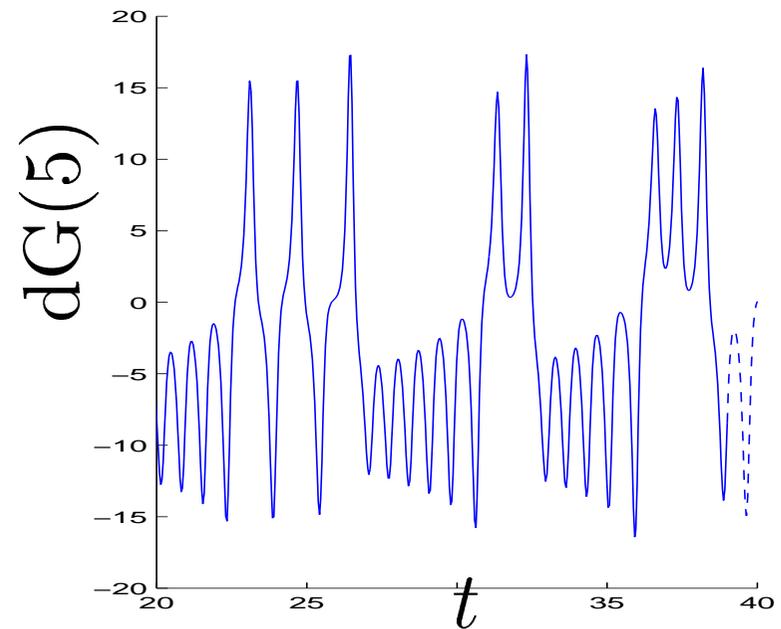
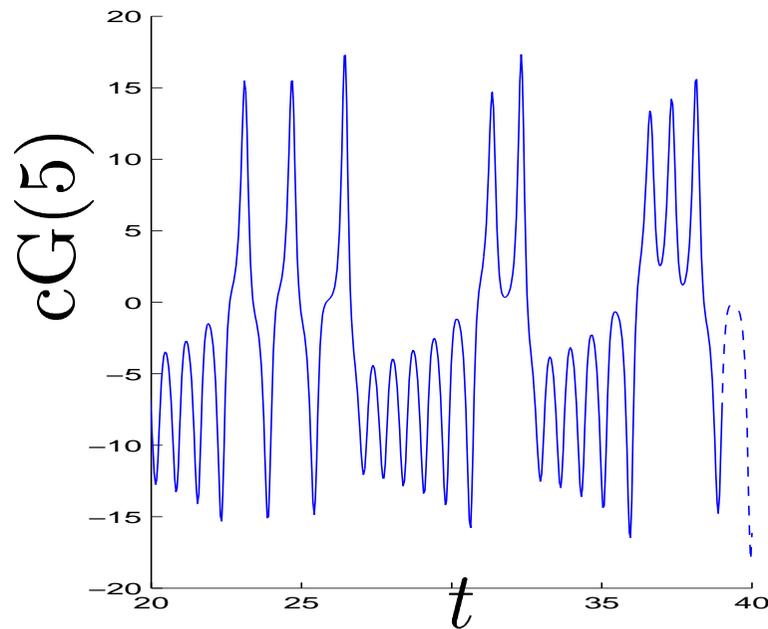
A Simple Experiment

- $T = 40$
- $k = 0.001$



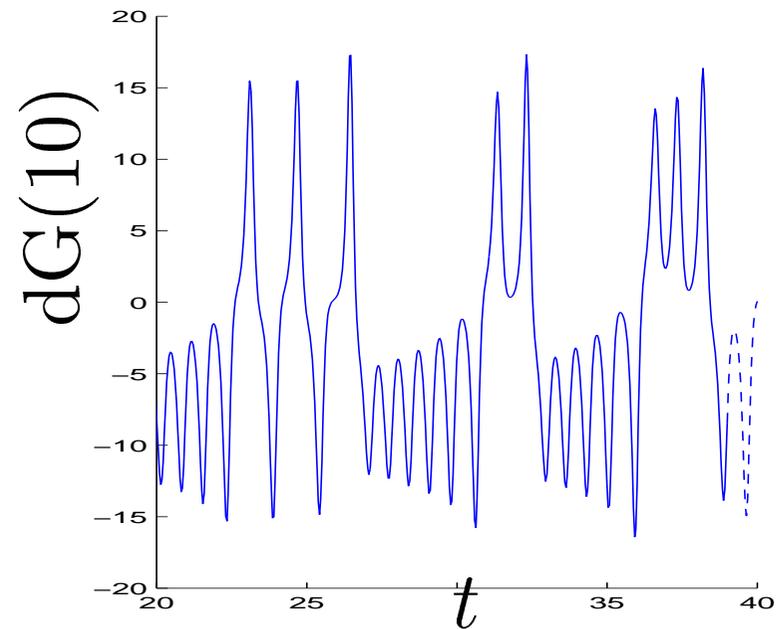
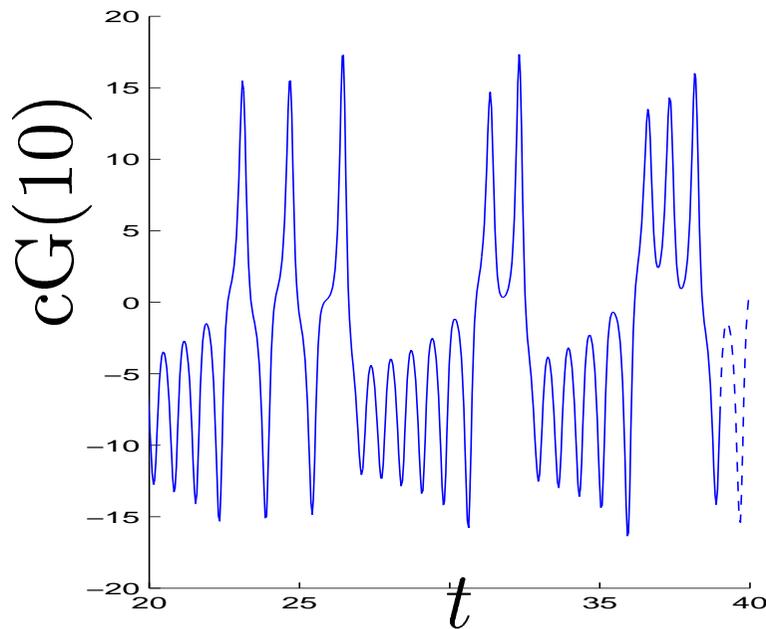
A Simple Experiment

- $T = 40$
- $k = 0.001$



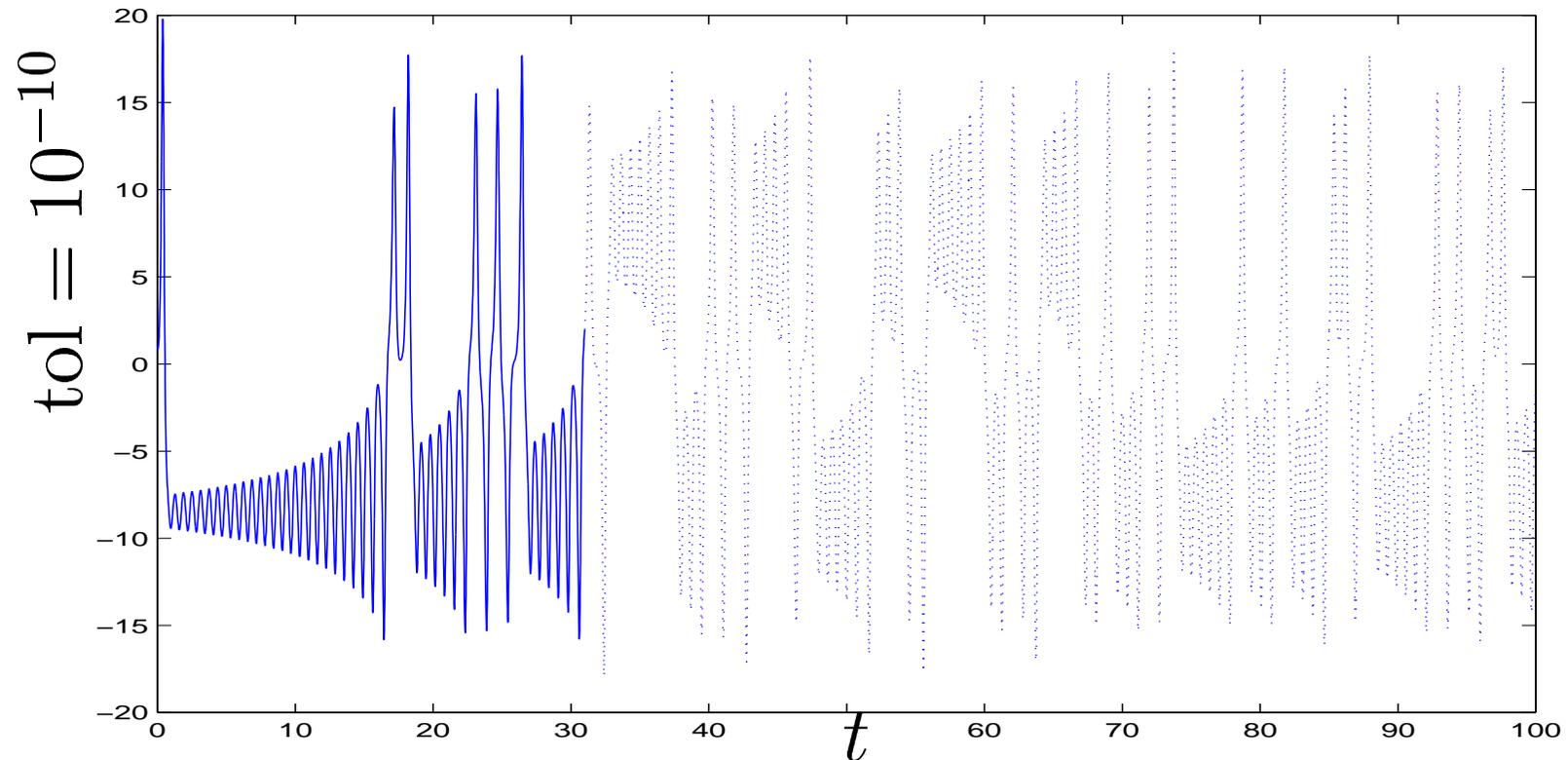
A Simple Experiment

- $T = 40$
- $k = 0.001$



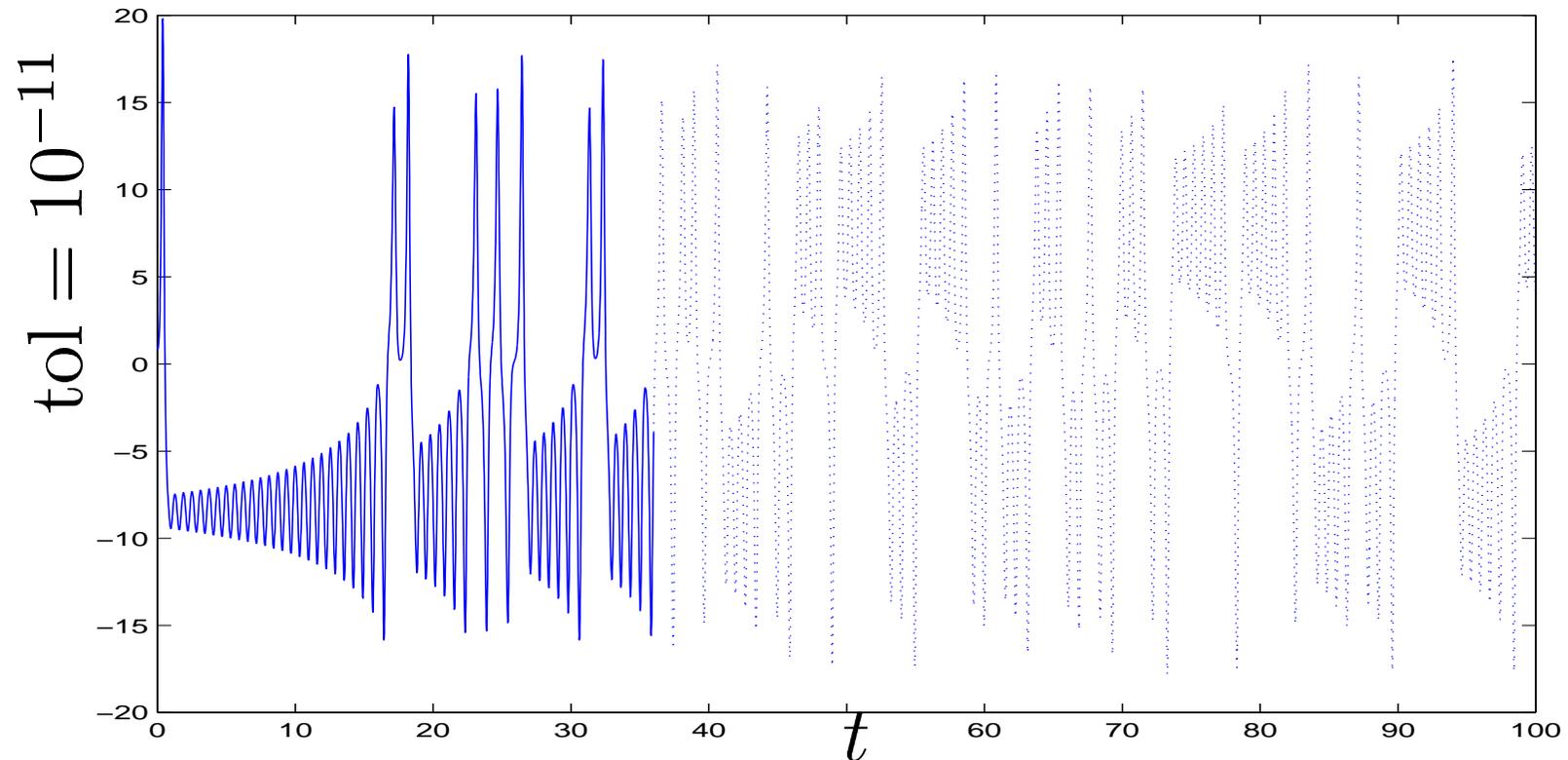
ode45

Trying the same thing with Matlabs ode45:



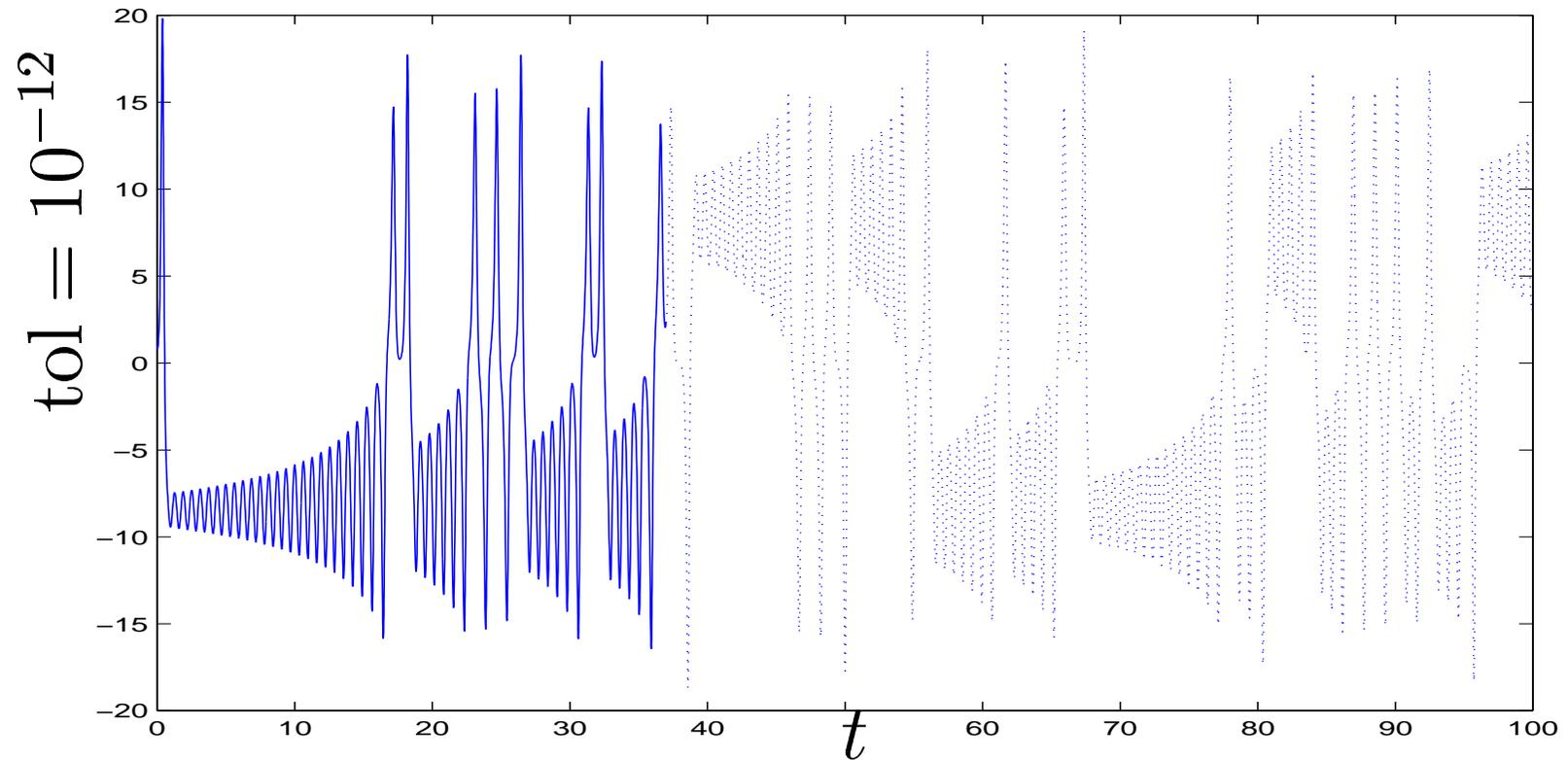
ode45

Trying the same thing with Matlabs ode45:



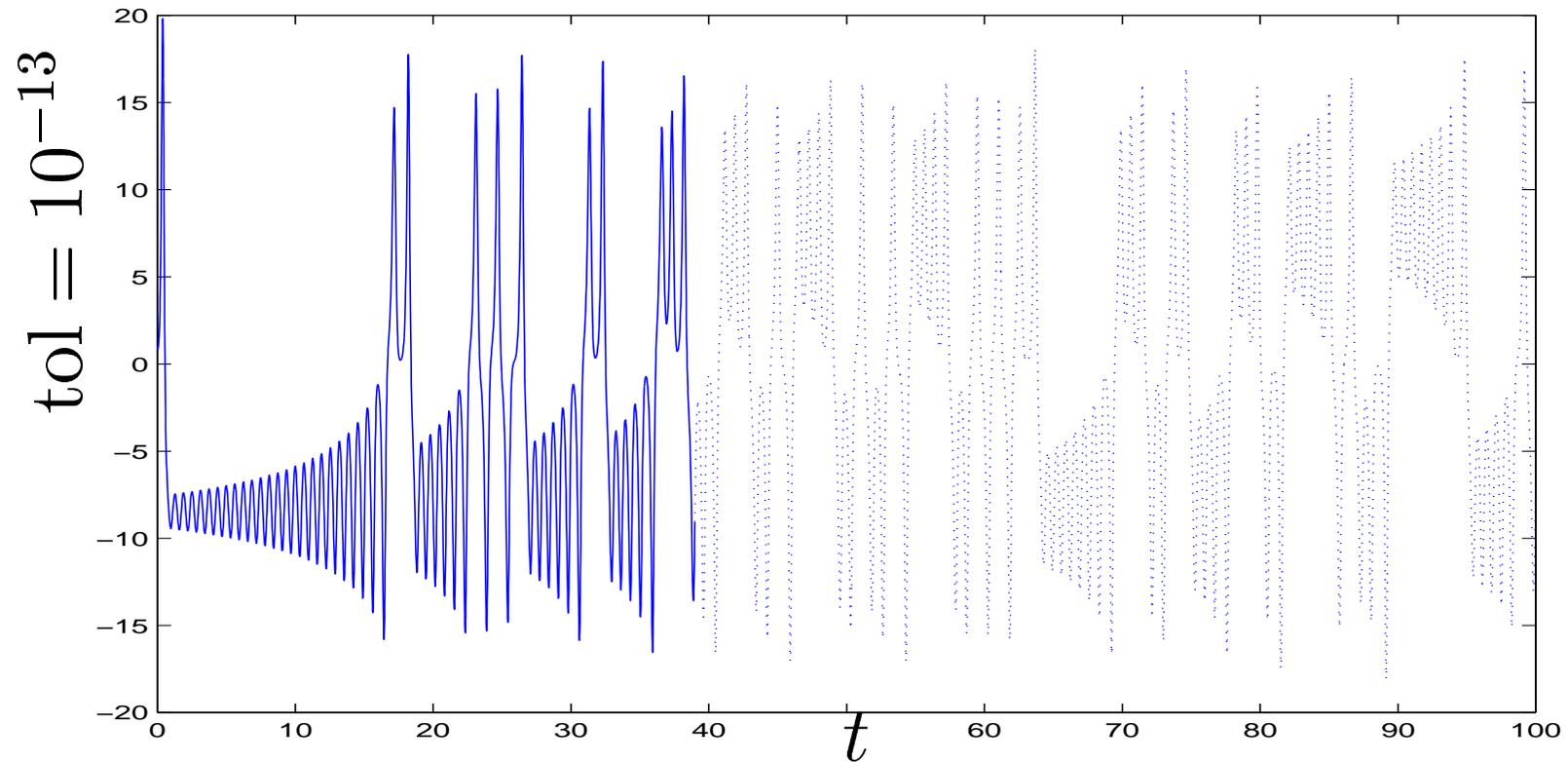
ode45

Trying the same thing with Matlabs ode45:



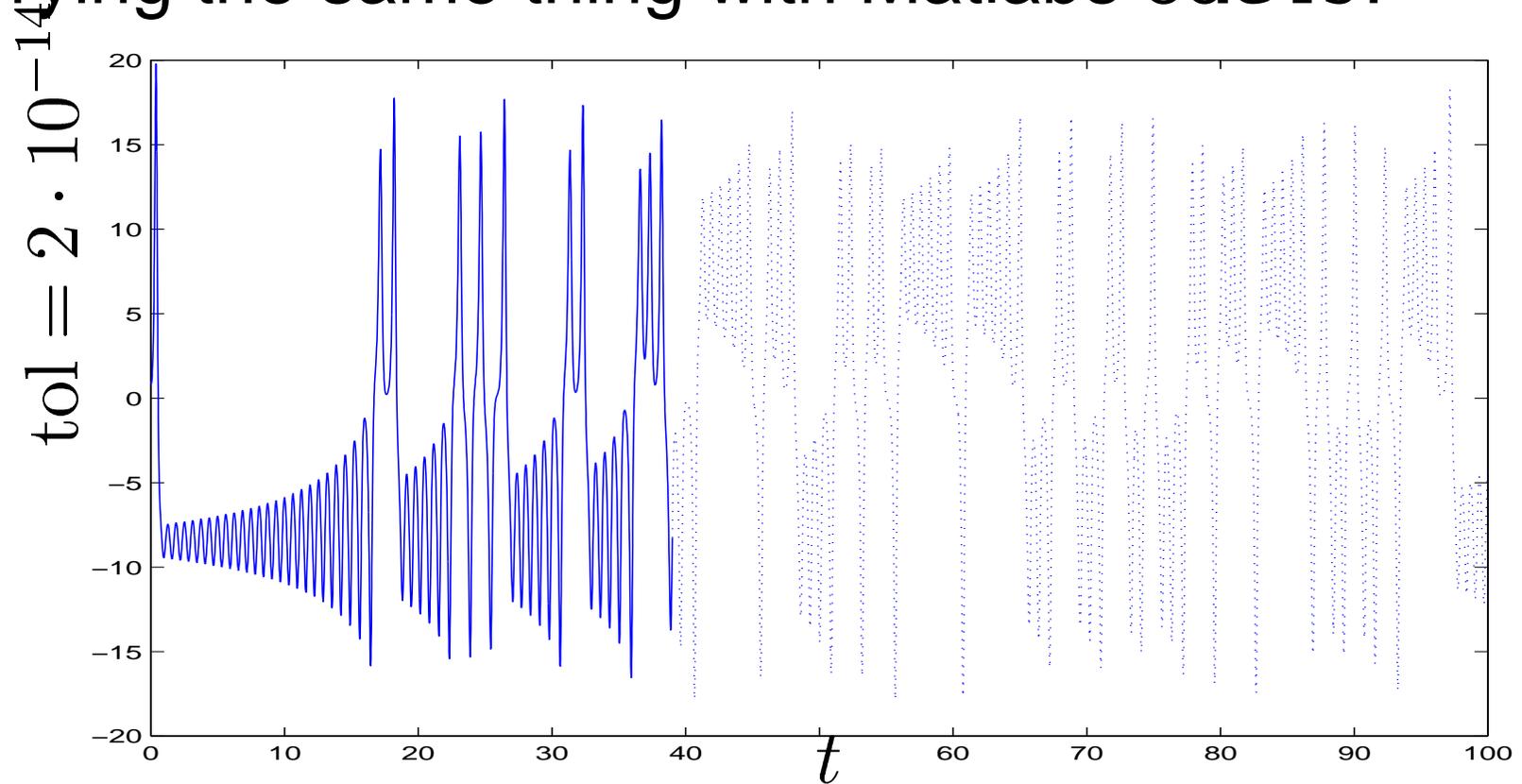
ode45

Trying the same thing with Matlabs ode45:



ode45

Trying the same thing with Matlabs ode45:



Getting Further

Computational error = $SC\|R(U)\|$

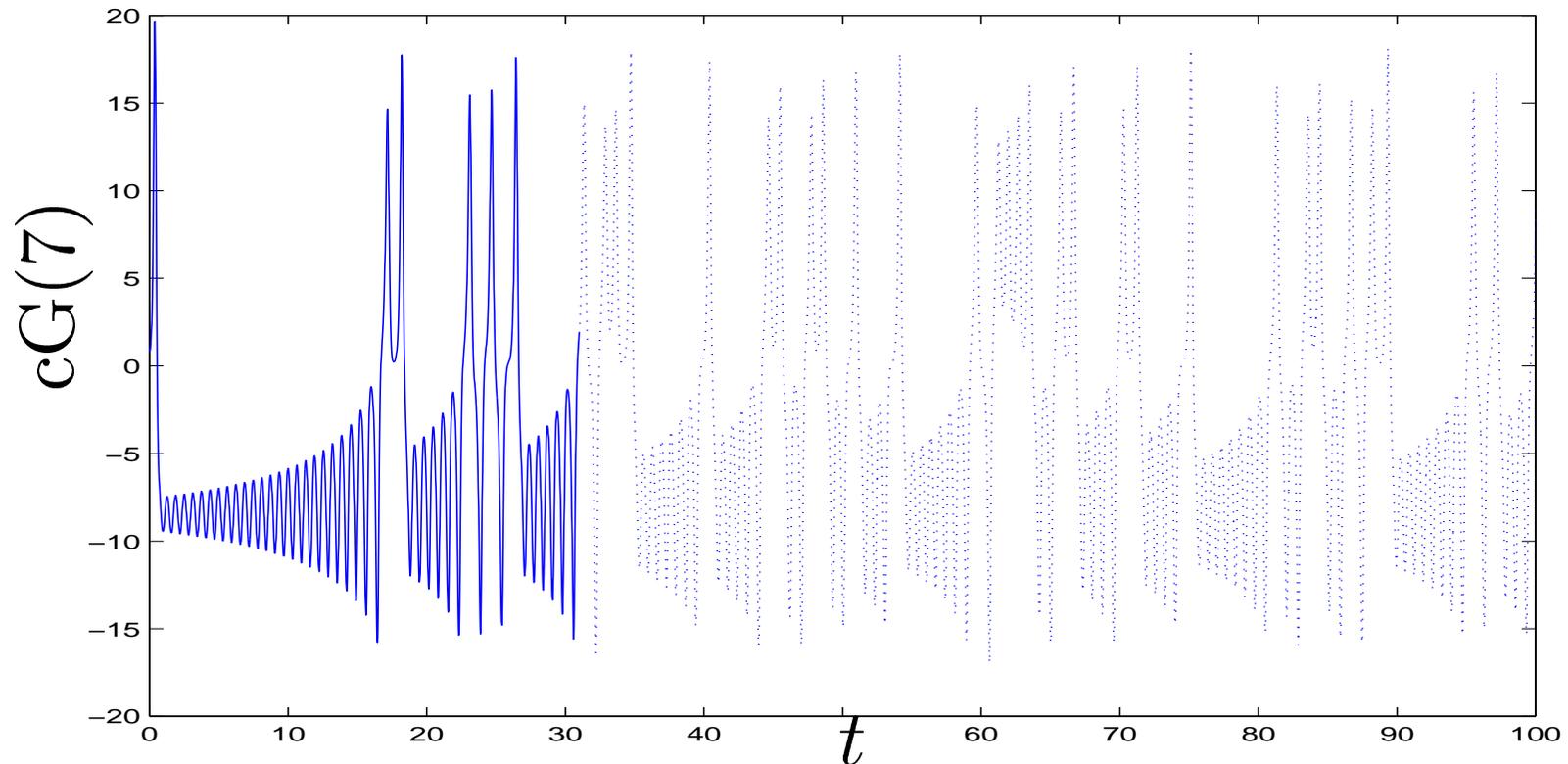
- Small residual
- Large stability factor

The round-off error is at least 10^{-16} in each time step using double precision

This means that we have to take fewer time steps, using a very high order method

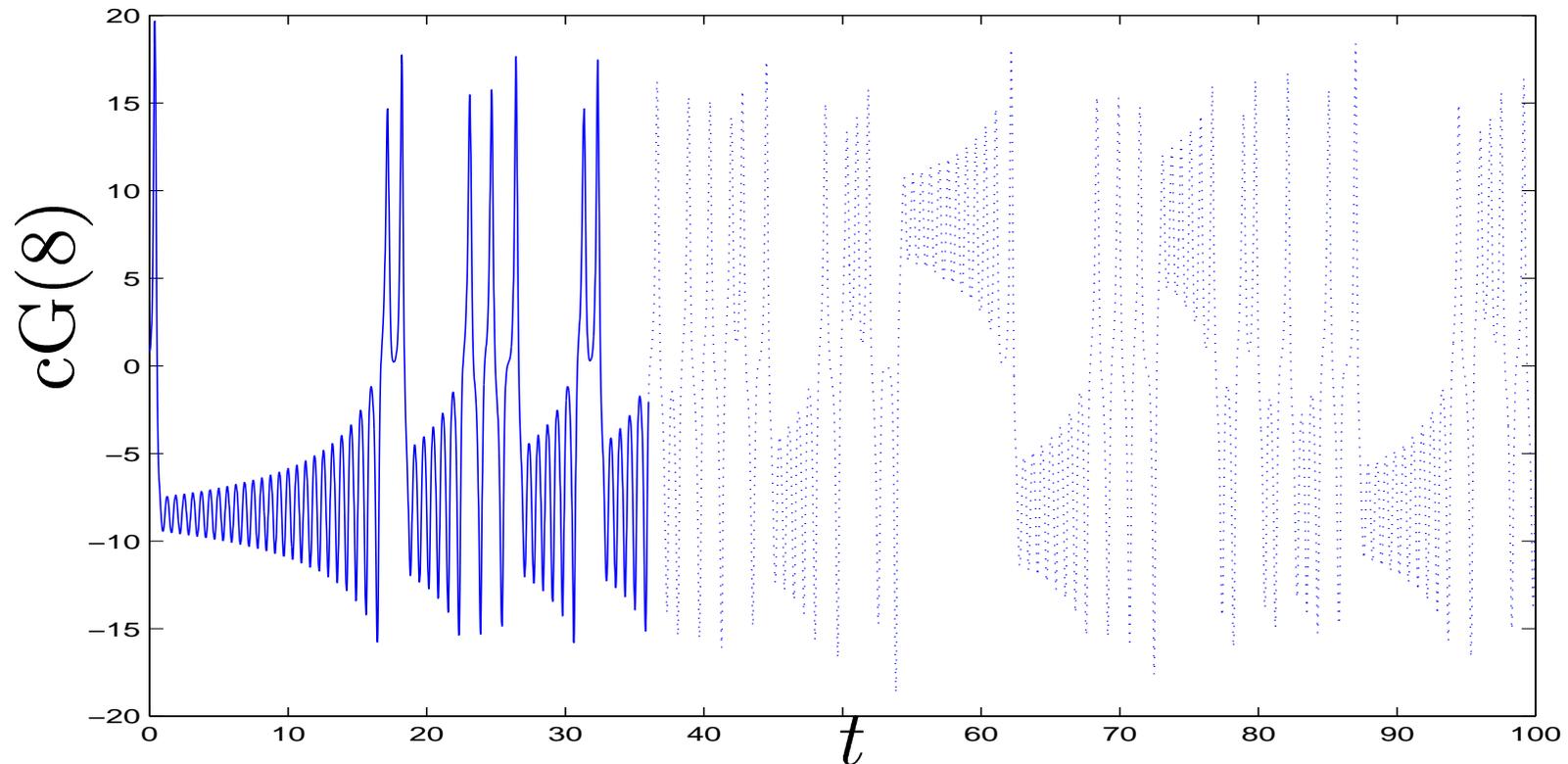
A Simple Experiment — *continued*

Increasing the time-step to $k = 0.1$:



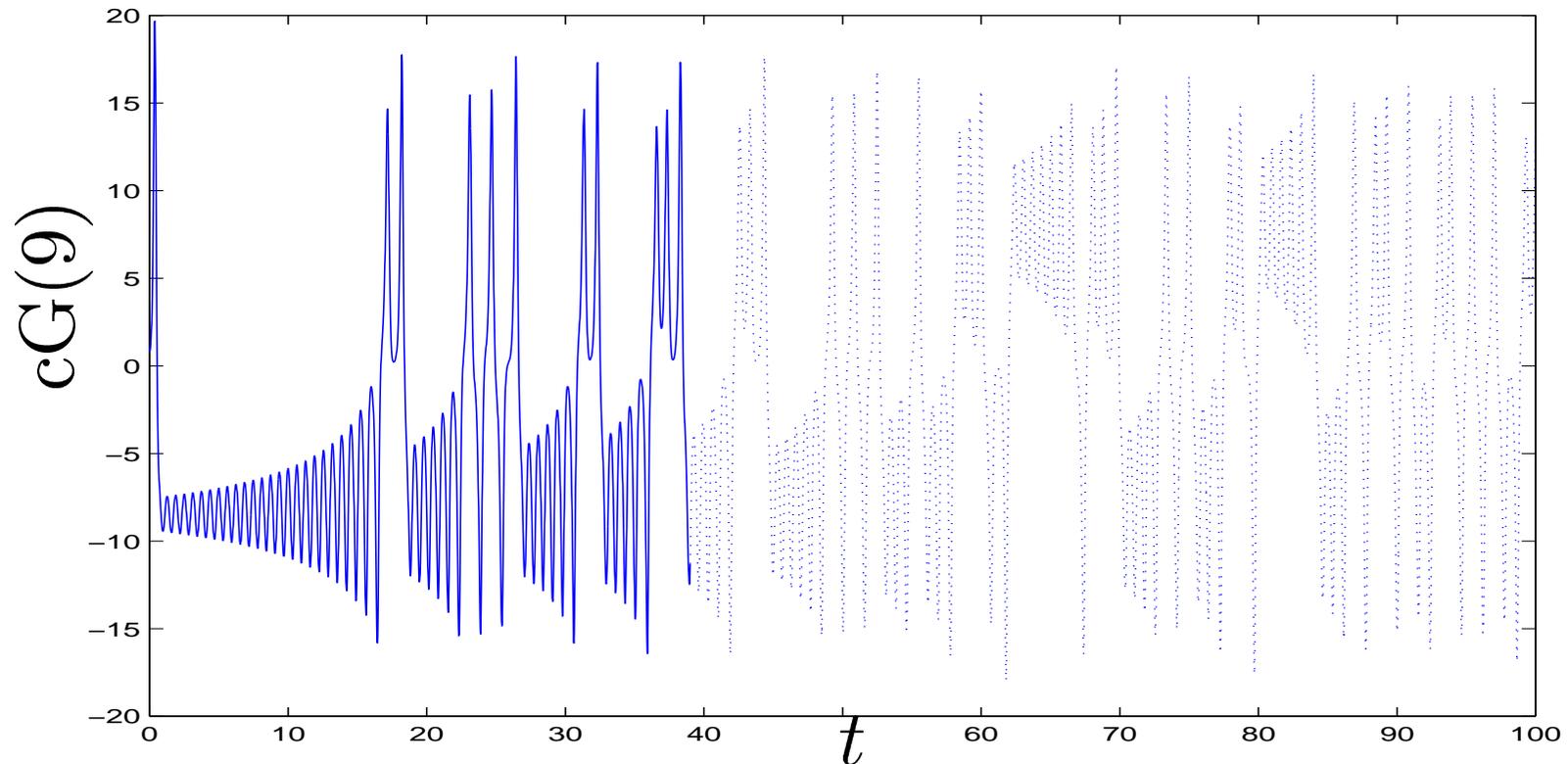
A Simple Experiment — *continued*

Increasing the time-step to $k = 0.1$:



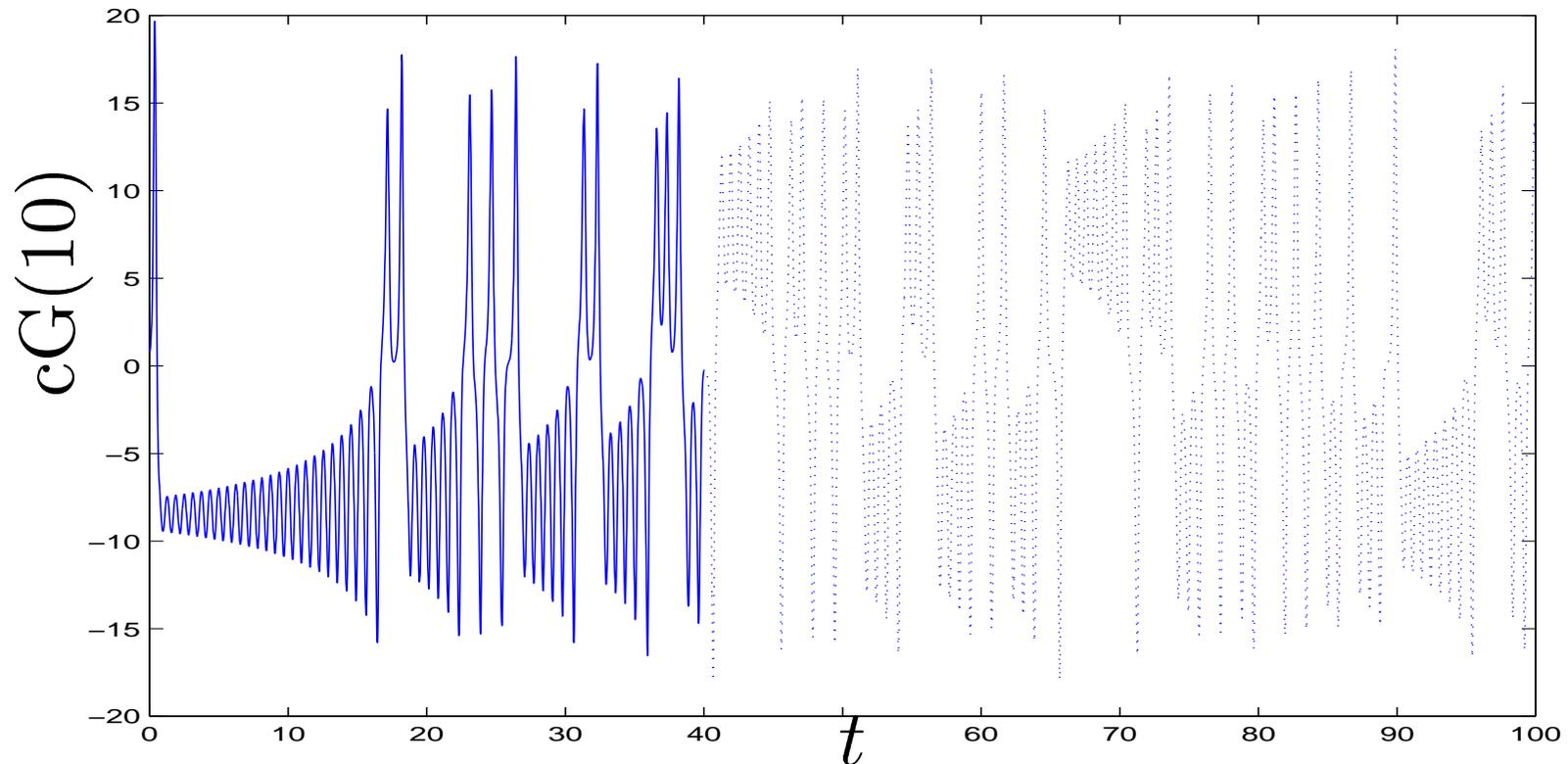
A Simple Experiment — *continued*

Increasing the time-step to $k = 0.1$:



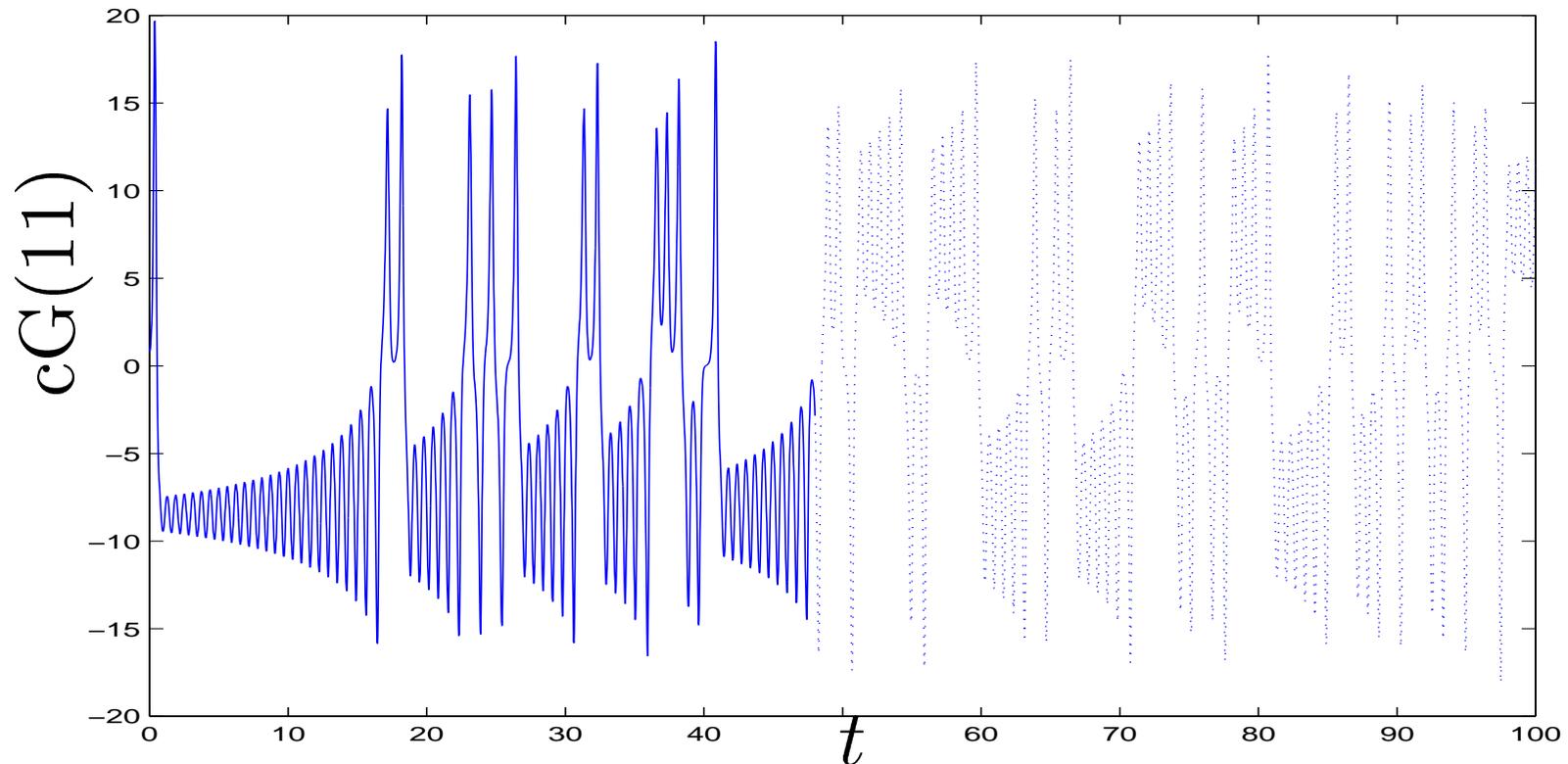
A Simple Experiment — *continued*

Increasing the time-step to $k = 0.1$:



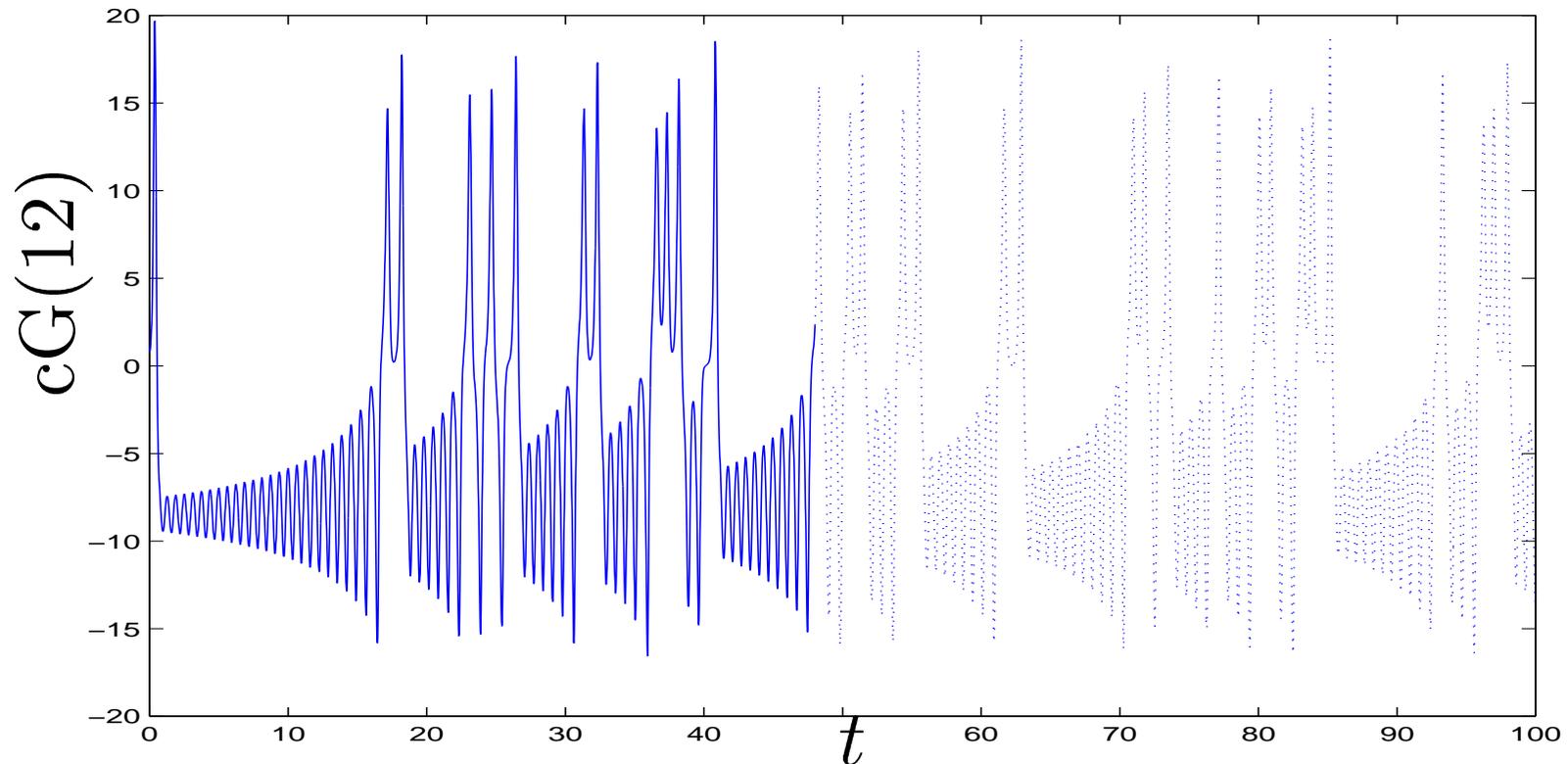
A Simple Experiment — *continued*

Increasing the time-step to $k = 0.1$:



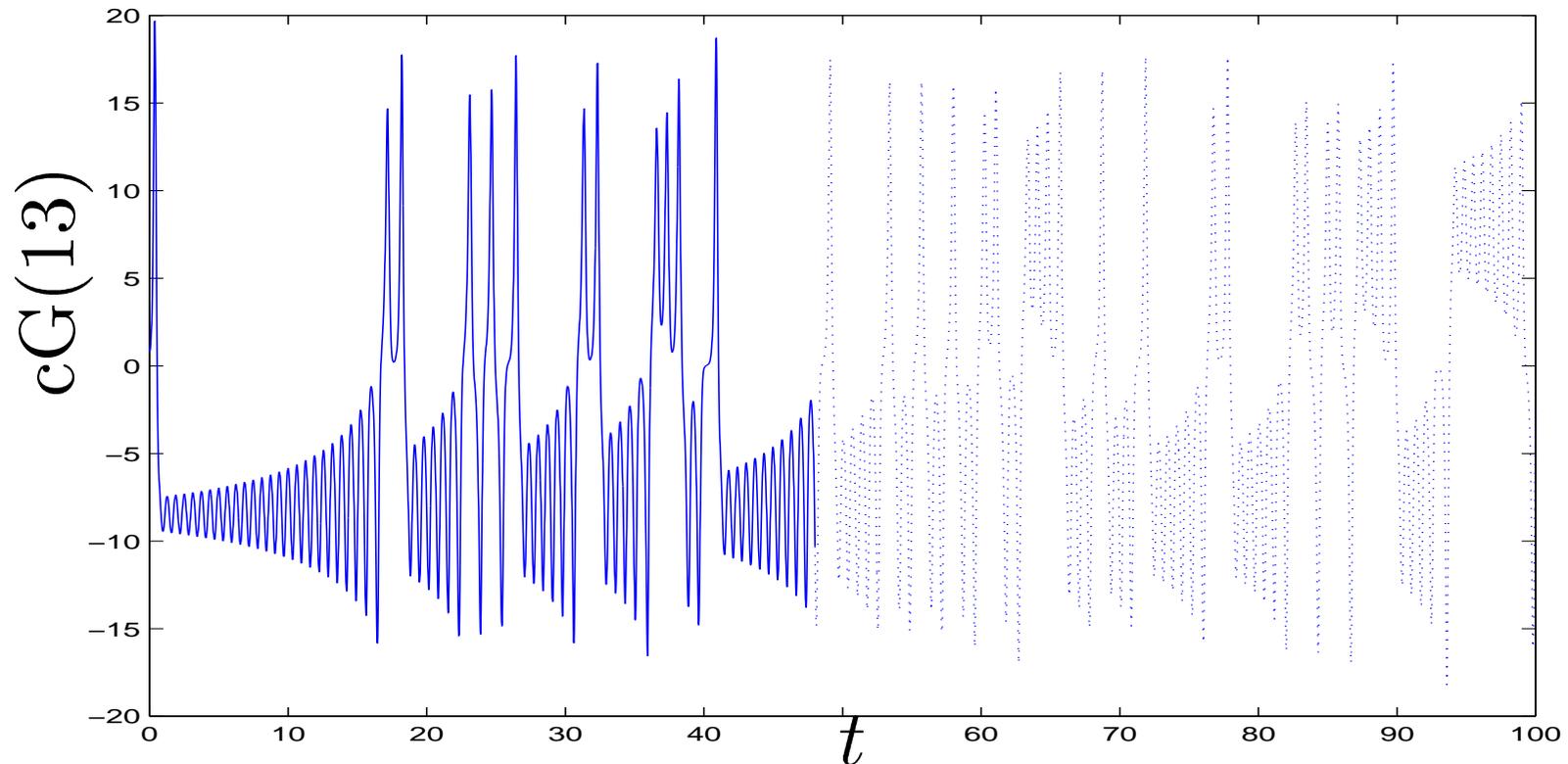
A Simple Experiment — *continued*

Increasing the time-step to $k = 0.1$:



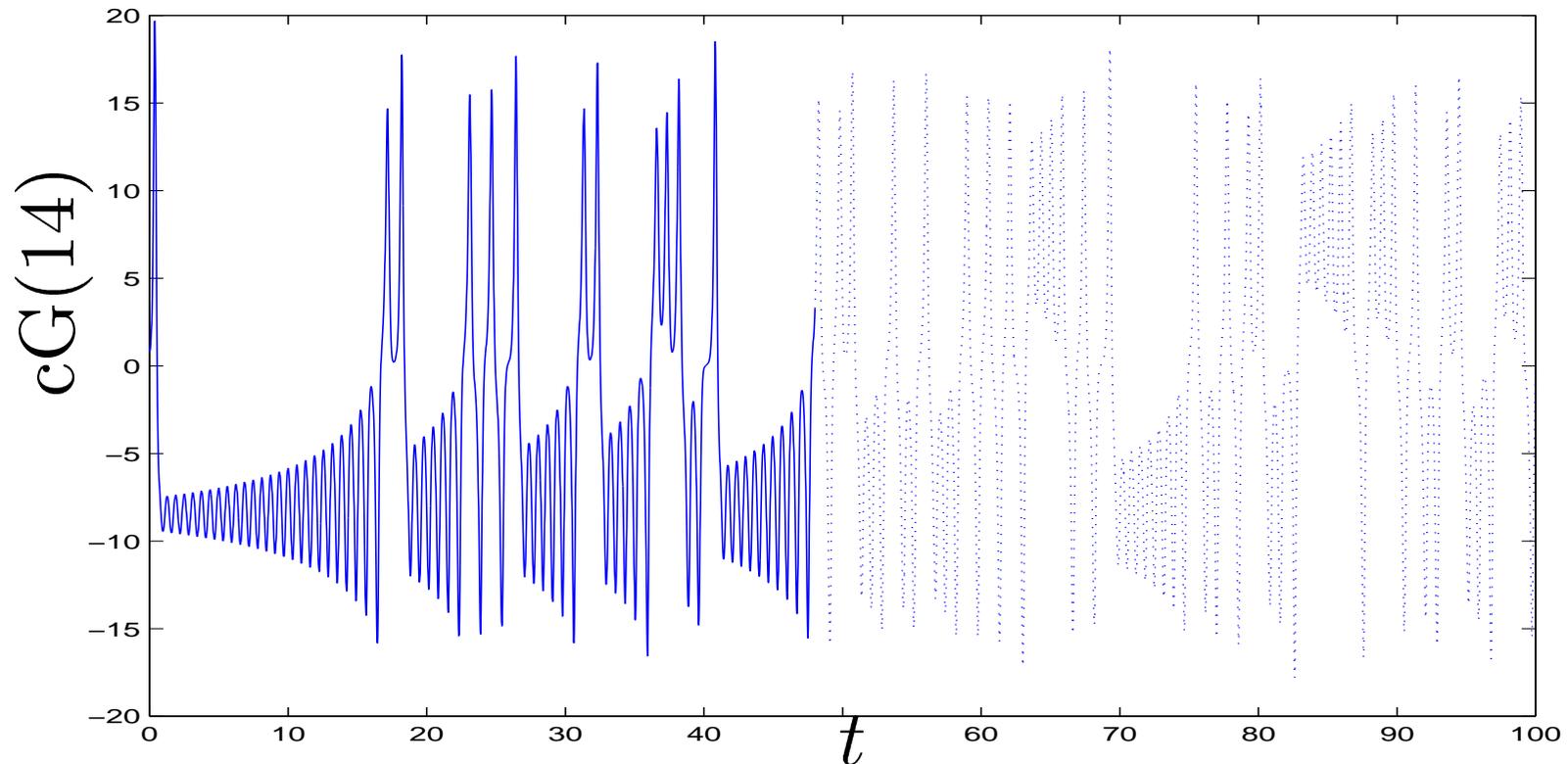
A Simple Experiment — *continued*

Increasing the time-step to $k = 0.1$:



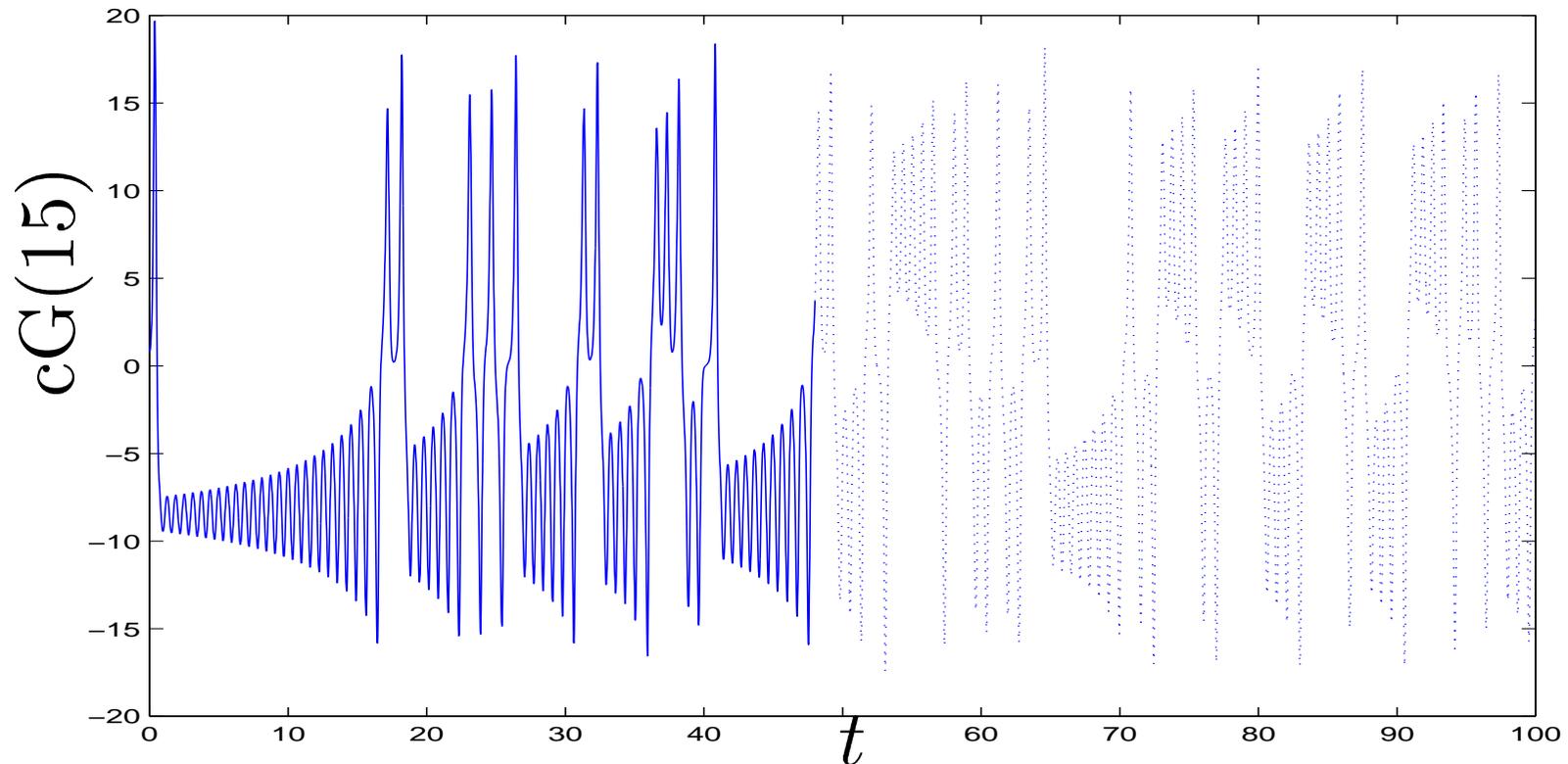
A Simple Experiment — *continued*

Increasing the time-step to $k = 0.1$:



A Simple Experiment — *continued*

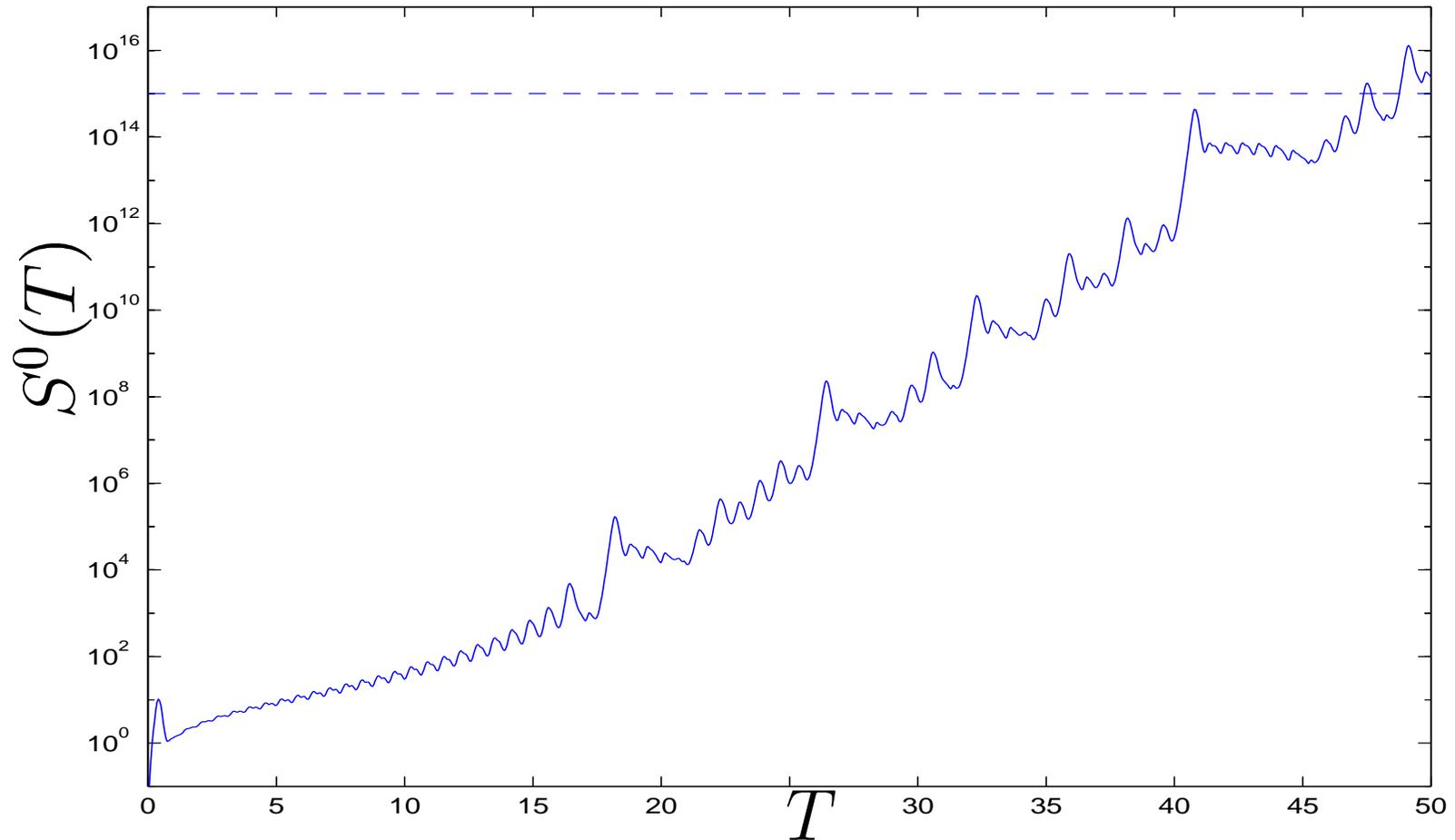
Increasing the time-step to $k = 0.1$:



The Stability Factor

- We do not come further than 50 even if we take larger time steps
- The round-off error is at least 10^{-16} at every time step
- The stability factor reaches 10^{16} at ~ 50

The Stability Factor



Linearized dual Navier-Stokes eqns.

$$\begin{aligned} -\dot{\varphi} - (u \cdot \nabla)\varphi + \nabla U \cdot \varphi + \nabla\theta - \epsilon\Delta\varphi &= 0 && \text{in } Q \\ \operatorname{div} \varphi &= 0 && \text{in } Q \\ \varphi &= 0 && \text{on } \Gamma \times I \\ \varphi(\cdot, T) &= \psi && \text{in } \Omega \end{aligned}$$

The interaction between transport $-(u \cdot \nabla)\varphi$, diffusion $-\nu\Delta\varphi$, and reaction $\nabla U \cdot \varphi$ is crucial

Linearized dual Navier-Stokes eqns.

$$\begin{aligned} -\dot{\varphi} - (u \cdot \nabla)\varphi + \nabla U \cdot \varphi + \nabla \theta - \epsilon \Delta \varphi &= 0 && \text{in } Q \\ \operatorname{div} \varphi &= 0 && \text{in } Q \\ \varphi &= 0 && \text{on } \Gamma \times I \\ \varphi(\cdot, T) &= \psi && \text{in } \Omega \end{aligned}$$

The transport $-(u \cdot \nabla)\varphi$ depends on the base flow u acting as convecting velocity (backwards). An irregular base flow u gives an irreg. dual solution

Linearized dual Navier-Stokes eqns.

$$\begin{aligned} -\dot{\varphi} - (u \cdot \nabla)\varphi + \nabla U \cdot \varphi + \nabla\theta - \epsilon\Delta\varphi &= 0 && \text{in } Q \\ \operatorname{div} \varphi &= 0 && \text{in } Q \\ \varphi &= 0 && \text{on } \Gamma \times I \\ \varphi(\cdot, T) &= \psi && \text{in } \Omega \end{aligned}$$

The reaction $\nabla U \cdot \varphi$ depends on the regularity of the computed flow through ∇U , causing more reaction for irregular flow (large ∇U)

Linearized dual Navier-Stokes eqns.

$$\begin{aligned} -\dot{\varphi} - (u \cdot \nabla)\varphi + \nabla U \cdot \varphi + \nabla\theta - \epsilon\Delta\varphi &= 0 && \text{in } Q \\ \operatorname{div} \varphi &= 0 && \text{in } Q \\ \varphi &= 0 && \text{on } \Gamma \times I \\ \varphi(\cdot, T) &= \psi && \text{in } \Omega \end{aligned}$$

Global data ψ may give cancellation in the reaction $\nabla U \cdot \varphi$, which would make global data to give smaller stability factors than local data

Example: Bluff body

- Channel flow with slip walls, 1×1 rectangular cross section and length 4.
- Cubic body of side length 0.25 centered at $(0.5, 0, 0)$
- $x_1 = 0$ inflow boundary with inflow condition $u = (1, 0, 0)$
- Transparent outflow condition
- cG(1)cG(1), tetrahedral mesh $h = 1/32$

-
-
-

Bluff body

start animation

Bluff body - dual problem

- Take the state at $t = 18$ as initial data at $t = 0$
- Compute mean error in u_1 over $\omega \subset \Omega$ at $t = 2$
- Final data $\psi = (\chi_\omega/|\omega|, 0, 0)$
- We compute for ω being a square behind the body with side length $d(\omega)$
- cG(1)cG(1), tetrahedral mesh $h = 1/32$
- $\nu = 1/1000$

Stability factors in $L_1(I; L_1(\Omega))$ -norm

$$S_{0,1}(T) = \|\varphi\|_I$$

$$S_{1,1}(T) = \|\nabla\varphi\|_I$$

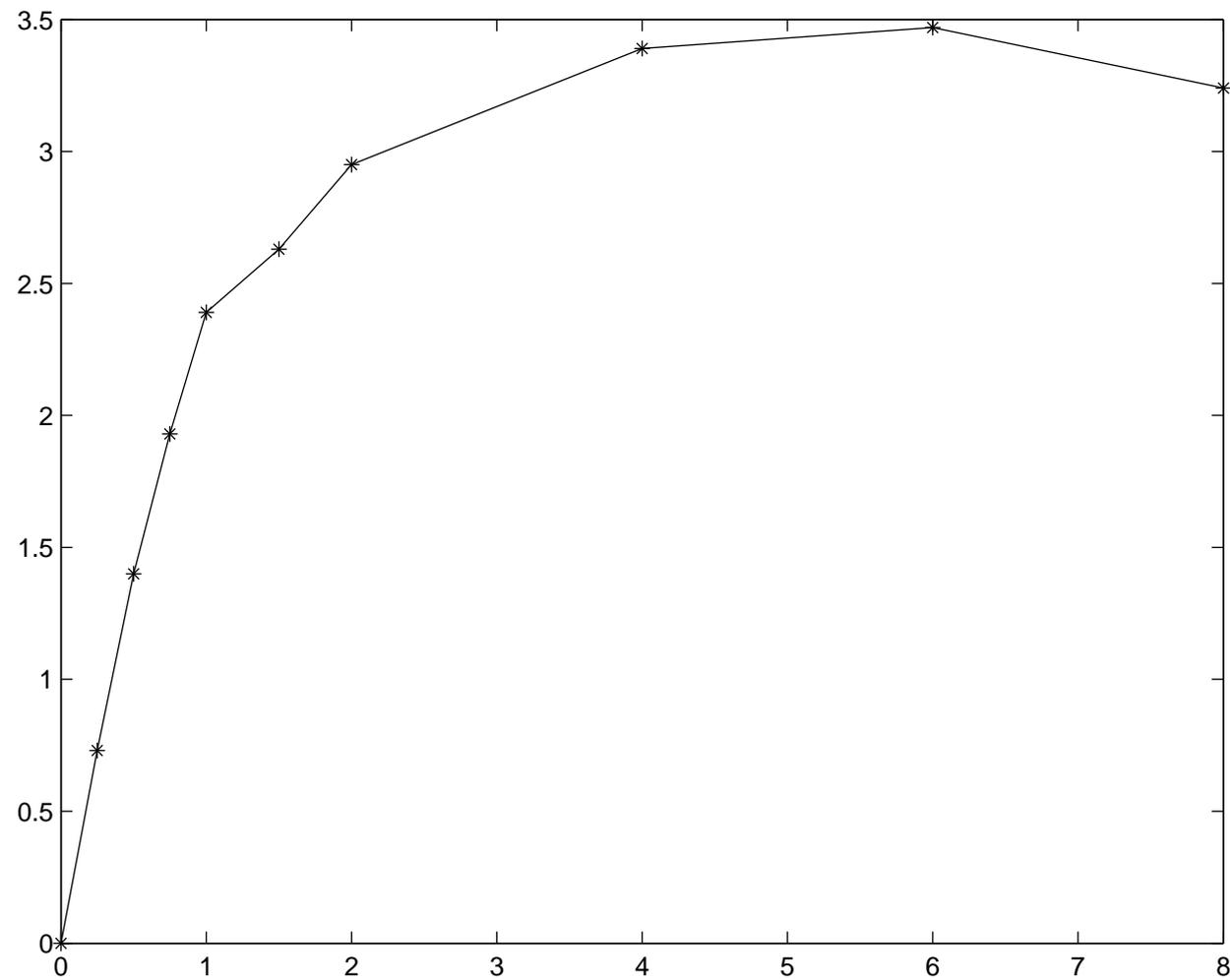
$$S_{1,2}(T) = \|\dot{\varphi}\|_I$$

$$S_{1,3}(T) = \|\nabla\theta\|_I$$

$$S_{2,1}(T) = \|\Delta\varphi\|_I$$

$\|\cdot\|_I$ is the $L_1(I; L_1(\Omega))$ -norm

$S_{1,1}(t)$



Stability factors in $L_1(I; L_1(\Omega))$ -norm

$d(\omega)$	$S_{0,1}$	$S_{1,1}$	$S_{1,2}$	$S_{1,3}$	$S_{2,1}$
0.0625	11.3	304.2	45.3	18.5	7627.5
0.125	5.8	152.3	28.6	12.0	3593.0
0.25	3.1	66.2	14.6	6.4	1533.5
0.5	1.9	25.4	8.3	3.3	491.5

Stability factors proportional to $1/d(\omega)$, where $d(\omega)$ is the side length of ω .

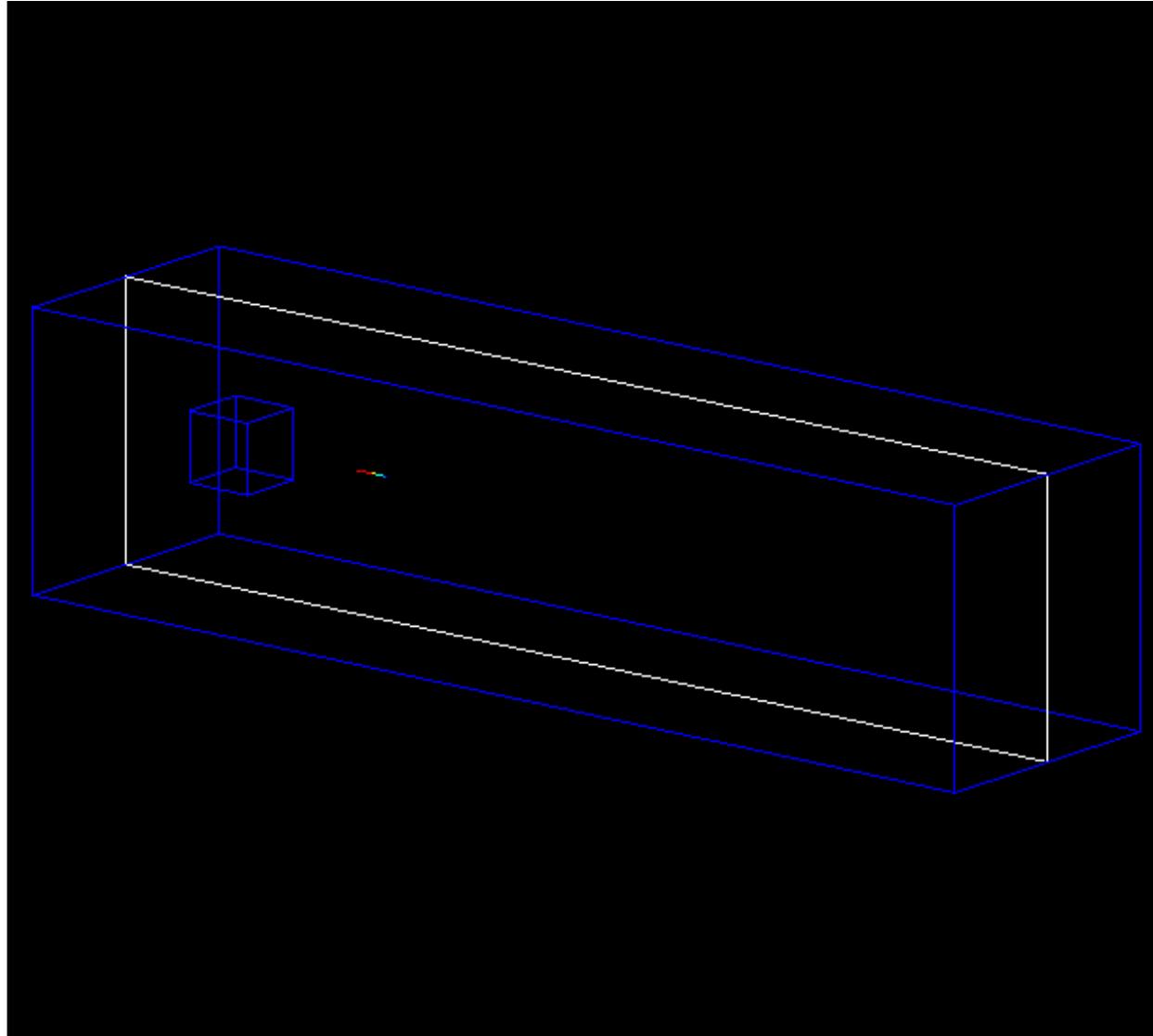
Stability factors in $L_1(I; L_1(\Omega))$ -norm

$d(\omega)$	$S_{0,1}$	$S_{1,1}$	$S_{1,2}$	$S_{1,3}$	$S_{2,1}$
0.0625	11.3	304.2	45.3	18.5	7627.5
0.125	5.8	152.3	28.6	12.0	3593.0
0.25	3.1	66.2	14.6	6.4	1533.5
0.5	1.9	25.4	8.3	3.3	491.5

Residuals are of order 1, which makes a small average to appear uncomputable on the current mesh, while a large average may be computable

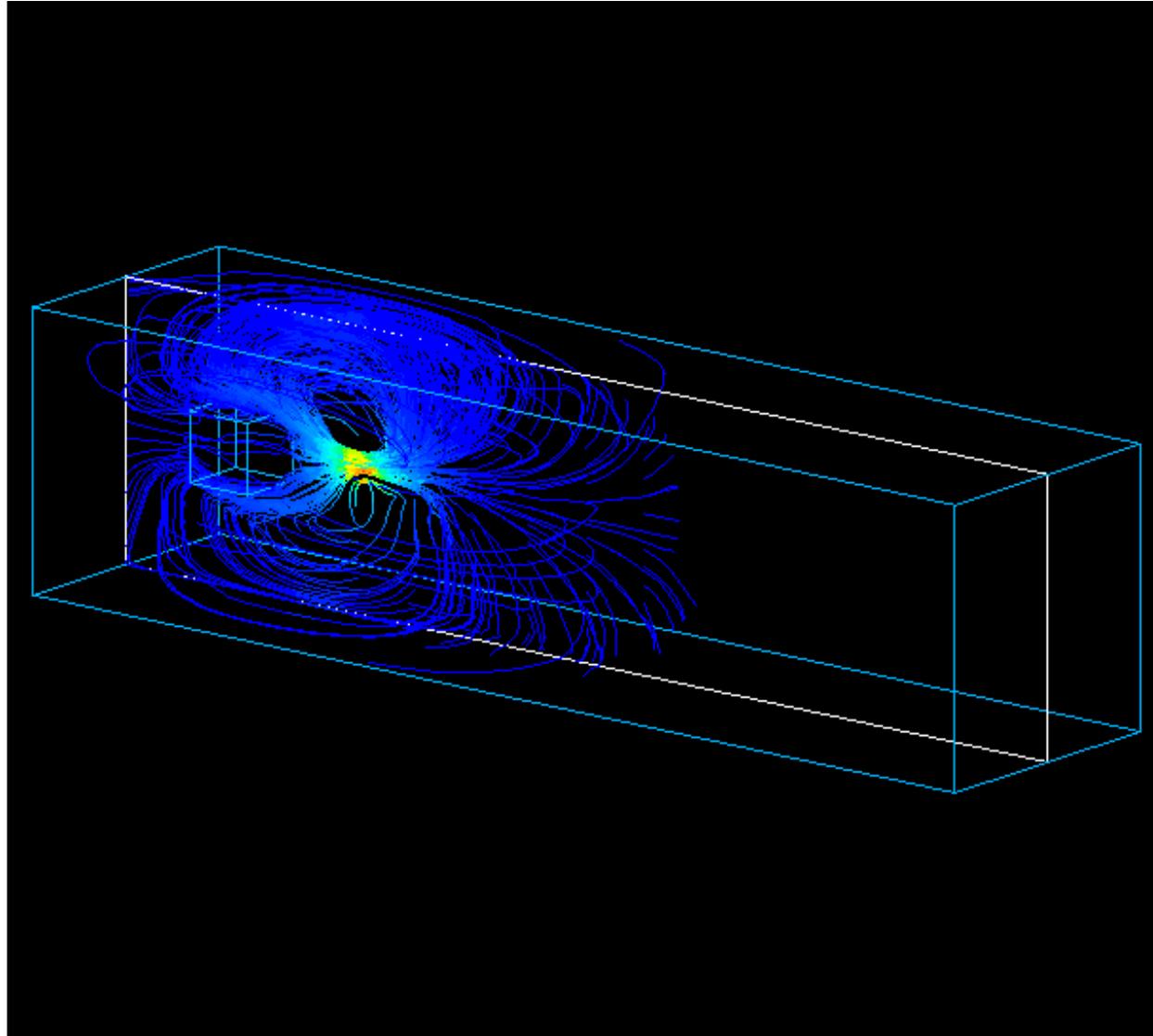
•
•
•

Dual solution, $d(\omega) = 0.0625, t = 2$



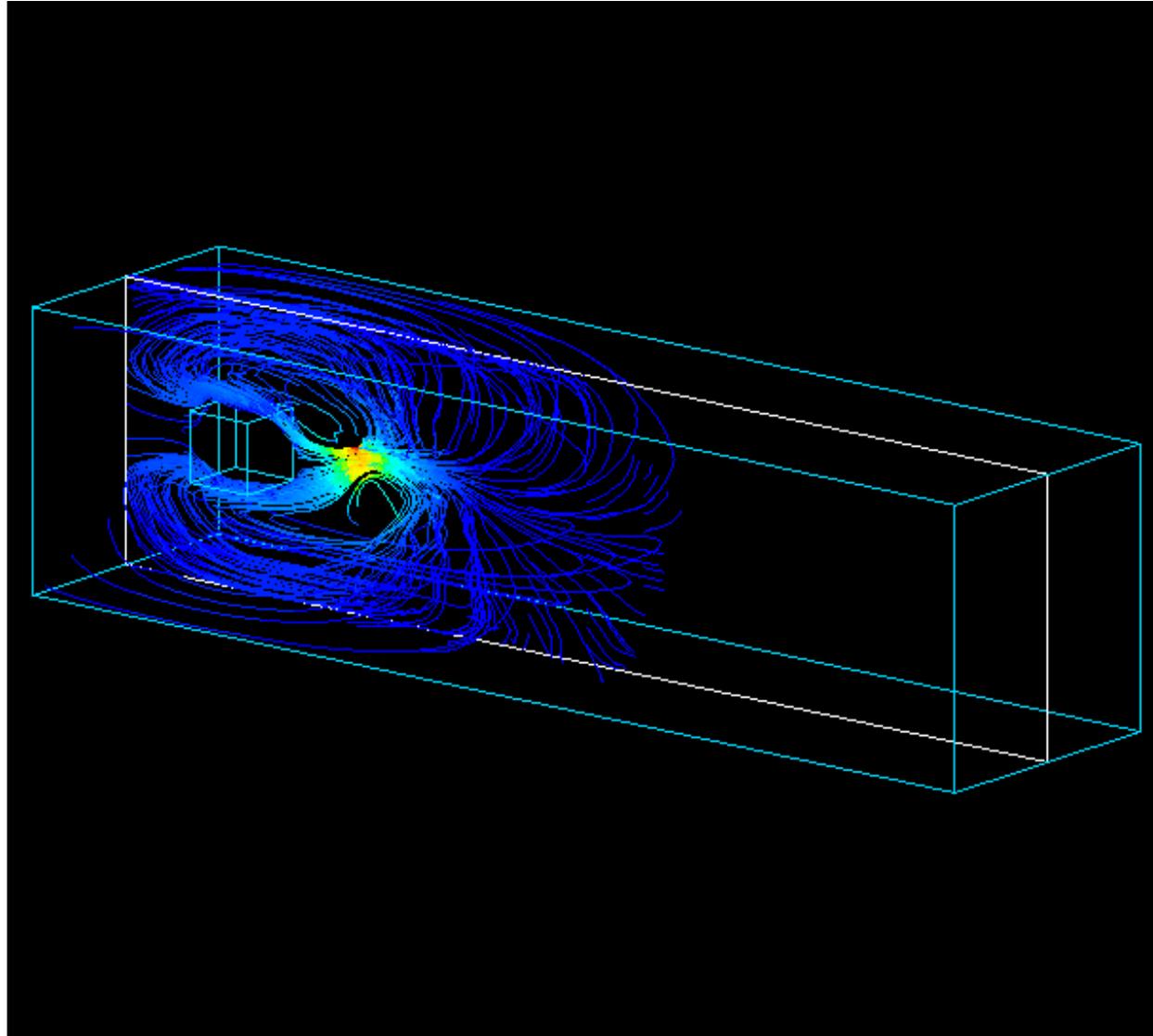
•
•
•

Dual solution, $d(\omega) = 0.0625, t = 1.75$



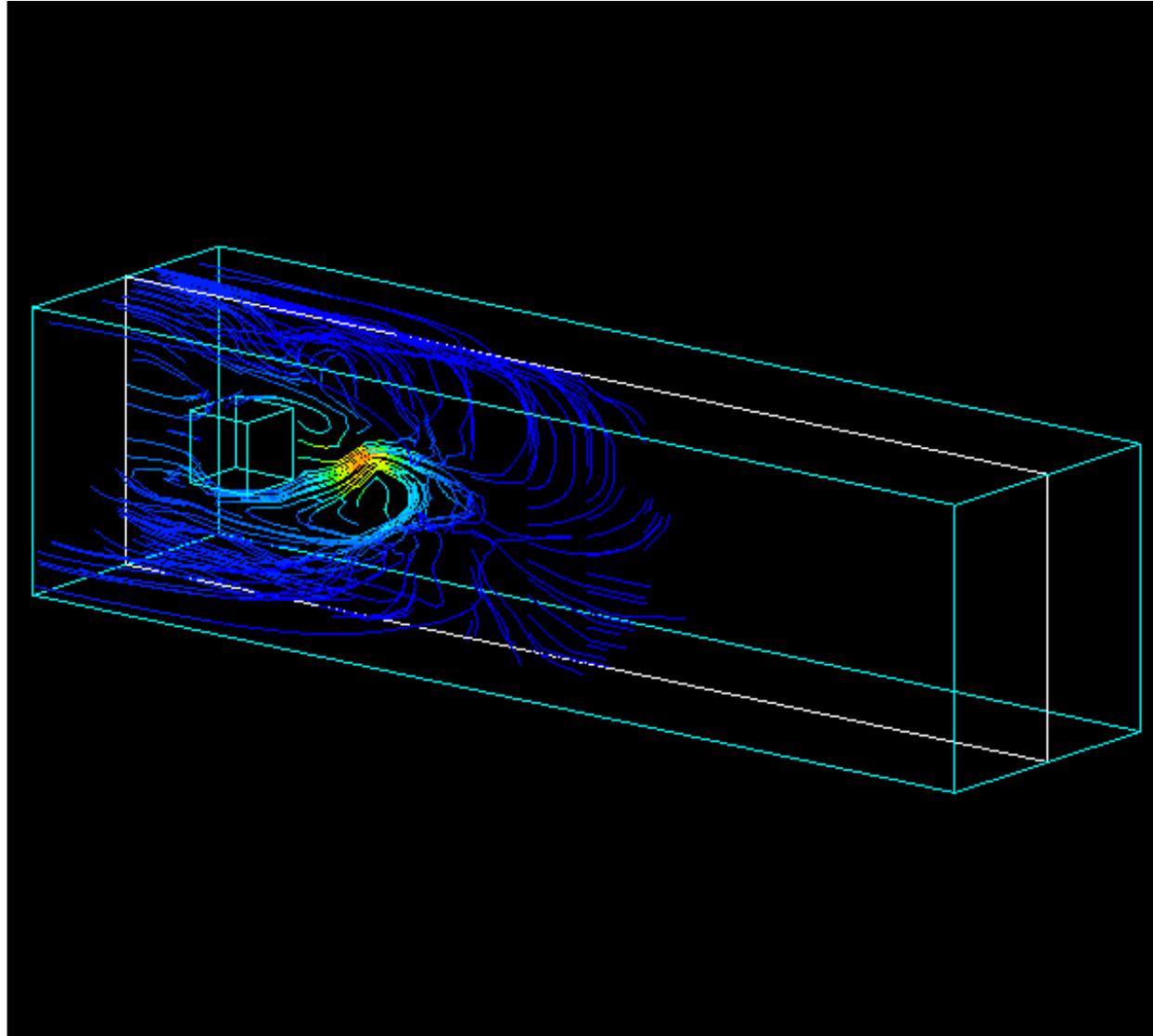
•
•
•

Dual solution, $d(\omega) = 0.0625, t = 1.5$



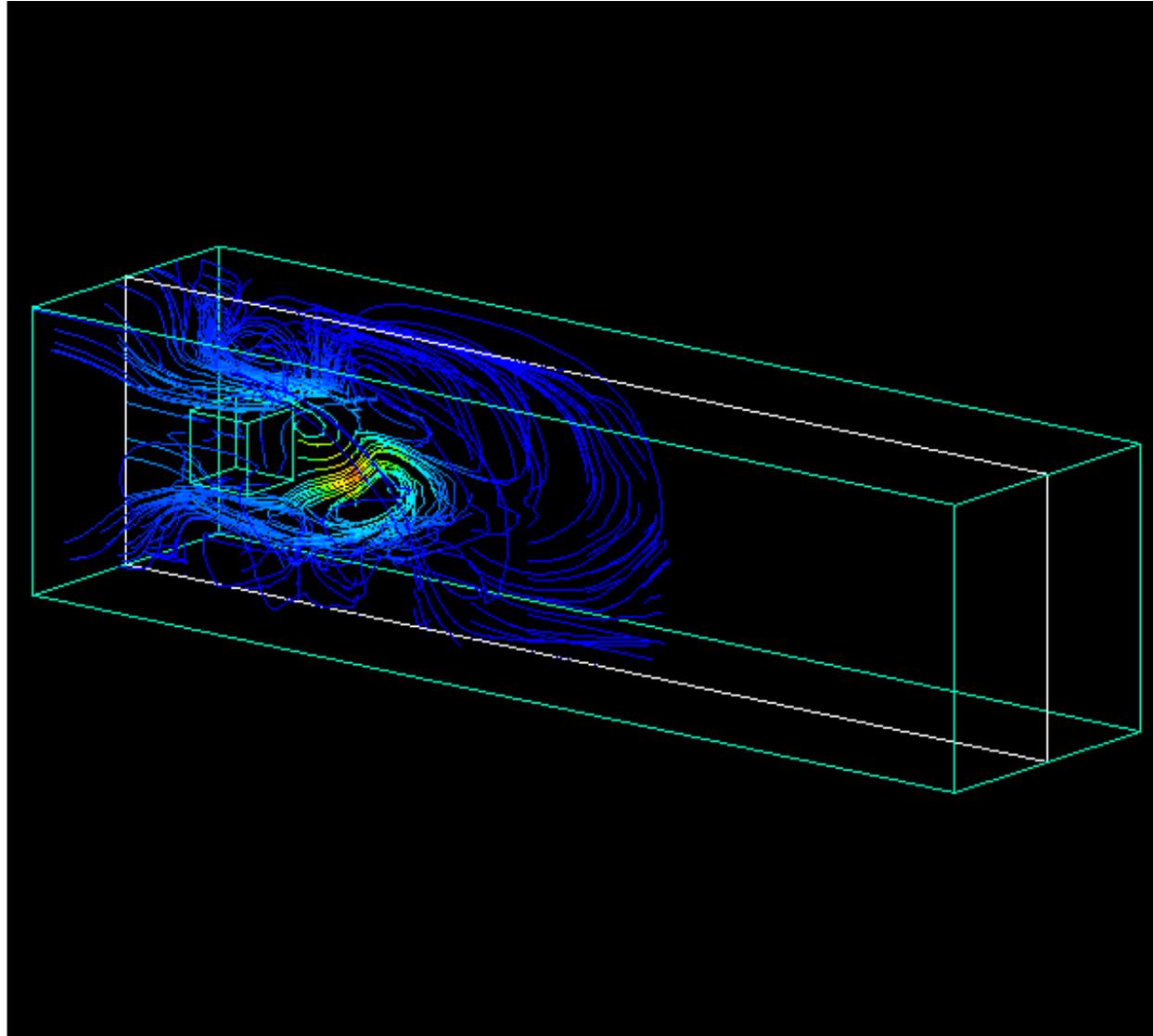
•
•
•

Dual solution, $d(\omega) = 0.0625, t = 1.25$



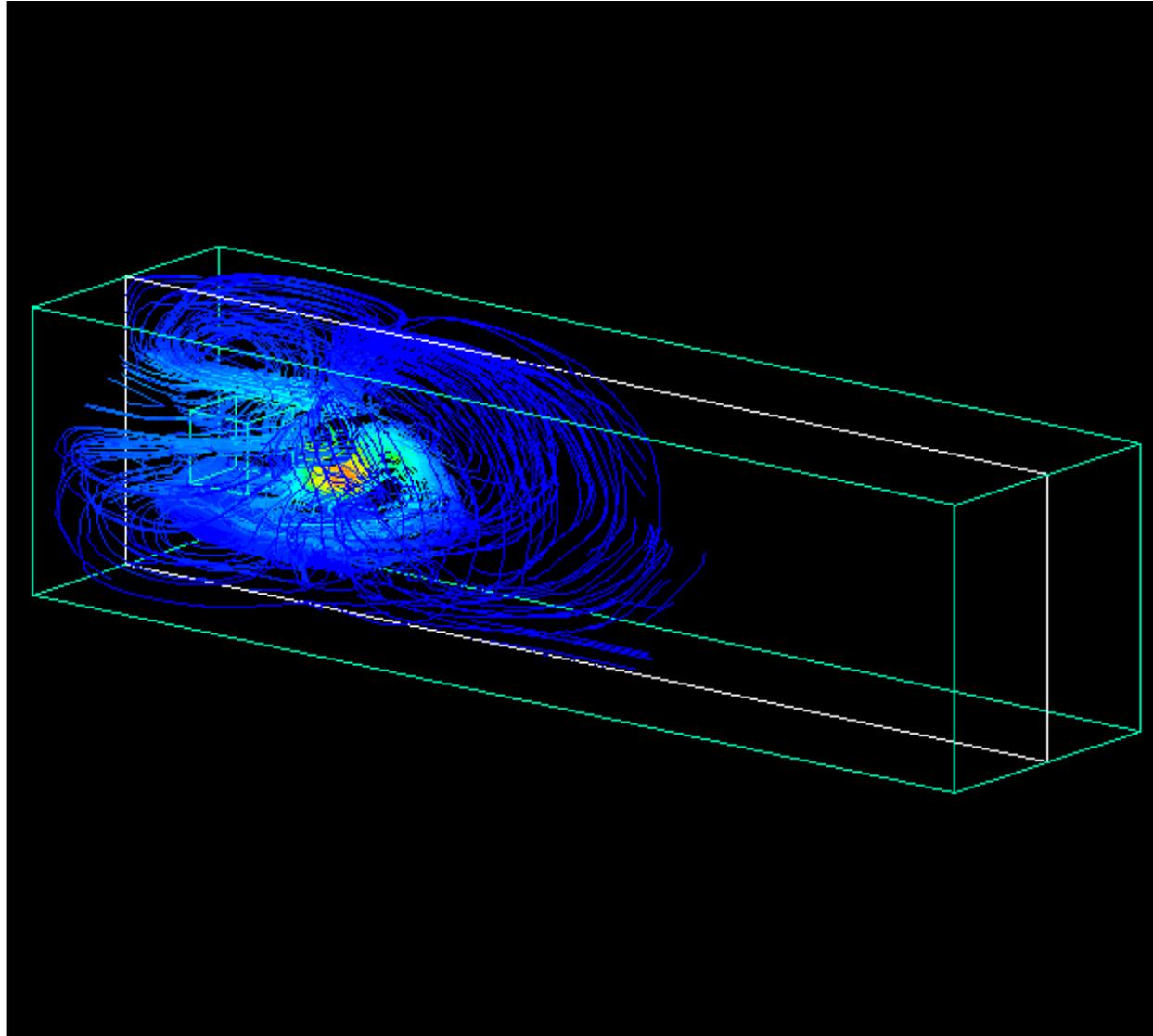
•
•
•

Dual solution, $d(\omega) = 0.0625, t = 1$



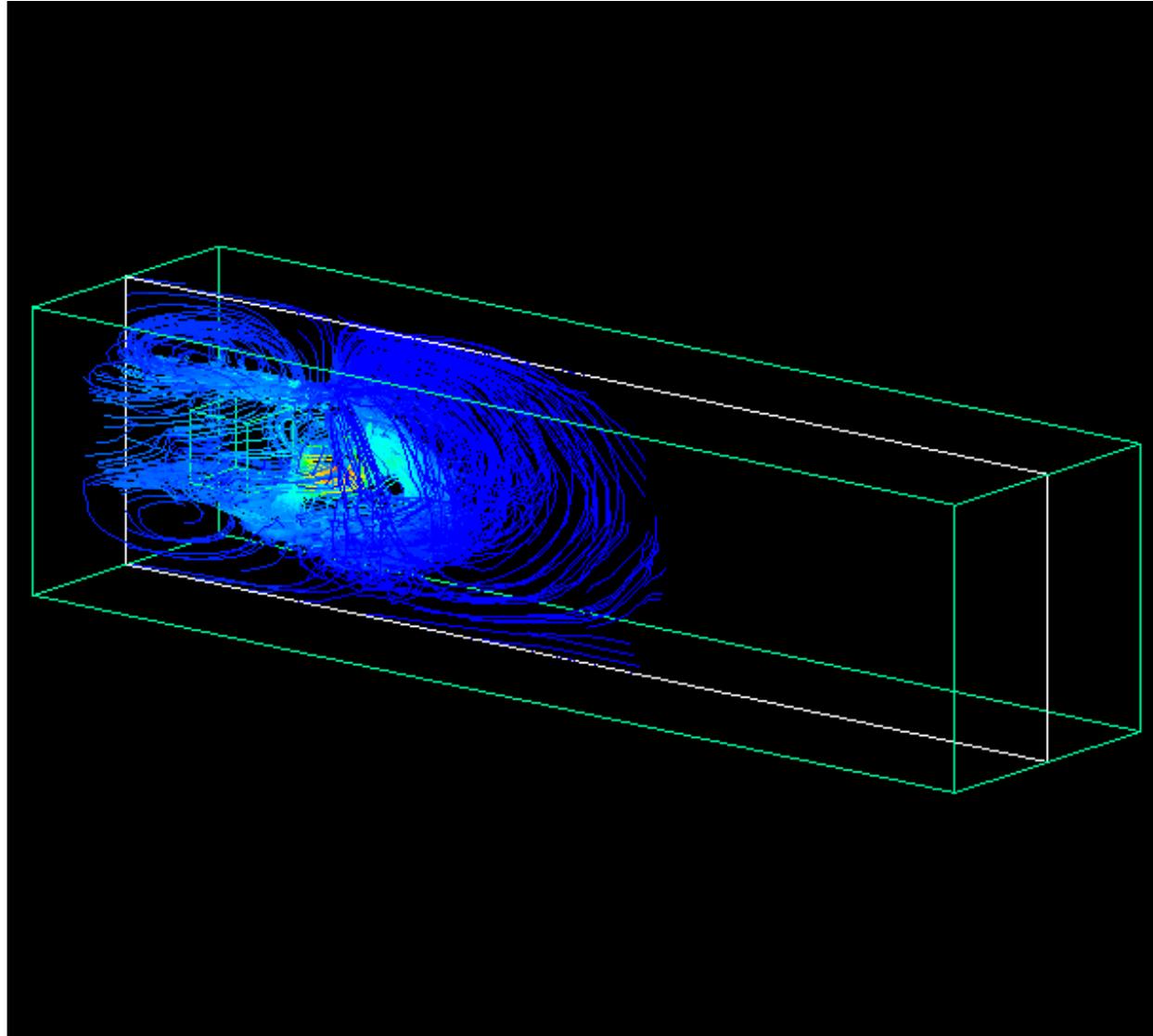
•
•
•

Dual solution, $d(\omega) = 0.0625, t = 0.75$



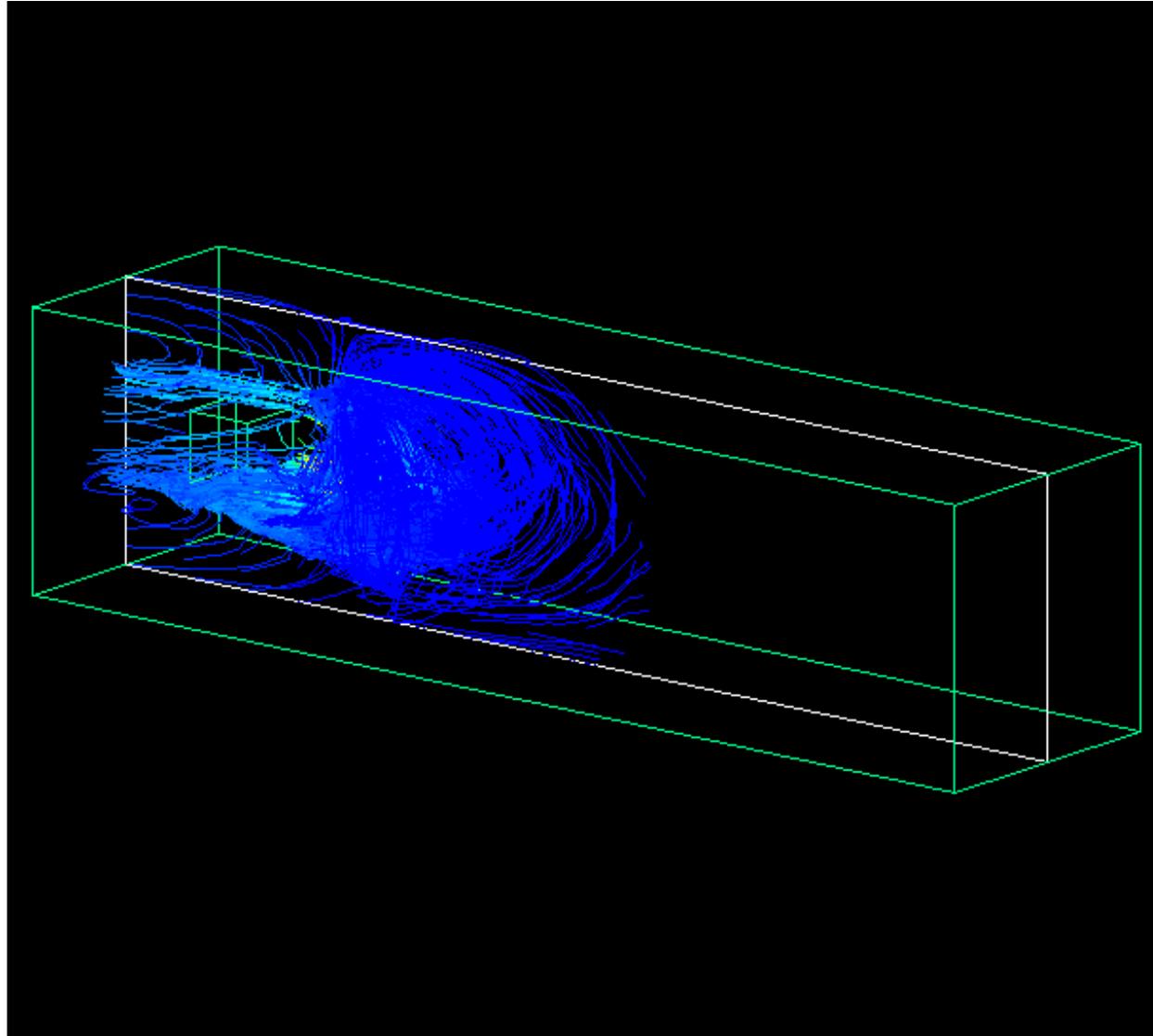
•
•
•

Dual solution, $d(\omega) = 0.0625, t = 0.5$



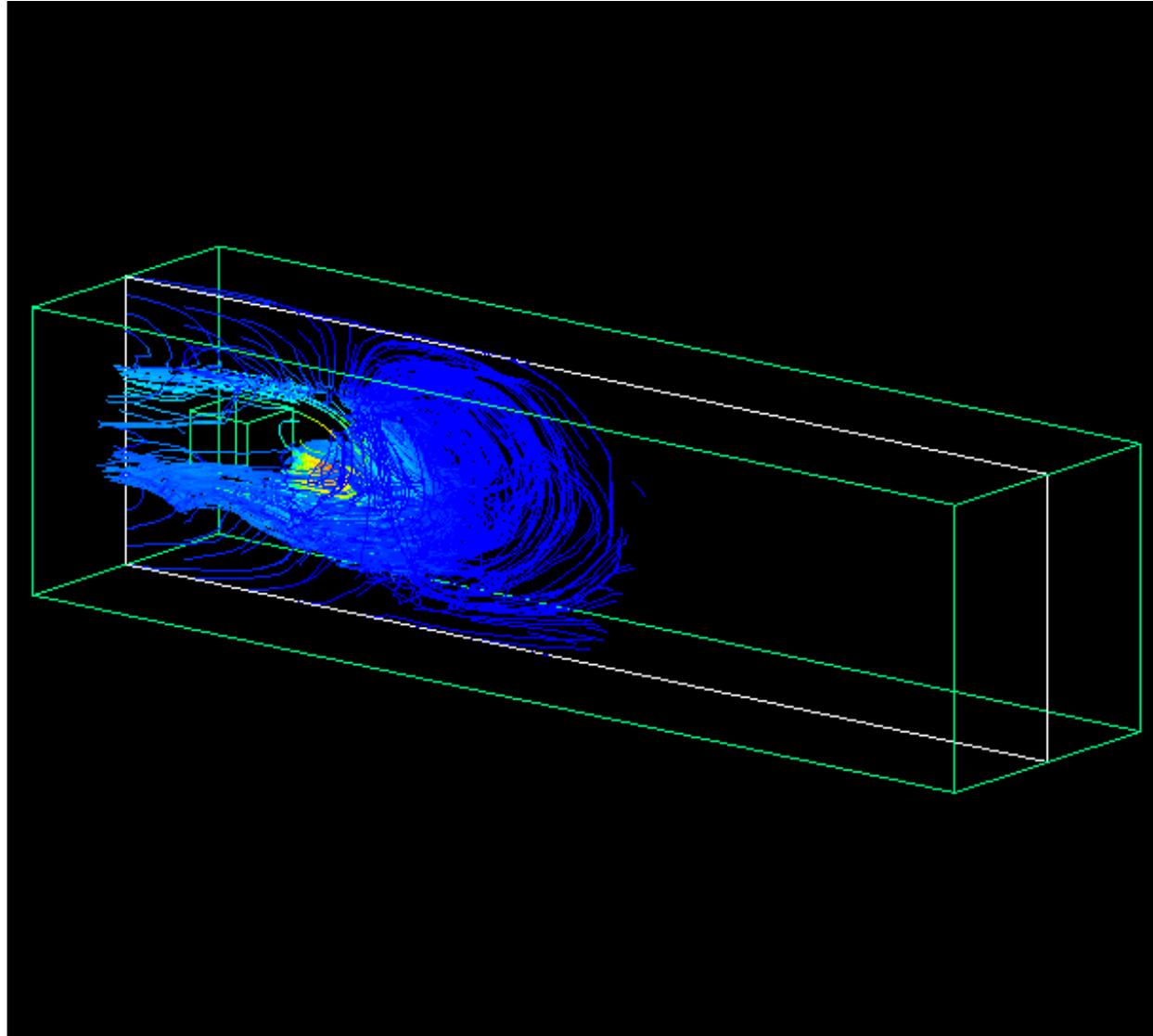
•
•
•

Dual solution, $d(\omega) = 0.0625, t = 0.25$



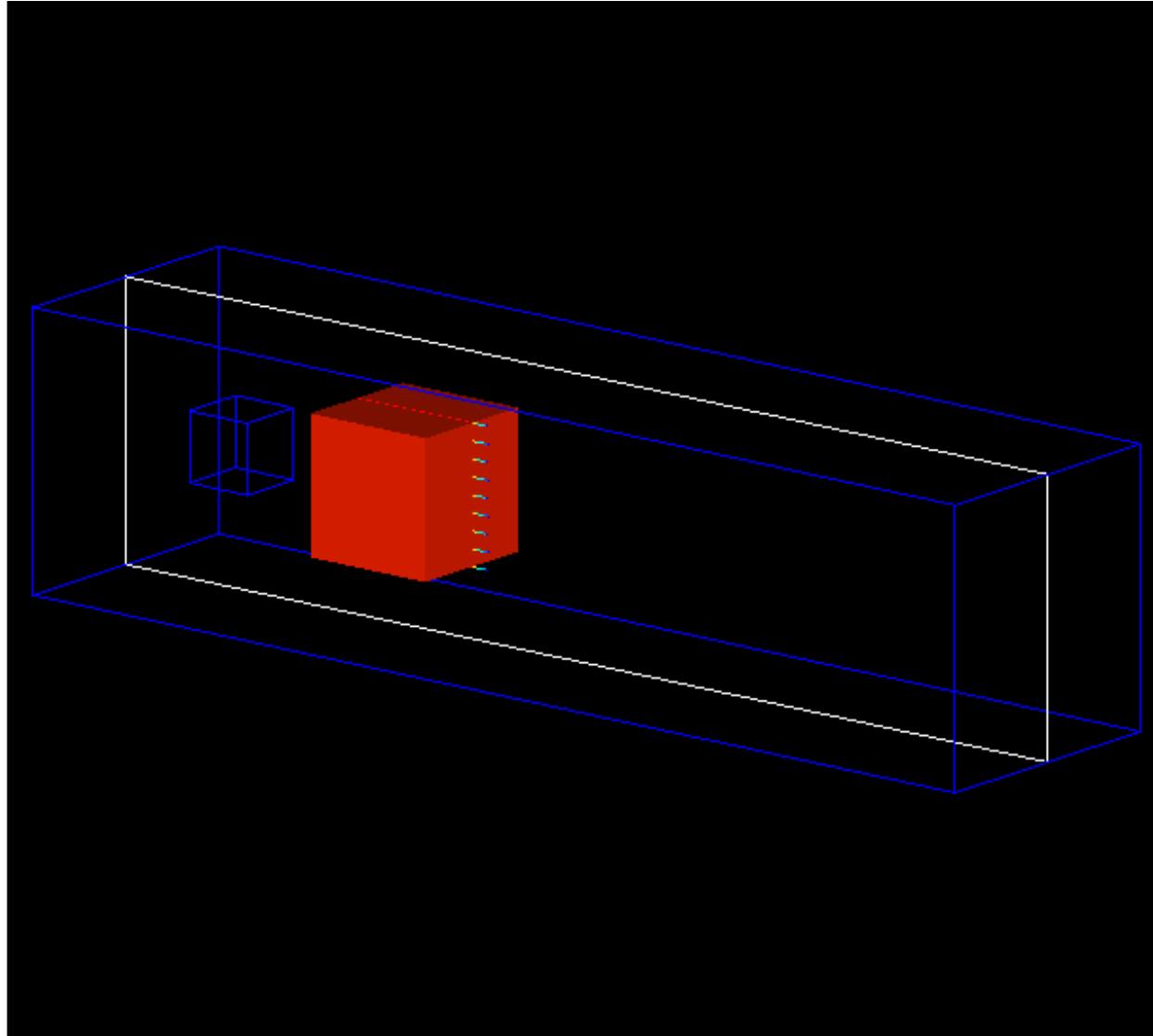
•
•
•

Dual solution, $d(\omega) = 0.0625, t = 0$



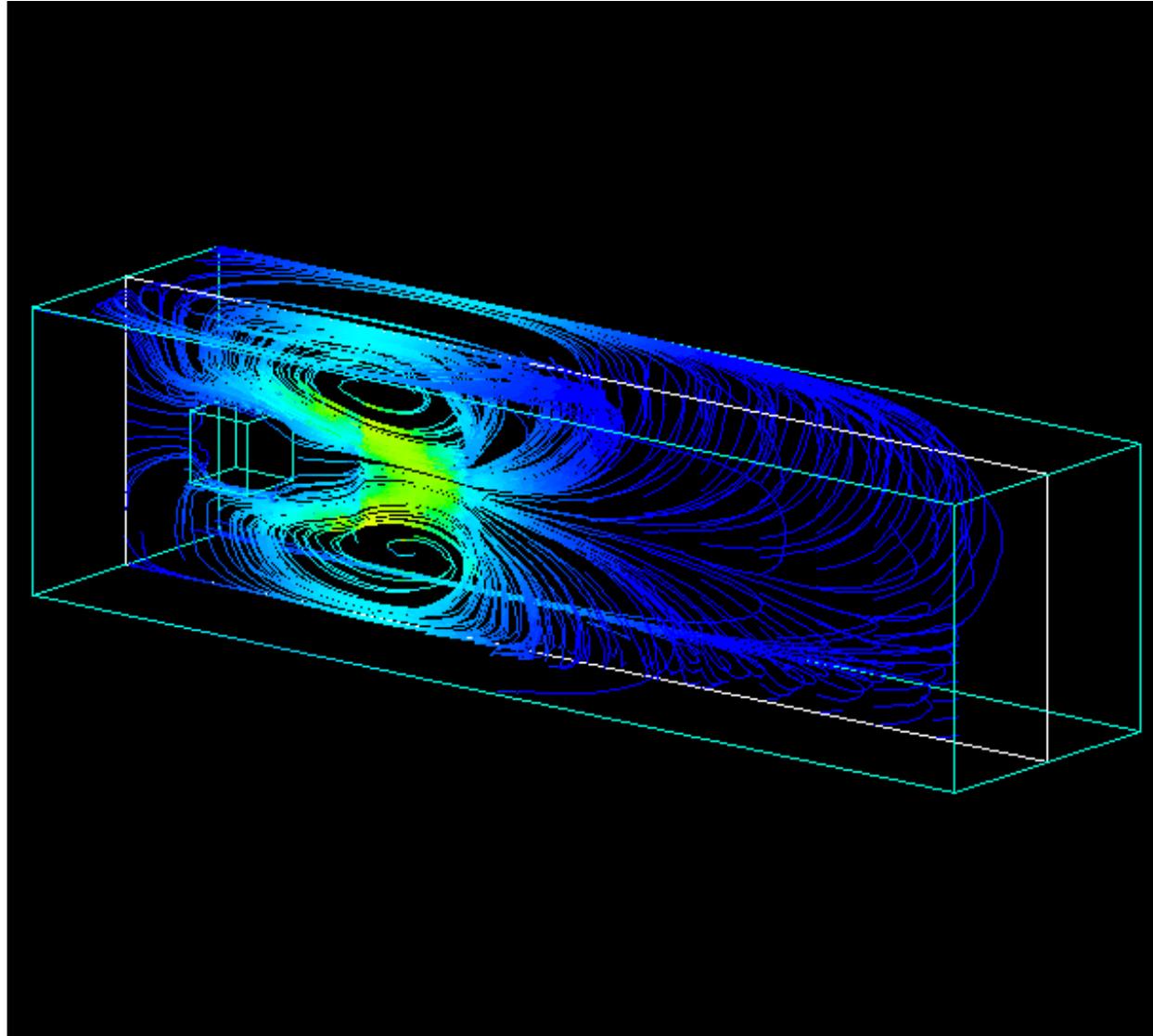
•
•
•

Dual solution, $d(\omega) = 0.5, t = 2$



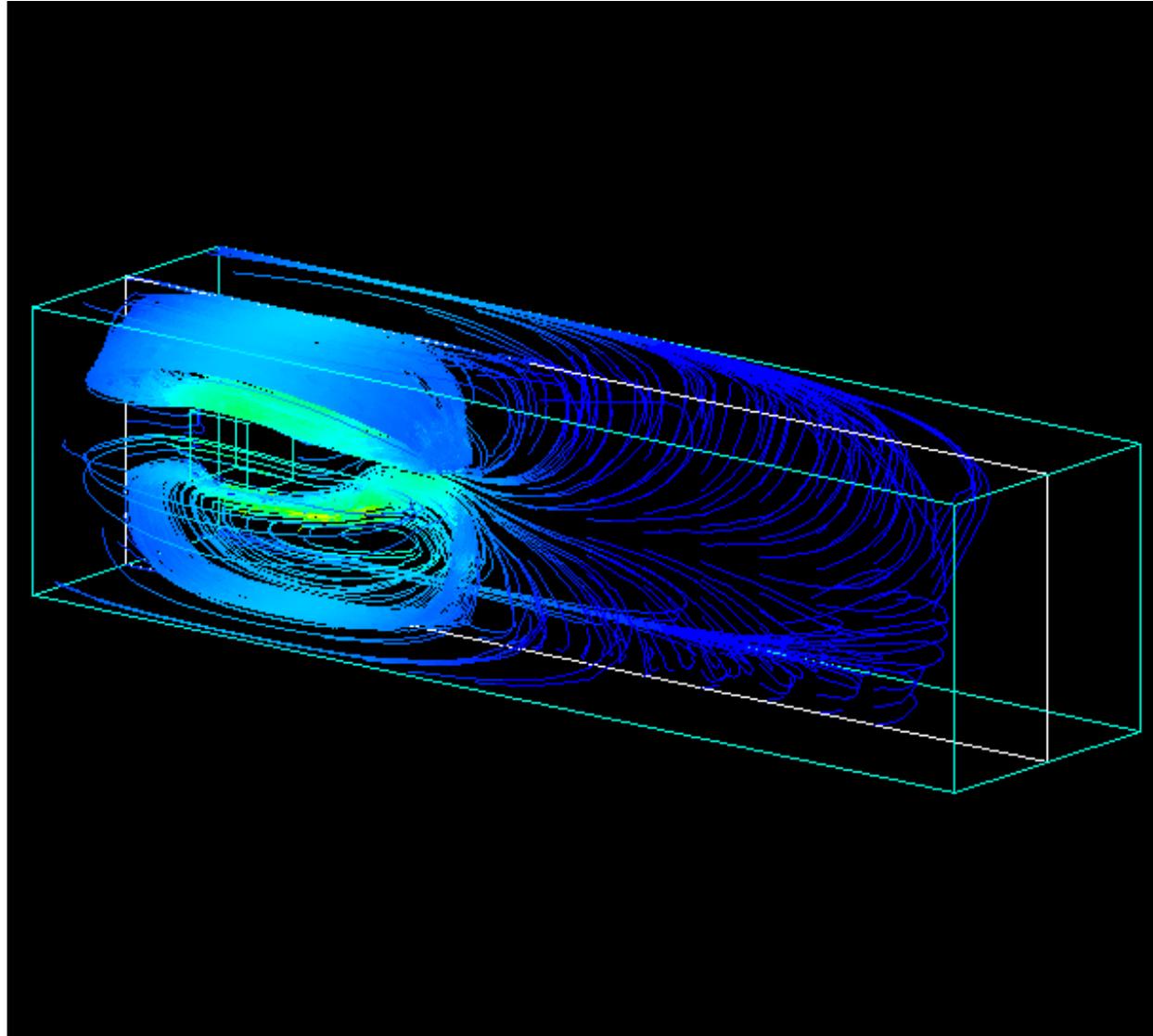
•
•
•

Dual solution, $d(\omega) = 0.5, t = 1.75$



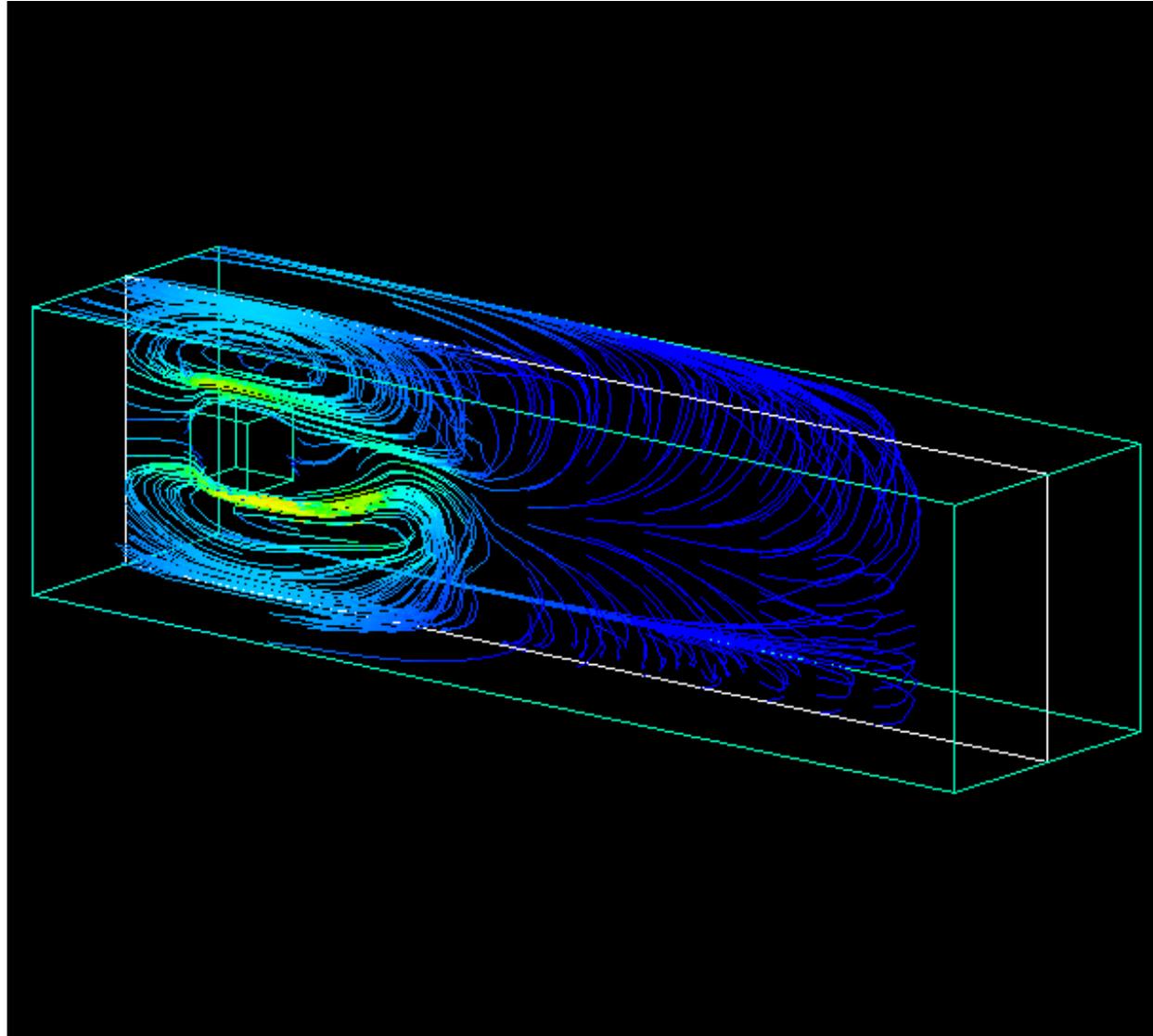
•
•
•

Dual solution, $d(\omega) = 0.5, t = 1.5$



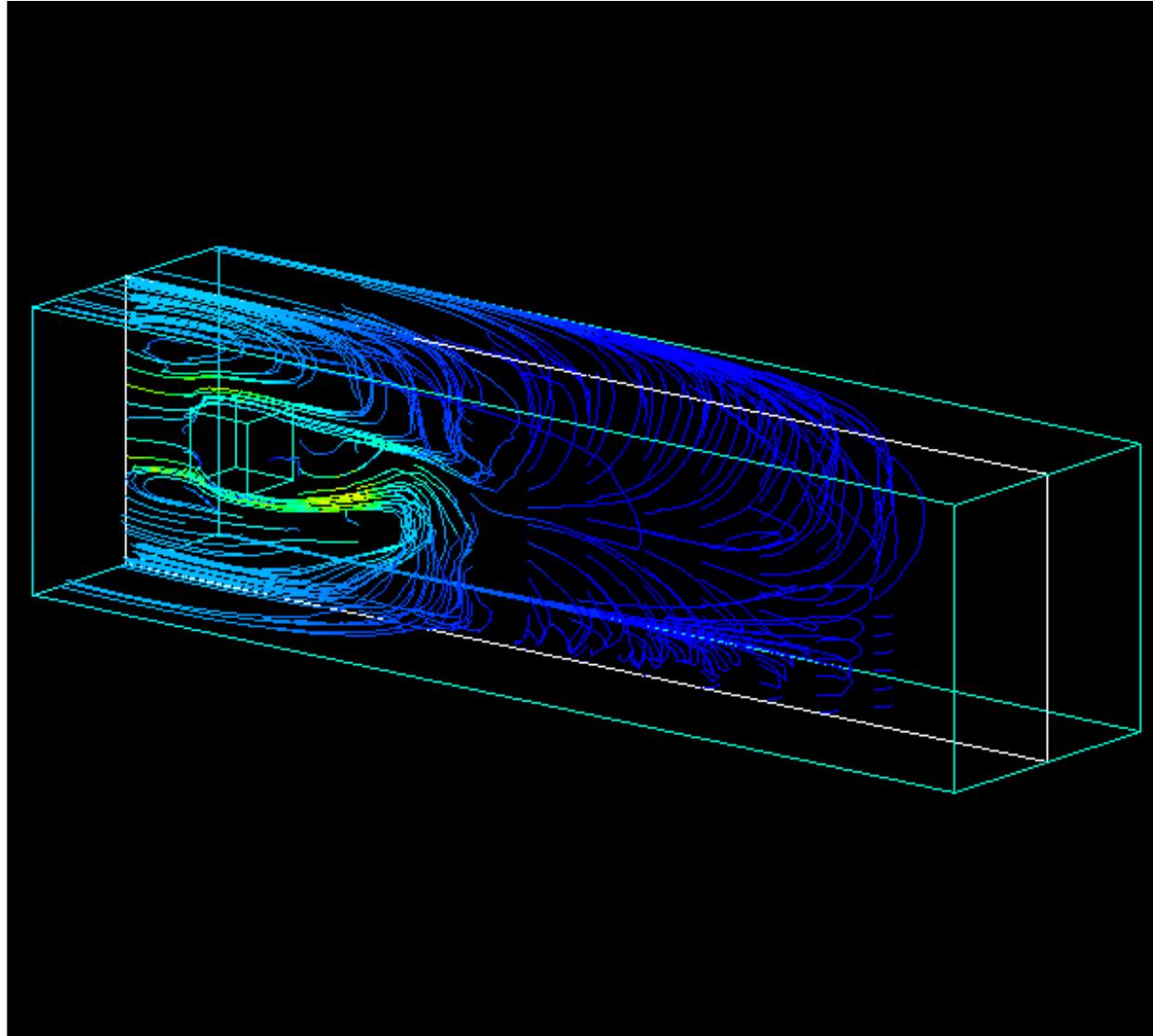
•
•
•

Dual solution, $d(\omega) = 0.5, t = 1.25$



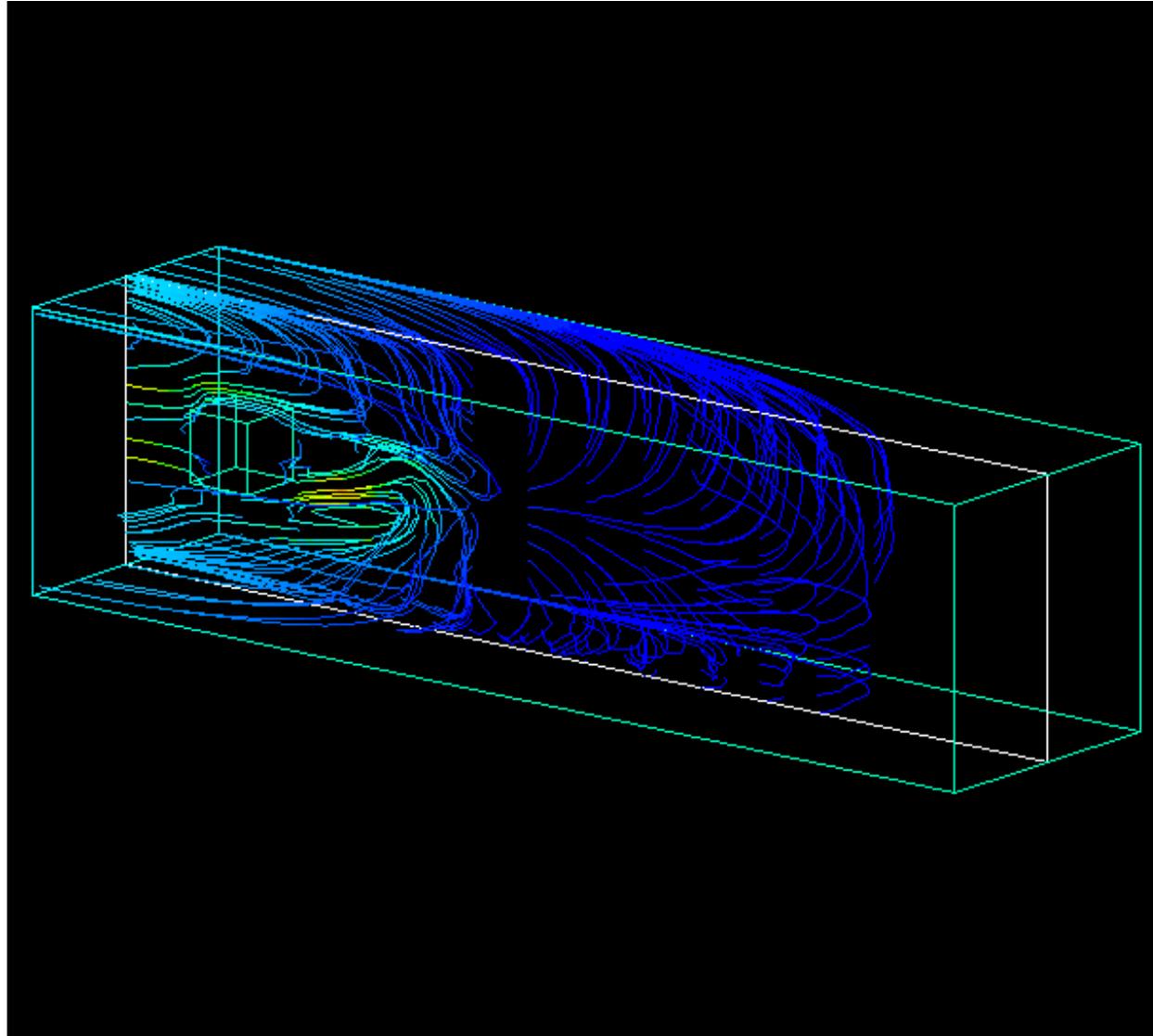
•
•
•

Dual solution, $d(\omega) = 0.5, t = 1$



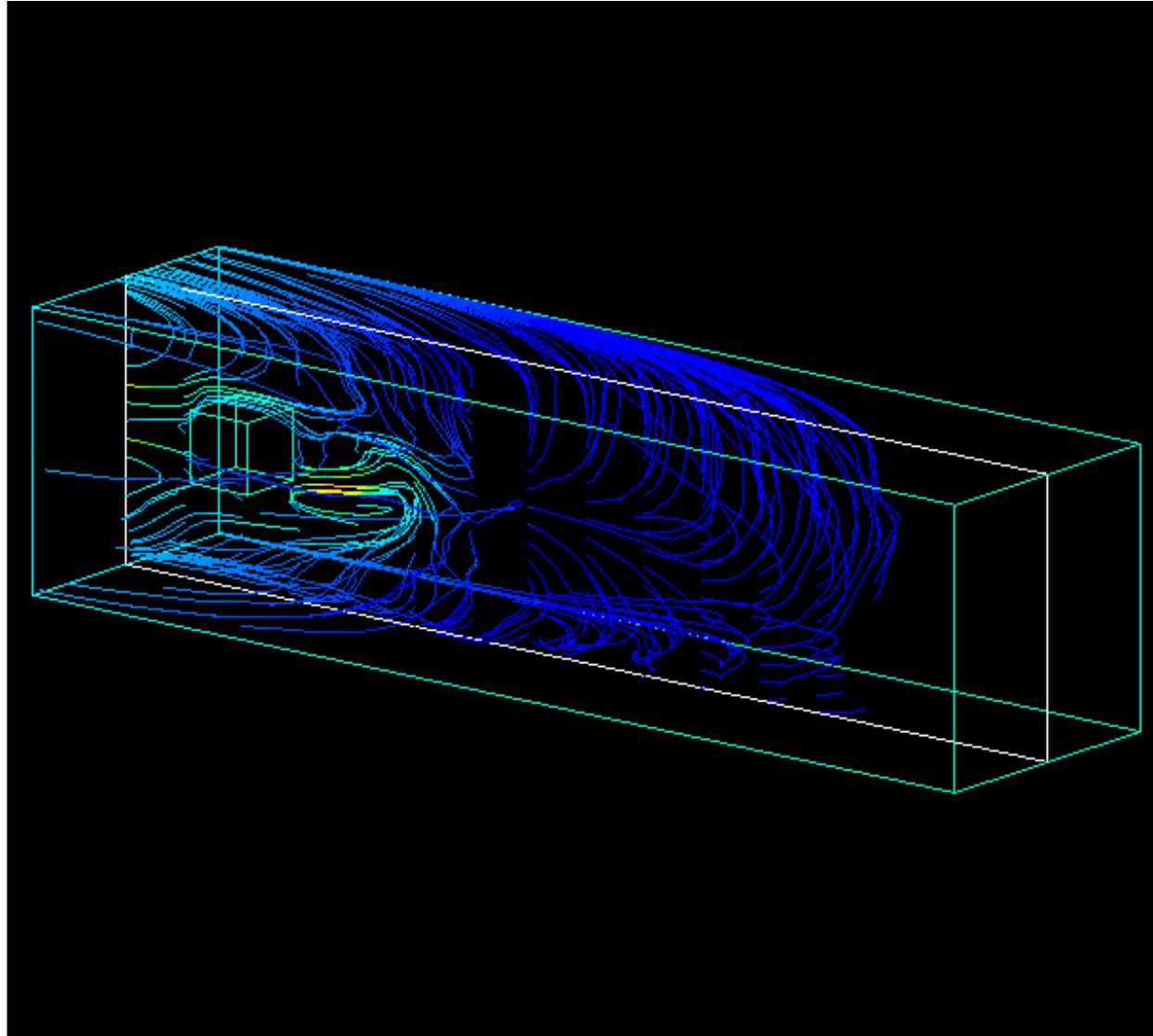
•
•
•

Dual solution, $d(\omega) = 0.5, t = 0.75$



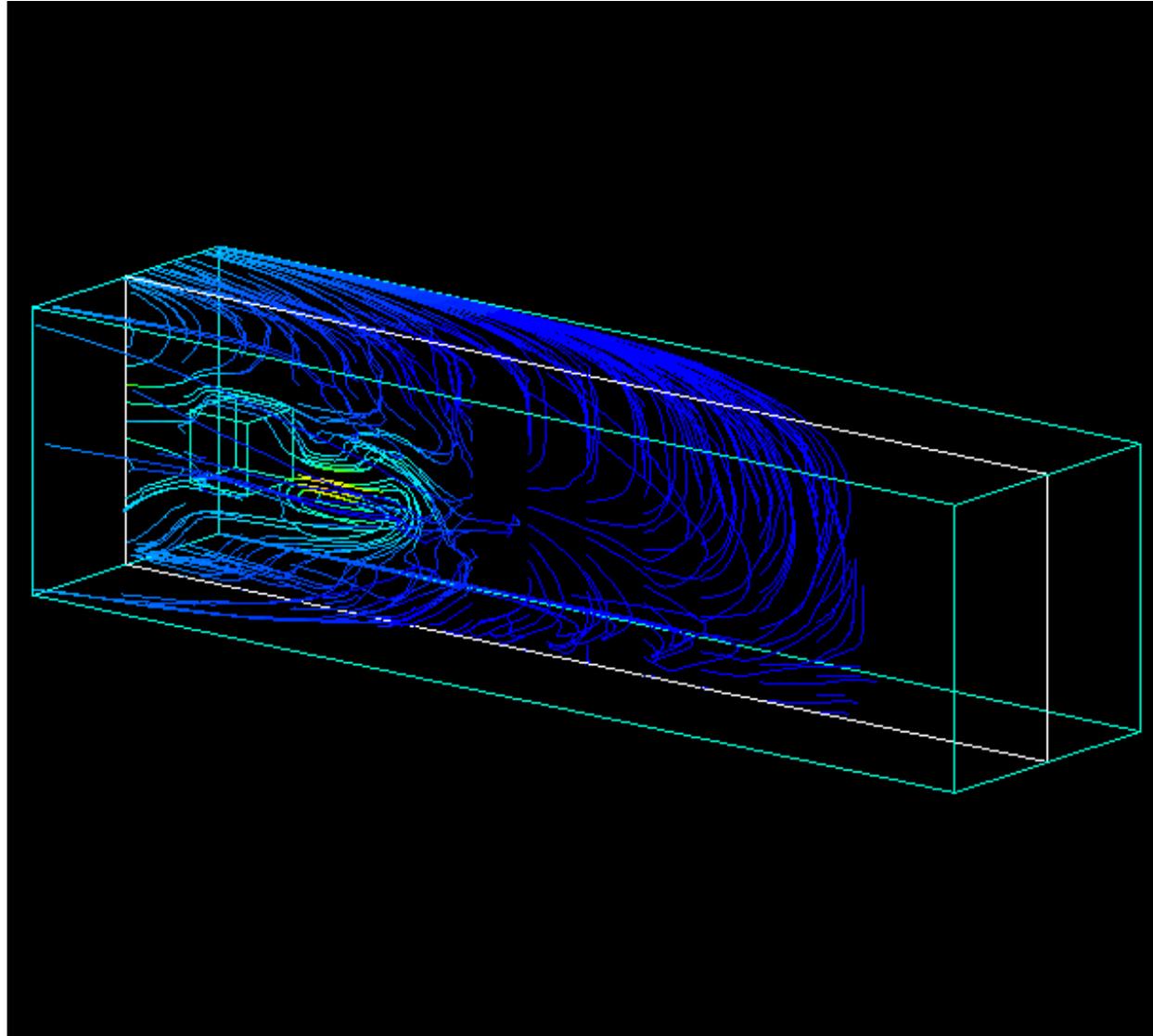
•
•
•

Dual solution, $d(\omega) = 0.5, t = 0.5$



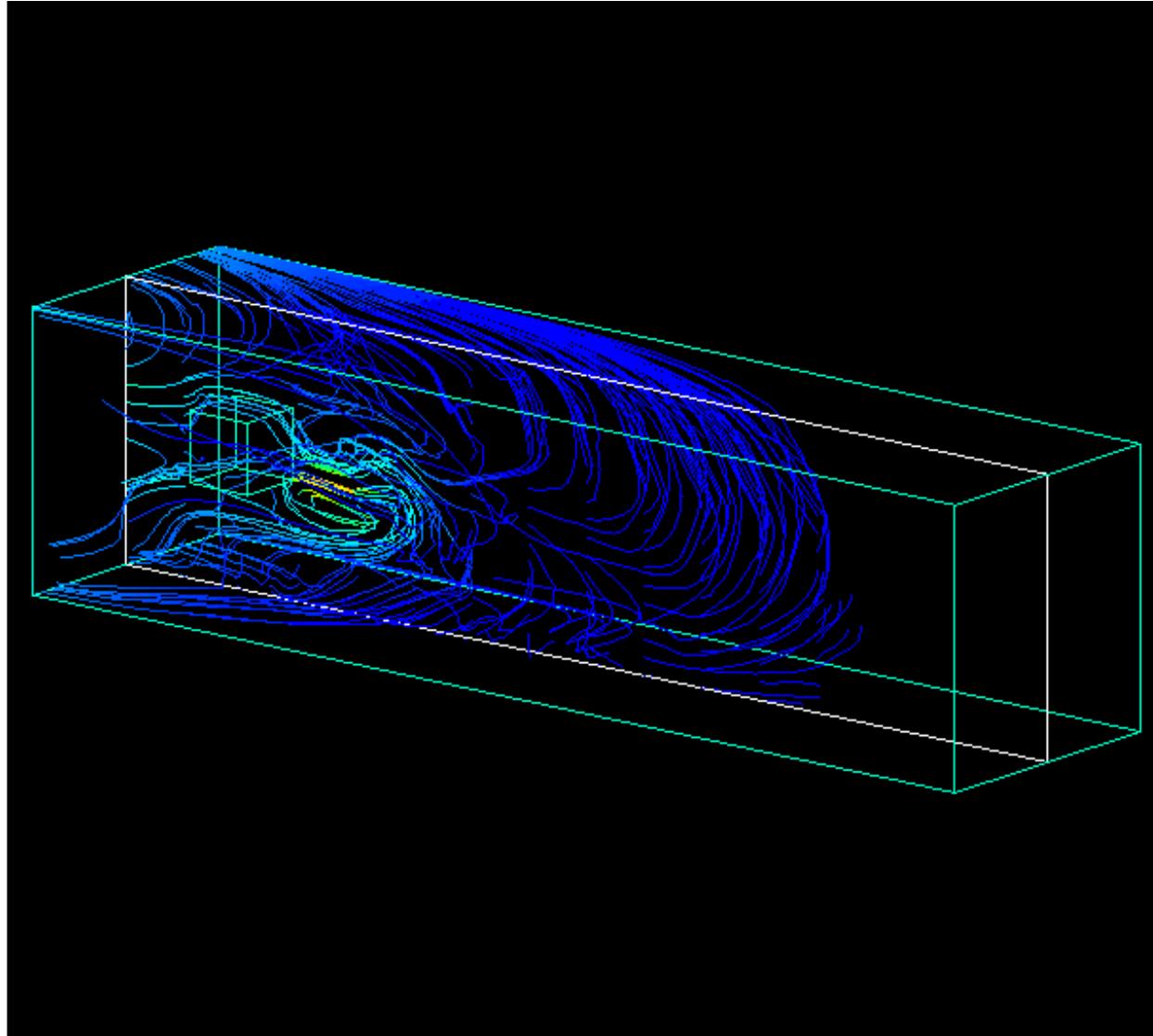
•
•
•

Dual solution, $d(\omega) = 0.5, t = 0.25$



•
•
•

Dual solution, $d(\omega) = 0.5, t = 0$



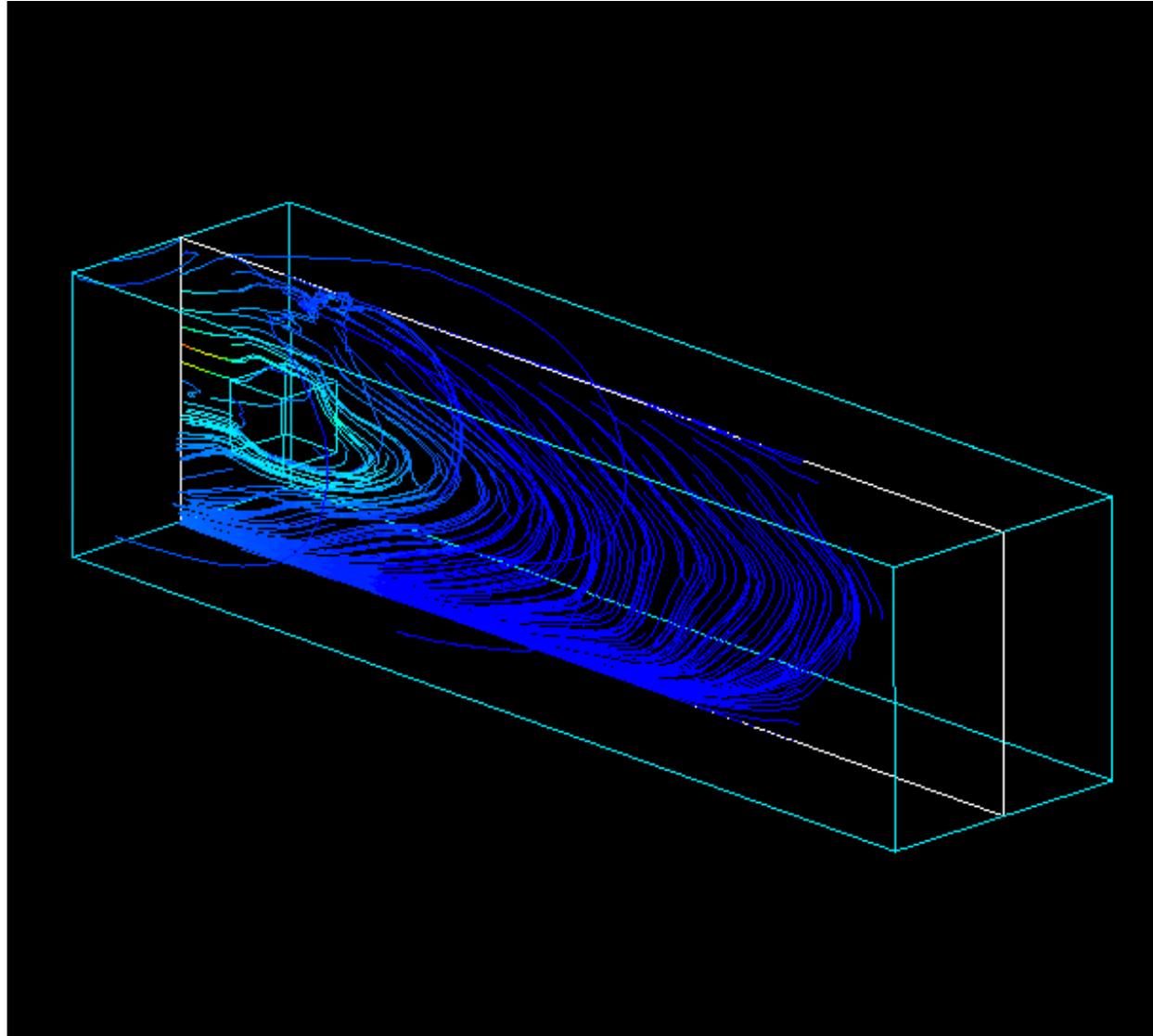
Stability factors with $d(\omega) = 0.25$

Area	$S_{0,1}$	$S_{1,1}$	$S_{1,2}$	$S_{1,3}$	$S_{2,1}$
Behind body	3.1	66.2	14.6	6.4	1533.5
Above body	1.9	32.0	12.3	5.5	663.9

Larger stability factors in the complex flow behind the body

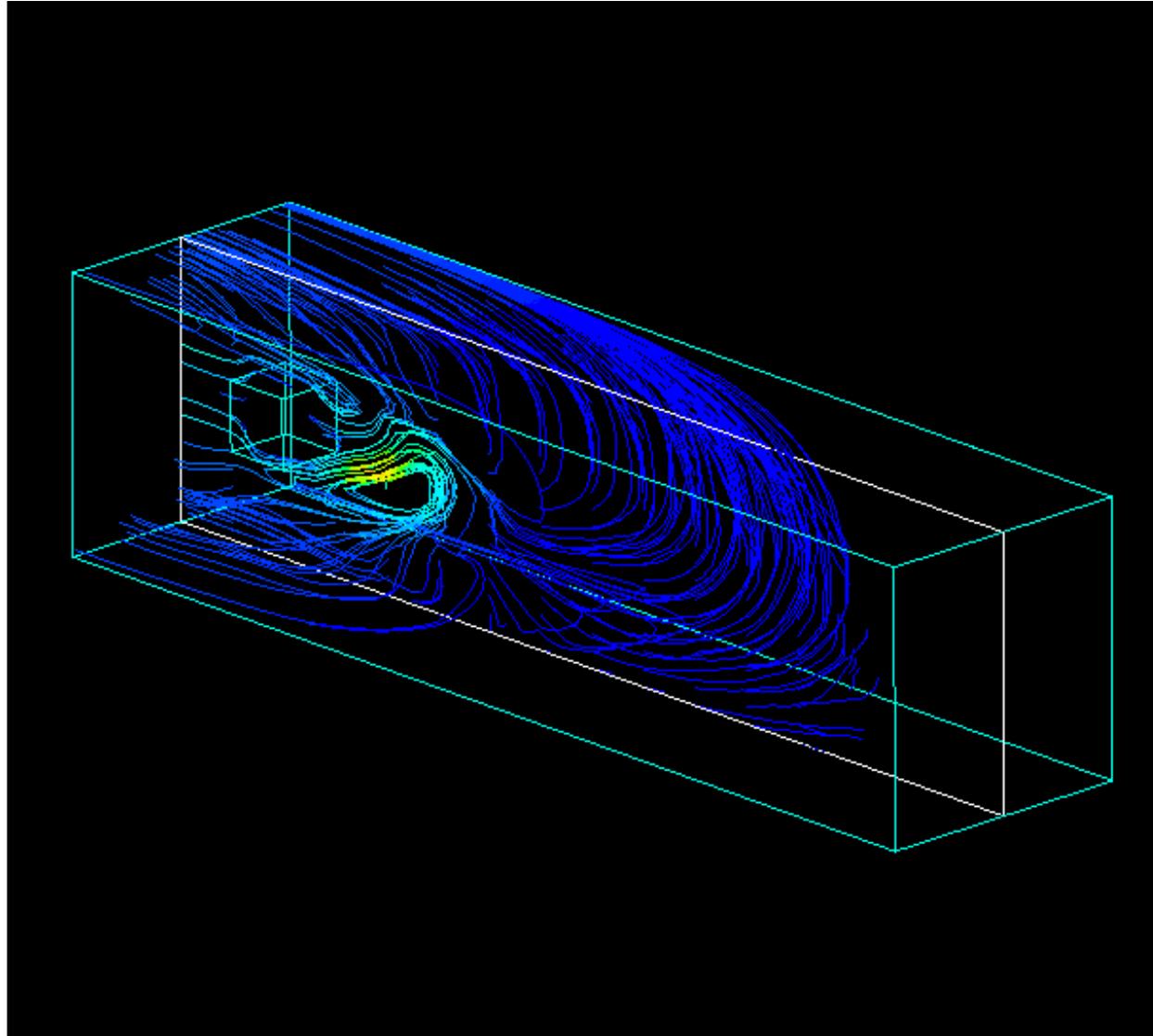
•
•
•

Dual solution at $t = 1$, ψ above body



•
•
•

Dual solution at $t = 1$, ψ behind body



Bluff body - Computation of the drag

- Take the state at $t = 18$ as initial data at $t = 0$
- Want to compute the mean drag force over $I = [0, 2]$, which corresponds to a boundary condition $u = (1/|I|, 0, 0)$ on the surface of the body during $[0, 2]$
- We also compute the mean drag force over $I = [1.75, 2]$, which corresponds to a boundary condition $u = (1/|I|, 0, 0)$ on the surface of the body during $[1.75, 2]$

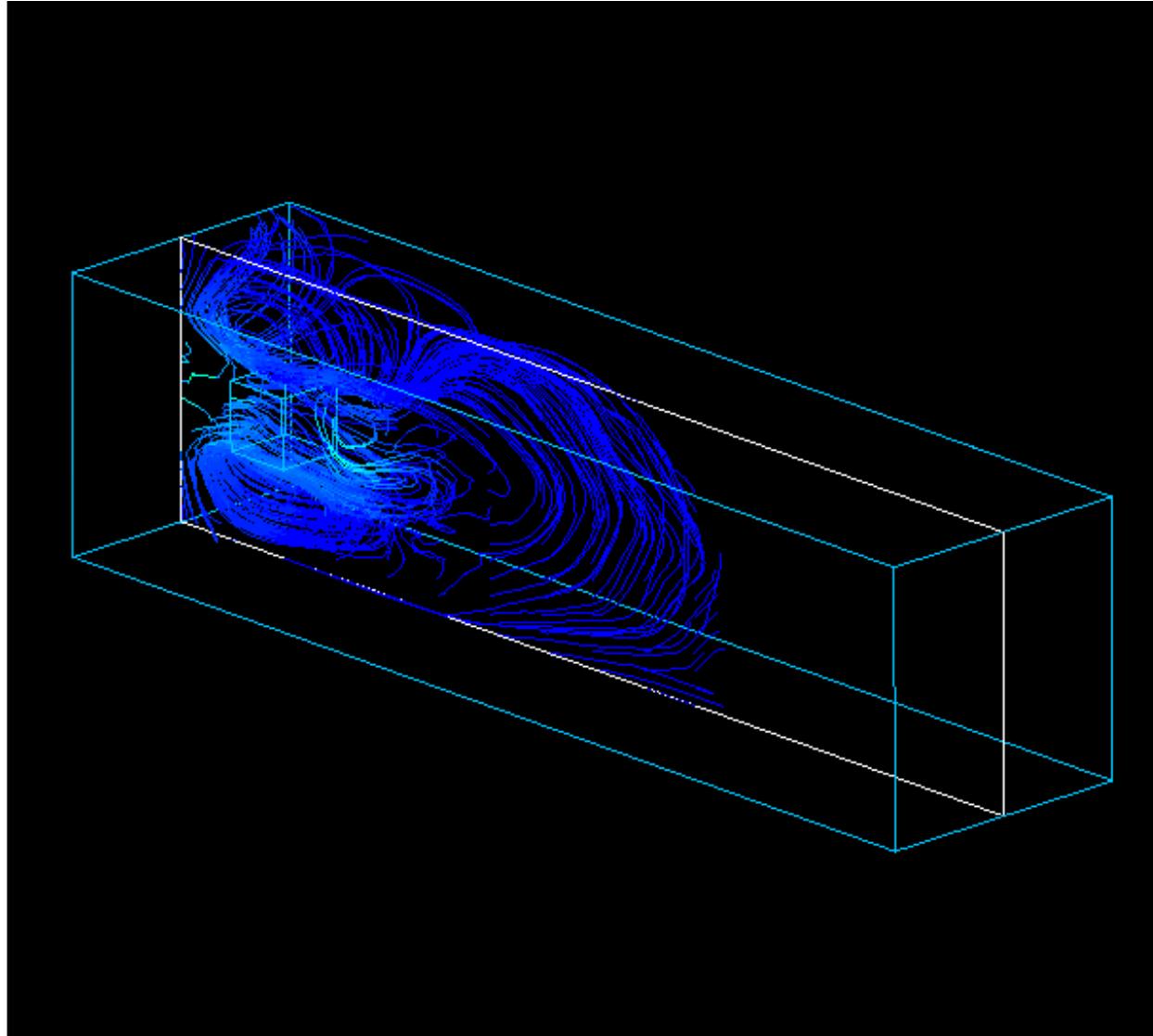
Stability factors for mean drag over I

I	$S_{0,1}$	$S_{1,1}$	$S_{1,2}$	$S_{1,3}$	$S_{2,1}$
$[0, 2]$	0.019	0.39	0.13	0.079	8.8
$[1.75, 2]$	0.43	5.5	0.37	0.29	83.8

Smaller stability factors for averages over longer time intervals

•
•
•

Dual solution for drag, $I = [1.75, 2]$, $t = 1$



Example: Jets

- Channel flow with slip walls, 1×1 rectangular cross section and length 4.
- Obstacle with 4 square holes of size 0.25×0.25 at $x_1 = 0.5$
- $x_1 = 0$ inflow boundary with inflow condition $u = (1, 0, 0)$
- Transparent outflow condition
- cG(1)cG(1), tetrahedral mesh $h = 1/32$
- $\nu = 1/10000$

-
-
-

Example: Jets

start animation

Example: Jets

- The mesh is too coarse for this problem \Rightarrow the residuals are too large

Example: Jets

Stability factors related to the mean error over $\omega \subset \Omega$, $d(\omega) = 0.25$, centered at $(2, 0, 0)$

$S_{0,1}$	$S_{1,1}$	$S_{1,2}$	$S_{1,3}$	$S_{2,1}$
11.1	395.0	41.9	56.7	10374.5

This quantity is not computable on the current mesh since the residuals are too large!

Also the dual solution linearized at U should not be trusted!

Example: Jets

- As a test, compute the dual problem corresponding to the error in the global average over $\Omega \times [0, 2]$, linearized at (the wrong) solution U
- This corresponds to a force $(1, 0, 0)$ in the dual problem (and zero final data)

Stability factors for the jets

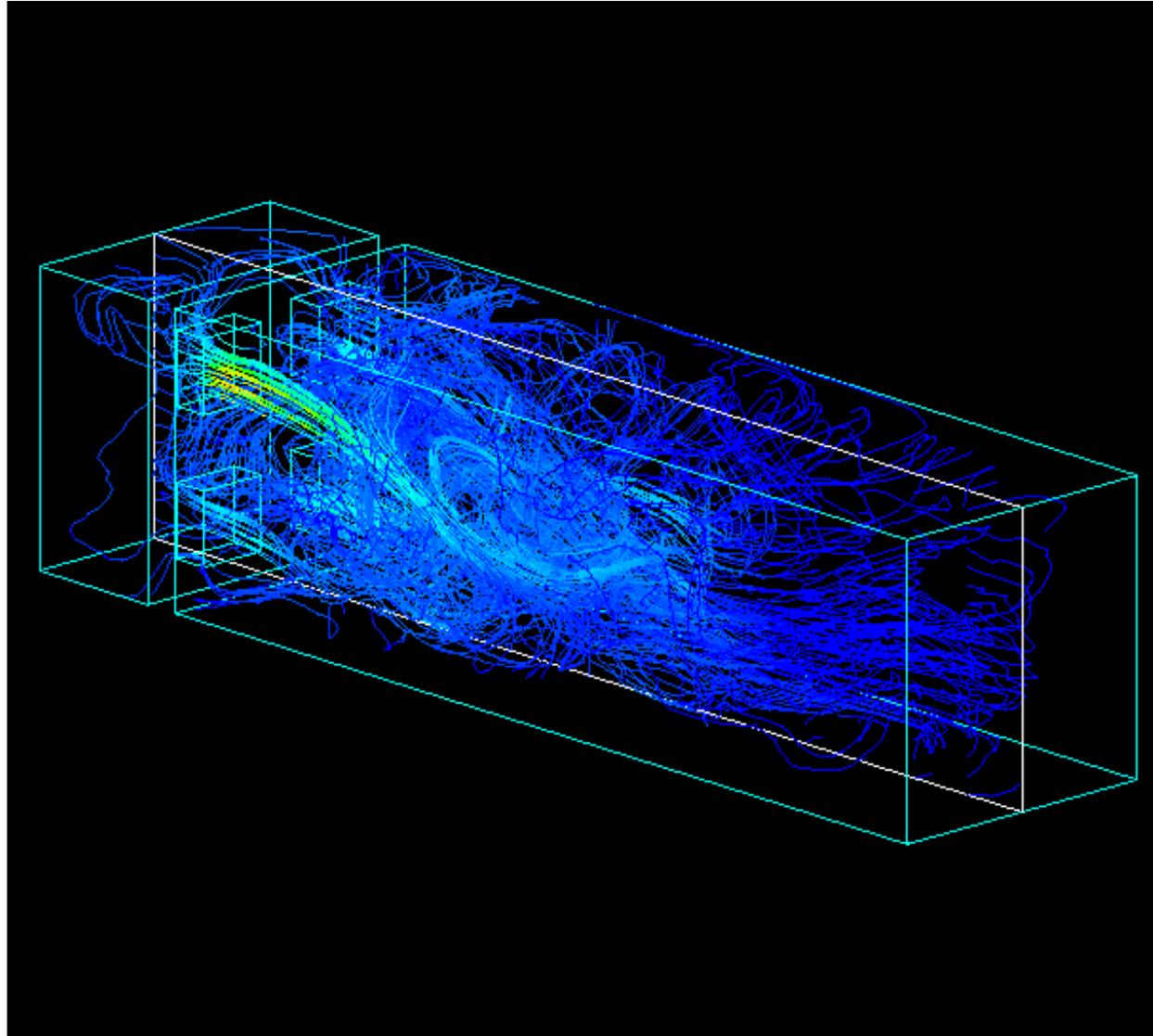
Stability factors related to the mean error over $\omega \subset \Omega$, with $d(\omega) = 0.25$ at $t = 2$ (local), and over $\Omega \times [0, 2]$ (global)

ω	$S_{0,1}$	$S_{1,1}$	$S_{1,2}$	$S_{1,3}$	$S_{2,1}$
local	11.1	395.0	41.9	56.7	10374.5
global	0.077	1.8	0.17	1.0	44.7

Global stability factors are considerably smaller, indicating that global quantities may be computed if the residuals were smaller \Rightarrow Good news!

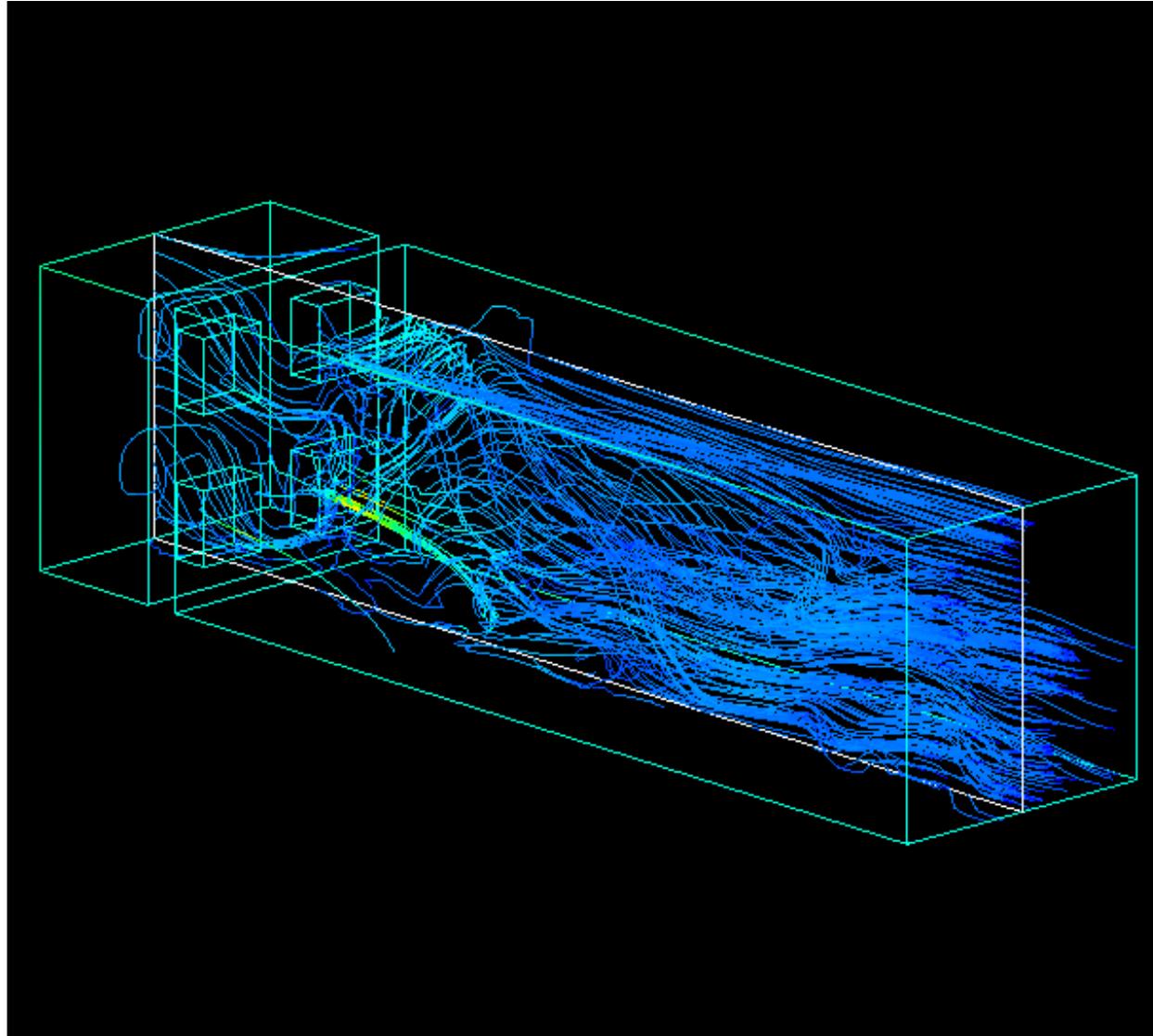
•
•
•

Dual solution, jet with local data, $t = 1$



•
•
•

Dual solution, jet with global data, $t = 1$



Perturbation growth in NSE

- Linear/exponential perturbation growth?
- Transition to turbulence

Linearized Navier-Stokes eqns. (LNSE)

$$\begin{aligned}\varphi_t + u \cdot \nabla \varphi + (\varphi \cdot \nabla)u - \nu \Delta \varphi + \nabla q &= g \\ \nabla \cdot \varphi &= 0 \\ \varphi|_{\partial\Omega} = 0, \quad \varphi(\cdot, 0) &= \varphi^0\end{aligned}$$

(φ, q) perturbation of given solution (u, p) to NSE, obtained by subtracting (u, p) from $(u + \varphi, p + q)$ corresponding to perturbed initial data $u^0 + \varphi^0$ and right hand side $f + g$, omitting $(\varphi \cdot \nabla)\varphi$

Linearized Navier-Stokes eqns. (LNSE)

$$\begin{aligned}\varphi_t + u \cdot \nabla \varphi + (\varphi \cdot \nabla)u - \nu \Delta \varphi + \nabla q &= g \\ \nabla \cdot \varphi &= 0 \\ \varphi|_{\partial\Omega} = 0, \quad \varphi(\cdot, 0) &= \varphi^0\end{aligned}$$

Again the interaction between the transport $u \cdot \nabla \varphi$, the diffusion $-\nu \Delta \varphi$, and the reaction $(\varphi \cdot \nabla)u$ is crucial

Linearized Navier-Stokes eqns. (LNSE)

$$\begin{aligned}\varphi_t + u \cdot \nabla \varphi + (\varphi \cdot \nabla)u - \nu \Delta \varphi + \nabla q &= g \\ \nabla \cdot \varphi &= 0 \\ \varphi|_{\partial\Omega} = 0, \quad \varphi(\cdot, 0) &= \varphi^0\end{aligned}$$

The basic question is to estimate (φ, q) in terms of the data (g, φ_0)

Linearized Navier-Stokes eqns. (LNSE)

$$\begin{aligned}\varphi_t + u \cdot \nabla \varphi + (\varphi \cdot \nabla)u - \nu \Delta \varphi + \nabla q &= g \\ \nabla \cdot \varphi &= 0 \\ \varphi|_{\partial\Omega} = 0, \quad \varphi(\cdot, 0) &= \varphi^0\end{aligned}$$

Weak stability factor $S_0(u, T, \varphi_0) = \frac{\|\varphi\|_I}{\|\varphi^0\|}$

where φ is the sol. to LNSE with $g = 0$ and $\varphi_0 \neq 0$

Linearized Navier-Stokes eqns. (LNSE)

$$\begin{aligned}\varphi_t + u \cdot \nabla \varphi + (\varphi \cdot \nabla)u - \nu \Delta \varphi + \nabla q &= g \\ \nabla \cdot \varphi &= 0 \\ \varphi|_{\partial\Omega} = 0, \quad \varphi(\cdot, 0) &= \varphi^0\end{aligned}$$

Weak stability factor $S_0(u, T) = \sup_{\varphi^0 \in L_2} \frac{\|\varphi\|_I}{\|\varphi^0\|}$

($\|v\|_I = \sup_{0 < t < T} \|v(\cdot, t)\|$)

Worst case exponential pertub. growth

$$\|\varphi(\cdot, t)\|^2 \leq -2 \int_0^t \int_{\Omega} (\varphi \cdot \nabla) u \cdot \varphi \, dx ds + \|\varphi^0\|^2$$

from multiplying LNSE by φ and integrating in space and time

Worst case exponential pertub. growth

$$\|\varphi(\cdot, t)\|^2 \leq -2 \int_0^t \int_{\Omega} (\varphi \cdot \nabla)u \cdot \varphi \, dx ds + \|\varphi^0\|^2$$

Grönwall's inequality $\Rightarrow S_0(u, T) \leq \exp(CKT)$,

where $C \approx 1$ and $K = \|\nabla u\|_{\infty}$

Exp. growth due to the zero order (reaction) term

$$(\varphi \cdot \nabla)u$$

Worst case exponential pertub. growth

Worst case exponential perturbation growth:

$$\|\varphi(\cdot, t)\|^2 \leq -2 \int_0^t \int_{\Omega} (\varphi \cdot \nabla)u \cdot \varphi \, dx ds + \|\varphi^0\|^2$$

A flow with exponential perturbation growth cannot exist as a stable flow \Rightarrow

Must be possible to obtain reduced growth rates by using special features of the zero order term

$(\varphi \cdot \nabla)u$ in some cases

Nearly parallel flow/shear flow

$$\|u_1\| \approx 1, \quad \|\bar{\nabla} u_1\|_\infty = C, \quad \|\bar{u}\|_\infty + \|\bar{\nabla} \bar{u}\|_\infty \leq c\nu,$$

where $\bar{u} = (u_2, u_3)$, $\bar{\nabla} = (\partial/\partial x_2, \partial/\partial x_3)$

$$u_1 \approx 1, \quad u_{1,1} \sim \nu, \quad u_{2,1}, u_{3,1} \sim \nu^2, \quad T \sim 1/\nu = \text{Re}$$

Assume that the perturbations (φ, q) are independent of x_1

Nearly parallel flow/shear flow

$$\begin{aligned}\varphi_{1,t} + u \cdot \nabla \varphi_1 + (\bar{\varphi} \cdot \bar{\nabla}) u_1 - \nu \Delta \varphi_1 &= 0 \\ \bar{\varphi}_t + u \cdot \nabla \bar{\varphi} + (\bar{\varphi} \cdot \bar{\nabla}) \bar{u} - \nu \Delta \bar{\varphi} + \bar{\nabla} q &= 0 \\ \bar{\nabla} \cdot \bar{\varphi} \equiv \varphi_{2,2} + \varphi_{3,3} &= 0 \\ \varphi|_{\partial\Omega} = 0, \quad \varphi(\cdot, 0) &= \varphi^0\end{aligned}$$

Observe that $\bar{\varphi}$ is fully decoupled from φ_1 !

Nearly parallel flow/shear flow

$$\begin{aligned}\varphi_{1,t} + u \cdot \nabla \varphi_1 + (\bar{\varphi} \cdot \bar{\nabla}) u_1 - \nu \Delta \varphi_1 &= 0 \\ \bar{\varphi}_t + u \cdot \nabla \bar{\varphi} + (\bar{\varphi} \cdot \bar{\nabla}) \bar{u} - \nu \Delta \bar{\varphi} + \bar{\nabla} q &= 0 \\ \bar{\nabla} \cdot \bar{\varphi} \equiv \varphi_{2,2} + \varphi_{3,3} &= 0 \\ \varphi|_{\partial\Omega} = 0, \quad \varphi(\cdot, 0) &= \varphi^0\end{aligned}$$

And that no zero order (reaction) term is not present in the equation for φ_1

Nearly parallel flow/shear flow

Compare with the ODE

$$\begin{aligned}\dot{\varphi}_1 - \varphi_2 &= 0 \\ \dot{\varphi}_2 &= 0 \\ \varphi^0 &= (0, \varphi_2^0)\end{aligned}$$

with solution $\varphi_1(t) = t \varphi_2^0$, $\varphi_2(t) = \varphi_2^0$, showing linear growth for φ_1

Nearly parallel flow/shear flow

Compare with the ODE

$$\begin{aligned}\dot{\varphi}_1 - \varphi_2 &= 0 \\ \dot{\varphi}_2 &= 0 \\ \varphi^0 &= (0, \varphi_2^0)\end{aligned}$$

with solution $\varphi_1(t) = t \varphi_2^0$ and $\varphi_2(t) = \varphi_2^0$, showing linear growth for φ_1 , which is very different from

$$\dot{\varphi}_1 - \varphi_1 = 0, \quad \varphi_1^0 \neq 0$$

with solution $\varphi_1(t) = \exp(t) \varphi_1^0$

Nearly parallel flow/shear flow

THEOREM: For nearly parallel flow and $T = \nu^{-1}$:

$$S_0(u, T) \leq C\nu^{-1}$$

We refer to the physical mechanism corresponding to this linear perturbation growth as the Taylor-Görtler mechanism

Nearly parallel flow/shear flow

Consider laminar pipe flow in a pipe directed along the x_1 axis:

- cross section ω
- velocity $u = (u_1, 0, 0)$
- computed velocity $U = (U_1, 0, 0)$
- u and U depends on (x_2, x_3) and time t

Corresponding linearized dual problem

$$\begin{aligned} -\dot{\varphi}_1 - \nu \Delta \varphi_1 &= 0 && \text{in } \omega \times I \\ -\dot{\varphi}_2 - \nu \Delta \varphi_2 + \theta_{,2} + U_{1,2} \varphi_1 &= 0 && \text{in } \omega \times I \\ -\dot{\varphi}_3 - \nu \Delta \varphi_3 + \theta_{,3} + U_{1,3} \varphi_1 &= 0 && \text{in } \omega \times I \\ \varphi_{2,2} + \varphi_{3,3} &= 0 && \text{in } \omega \times I \\ \varphi &= 0 && \text{on } \partial\omega \times I \\ \varphi(\cdot, T) &= \varphi^T && \text{in } \omega \end{aligned}$$

φ_1 decoupled from $\bar{\varphi} = (\varphi_2, \varphi_3)$, so perturbations (stability factors) grow linear with T or Re

ODE-model for transition

Find $w(t) = (w_1(t), w_2(t))$ such that

$$\dot{w}_1 + \nu w_1 - \lambda w_1 w_2 = \nu \quad t > 0$$

$$\dot{w}_2 + 2\nu w_2 - \nu w_2 w_1 = 0 \quad t > 0$$

$$w_1(0) = 1, \quad w_2(0) = \kappa \nu$$

where ν is a small positive parameter, and λ and κ are positive parameters of moderate size

w_1 represents flow in the main direction, and w_2 small transversal velocities

ODE-model for transition

The ODE models the terms

$$\dot{u}_1 + \nu \Delta u_1 - u_{1,2} u_2 = \nu \quad t > 0$$

$$\dot{u}_2 + \nu \Delta u_2 - u_{2,1} u_1 = 0 \quad t > 0$$

from the momentum equations of NSE, assuming the non linear coupling terms are modelled

$$u_{1,2} = -\lambda u_1 \quad \text{and} \quad u_{2,1} = -\nu u_2$$

ODE-model for transition

Find $w(t) = (w_1(t), w_2(t))$ such that

$$\begin{aligned}\dot{w}_1 + \nu w_1 - \lambda w_1 w_2 &= \nu & t > 0 \\ \dot{w}_2 + 2\nu w_2 - \nu w_2 w_1 &= 0 & t > 0 \\ w_1(0) = 1, \quad w_2(0) &= \kappa \nu\end{aligned}$$

Two stationary points: $(1, 0)$ and $(2, \nu/(2\lambda))$

$w = (1, 0)$ is stable, corresponding to Couette flow between two parallel plates or Poiseuille flow in a pipe, and $(2, \nu/(2\lambda))$ is unstable

ODE-model for transition

Find $w(t) = (w_1(t), w_2(t))$ such that

$$\begin{aligned} \dot{w}_1 + \nu w_1 - \lambda w_1 w_2 &= \nu & t > 0 \\ \dot{w}_2 + 2\nu w_2 - \nu w_2 w_1 &= 0 & t > 0 \\ w_1(0) = 1, \quad w_2(0) &= \kappa \nu \end{aligned}$$

We shall show how a small perturbation $\kappa \nu$ may take the flow from the stable base flow $(1, 0)$ to the unstable flow $(2, \nu/(2\lambda))$ if $\lambda \kappa$ is larger than some critical value of moderate size

ODE-model for transition

Find $w(t) = (w_1(t), w_2(t))$ such that

$$\dot{w}_1 + \nu w_1 - \lambda w_1 w_2 = \nu \quad t > 0$$

$$\dot{w}_2 + 2\nu w_2 - \nu w_2 w_1 = 0 \quad t > 0$$

$$w_1(0) = 1, \quad w_2(0) = \kappa \nu$$

We see that w_1 will grow as long as $\lambda w_2 > \nu$, and w_2 starts to grow when $w_1 > 2$

ODE-model for transition

Find $w(t) = (w_1(t), w_2(t))$ such that

$$\dot{w}_1 + \nu w_1 - \lambda w_1 w_2 = \nu \quad t > 0$$

$$\dot{w}_2 + 2\nu w_2 - \nu w_2 w_1 = 0 \quad t > 0$$

$$w_1(0) = 1, \quad w_2(0) = \kappa \nu$$

If w_1 reaches the value 2 before w_2 gets below ν/λ , then (w_1, w_2) will blow up, corresponding to instability

Linearized equations at $(1, 0)$

$$\begin{aligned}\dot{\varphi}_1 + \nu\varphi_1 - \lambda\varphi_2 &= \nu & t > 0 \\ \dot{\varphi}_2 - \nu\varphi_2 &= 0 & t > 0 \\ \varphi_1(0) = 0, \quad \varphi_2(0) &= \kappa\nu\end{aligned}$$

Linearized equations at $(1, 0)$

$$\begin{aligned}\dot{\varphi}_1 + \nu\varphi_1 - \lambda\varphi_2 &= \nu & t > 0 \\ \dot{\varphi}_2 - \nu\varphi_2 &= 0 & t > 0 \\ \varphi_1(0) = 0, \quad \varphi_2(0) &= \kappa\nu\end{aligned}$$

We have

$$w_1(t) \approx 1 + \lambda\kappa t\nu \exp(-t\nu), \quad w_2(t) \approx \kappa\nu \exp(-t\nu)$$

which shows slow growth in w_1 and slow decay in w_2 over a long time scale prior to the blow up, occurring if $\lambda\kappa$ is above a certain threshold

Computational experiment 1

'Poiseuille flow' driven by a force

$$f = (32\nu(x_2(1 - x_2) + x_3(1 - x_3)), 0, 0)$$

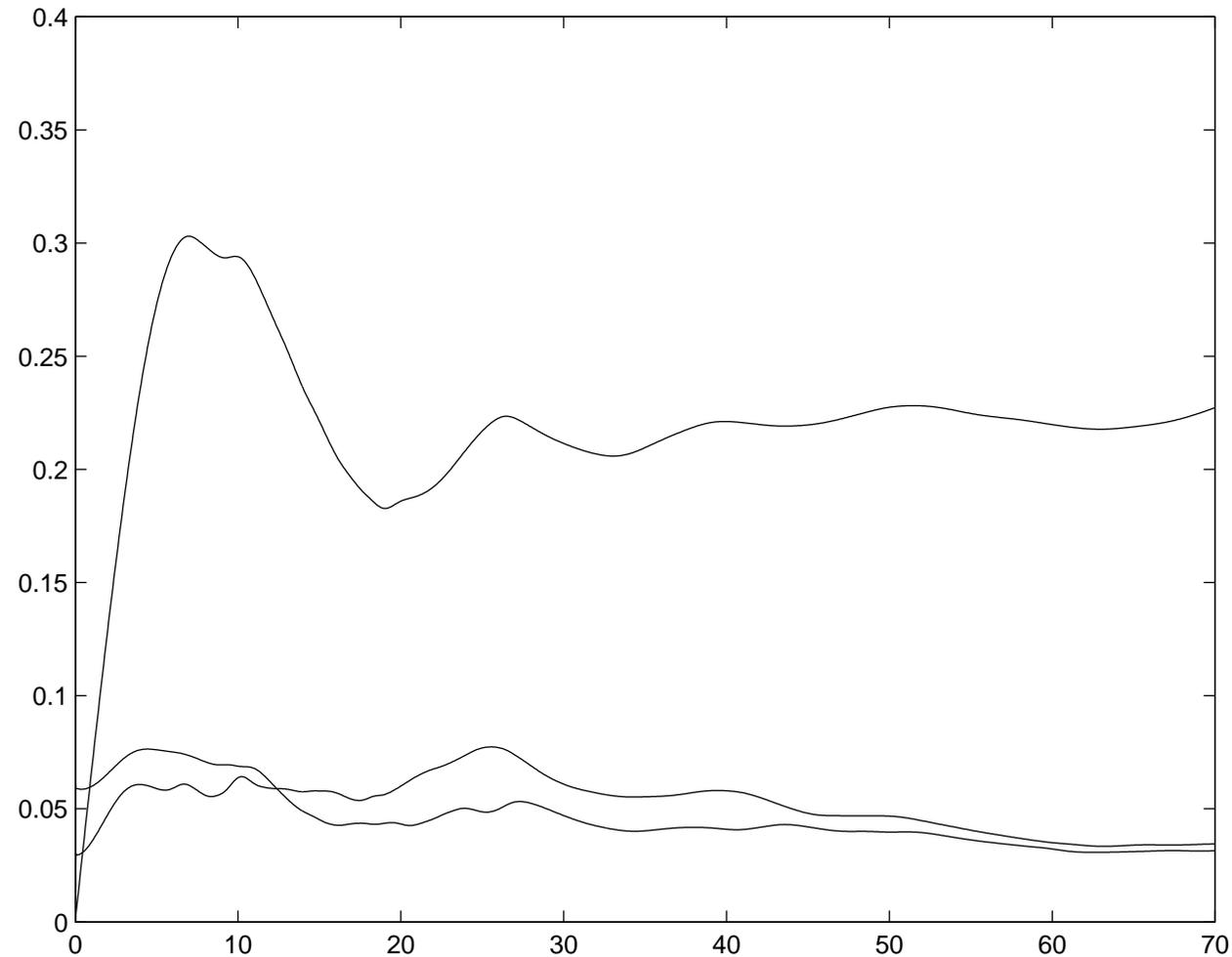
- rectangular cross section 1×1
- no slip b.c. at walls
- periodic b.c. in streamwise direction
- cG(1)cG(1) method, regular tetrahedral mesh with $h = 1/64$

Computational experiment 1

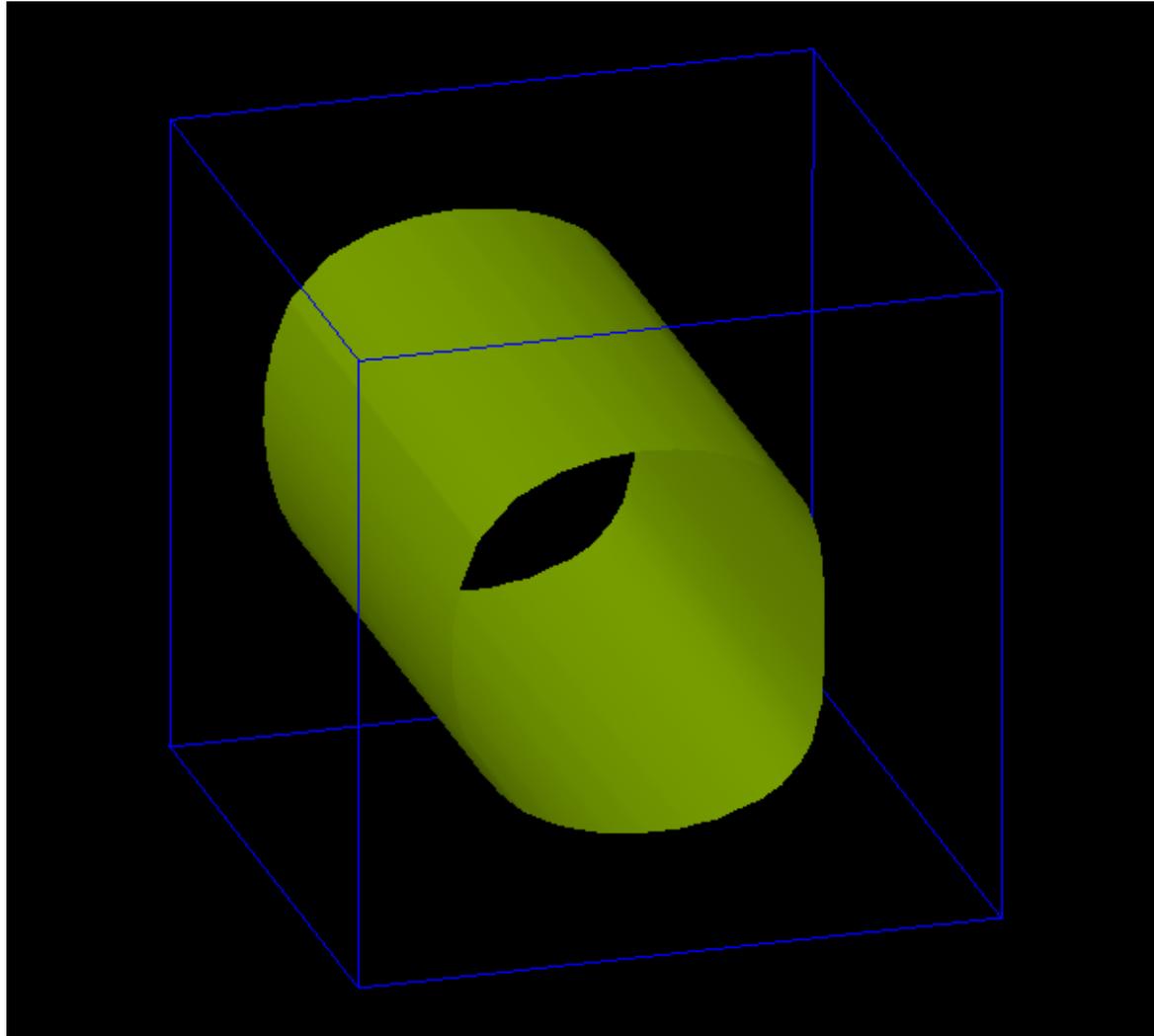
- small initial transversal perturbation $\bar{\varphi}(x_2, x_3)$ of order 0.1
- very small x_1 -dependent driving force of order 10^{-3} creating and sustaining very small streamwise variation

•
•
•

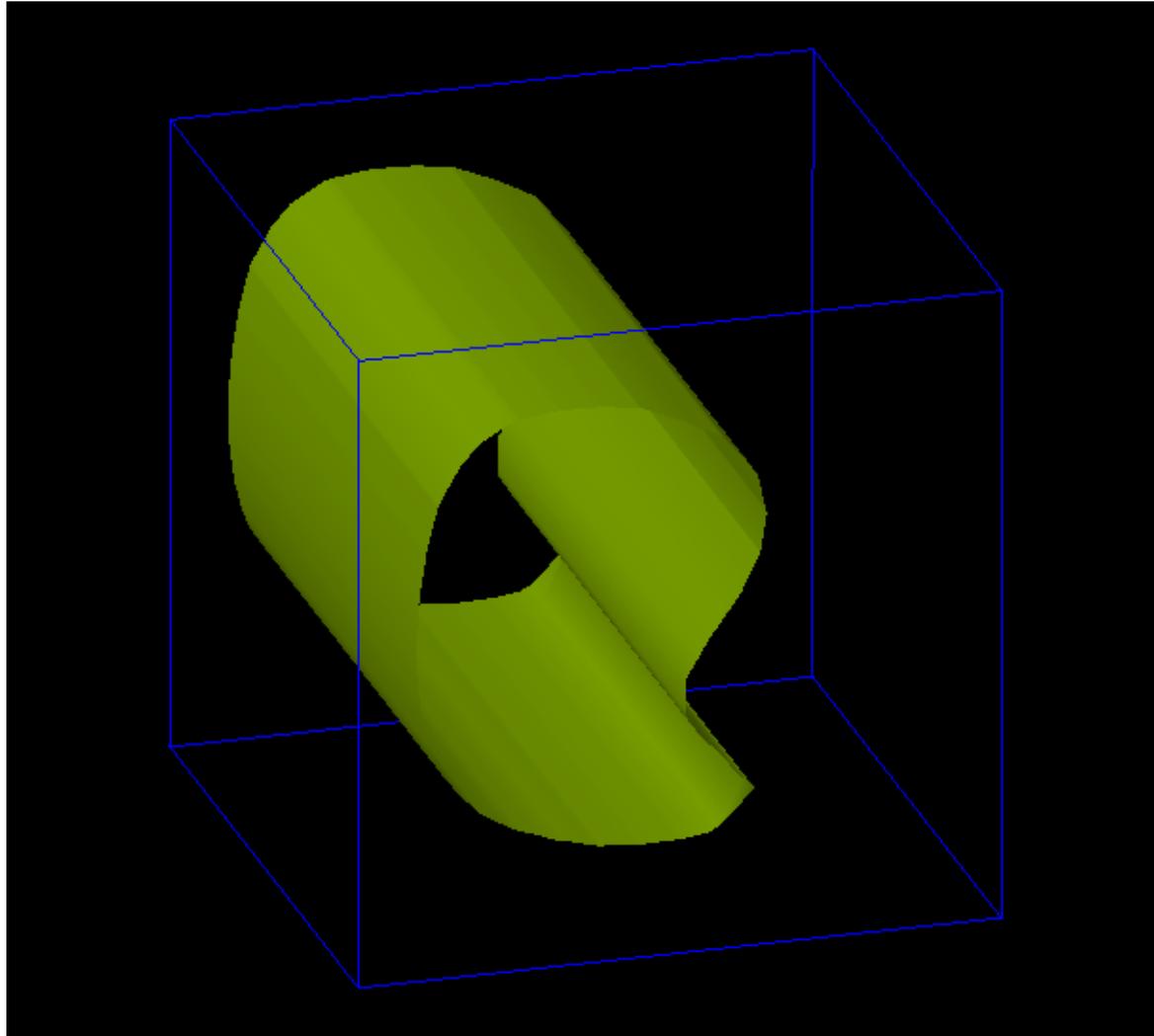
$\|\varphi_1\|$, $\|\varphi_2\|$, $\|\varphi_3\|$, linear growth in $\|\varphi_1\|$



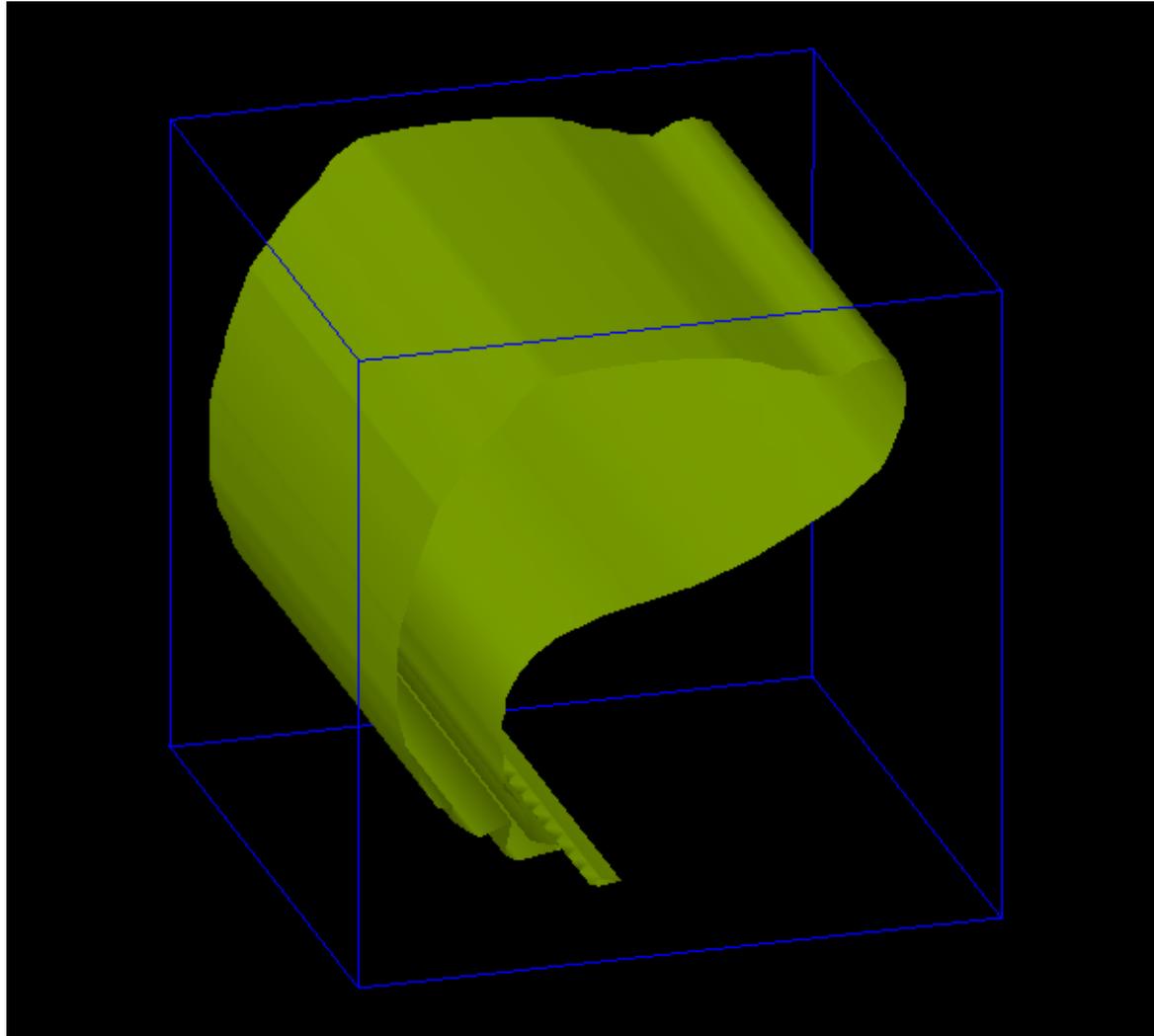
•
•
•
 $\varphi_1, \quad t = 1$ (Taylor-Görtler mech.)



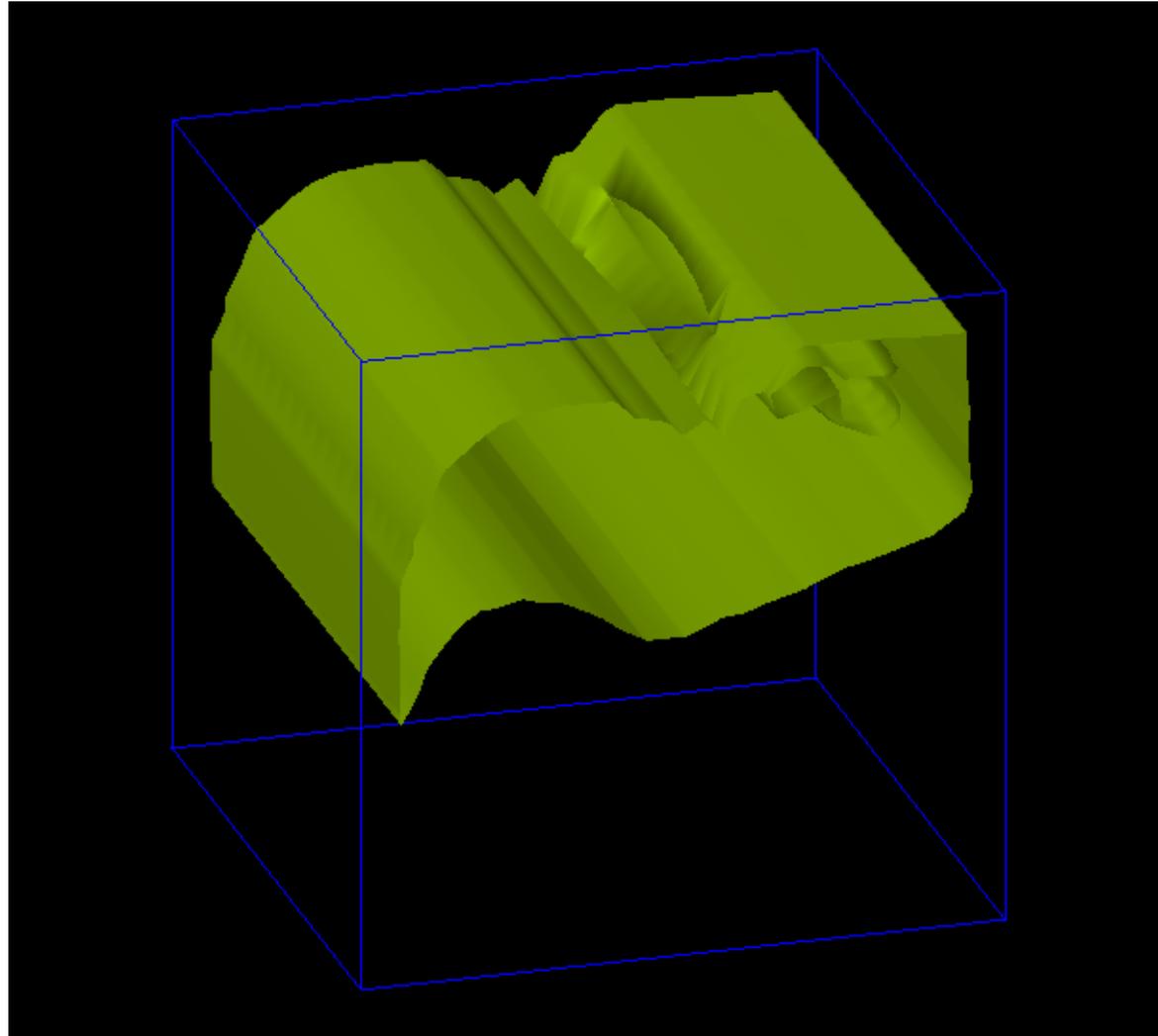
•
•
•
 $\varphi_1, \quad t = 3$ (Taylor-Görtler mech.)



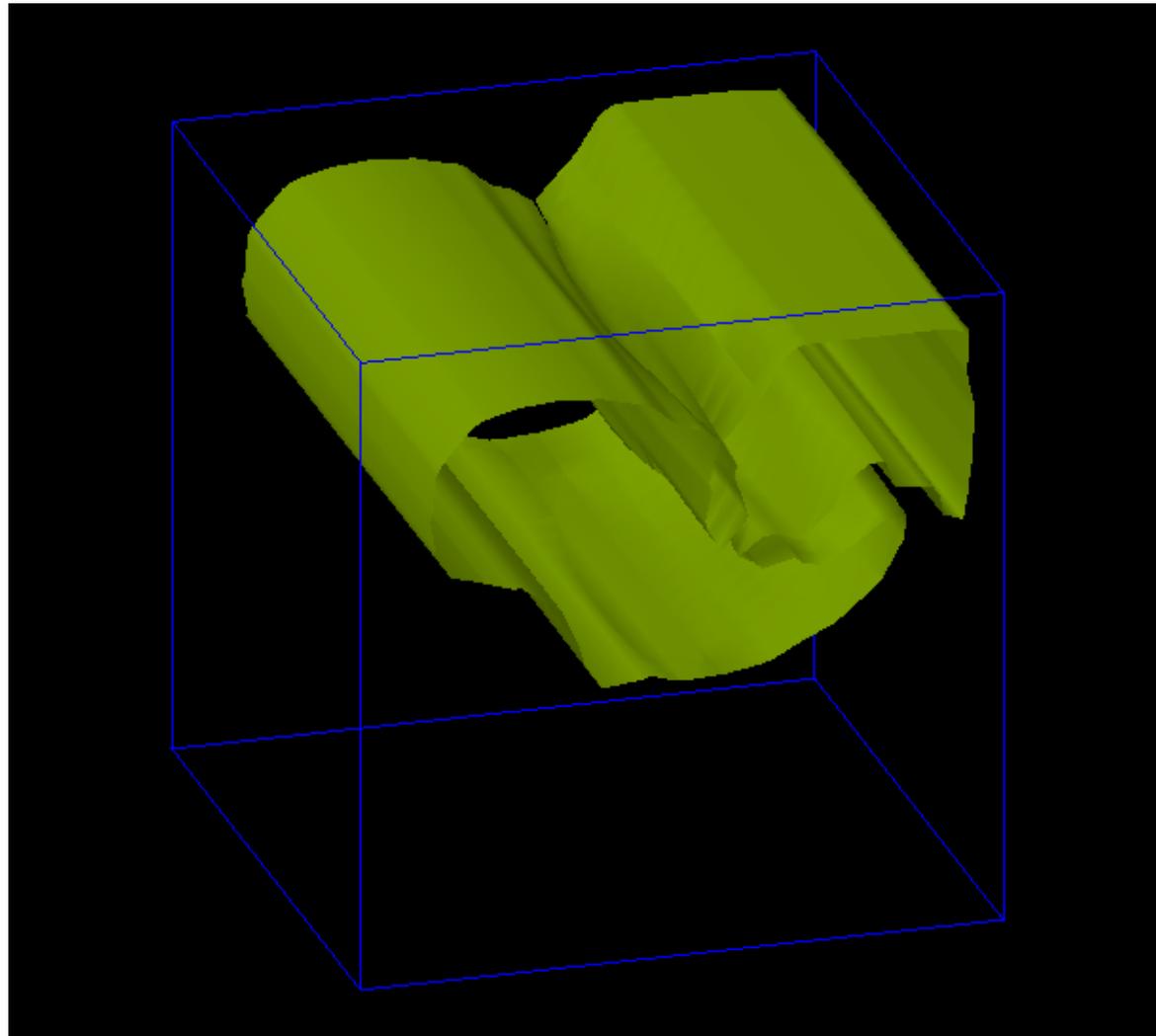
•
•
•
 $\varphi_1, \quad t = 6$ (Taylor-Görtler mech.)



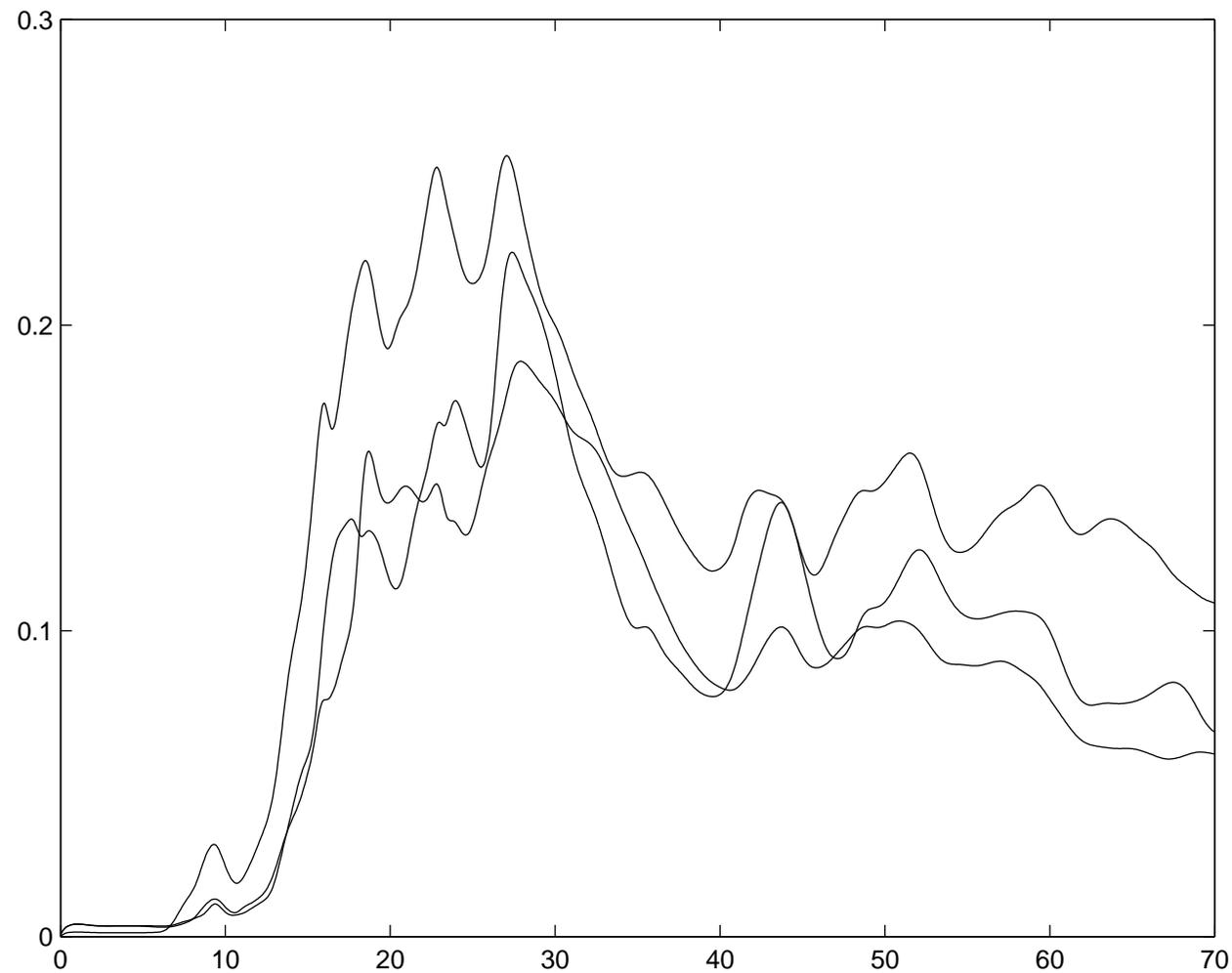
•
•
•
 $\varphi_1, \quad t = 9$ (Taylor-Görtler mech.)



•
•
•
 $\varphi_1, \quad t = 12$ (Taylor-Görtler mech.)



$$\|du_i/dx_1\|$$



Computational experiment 2

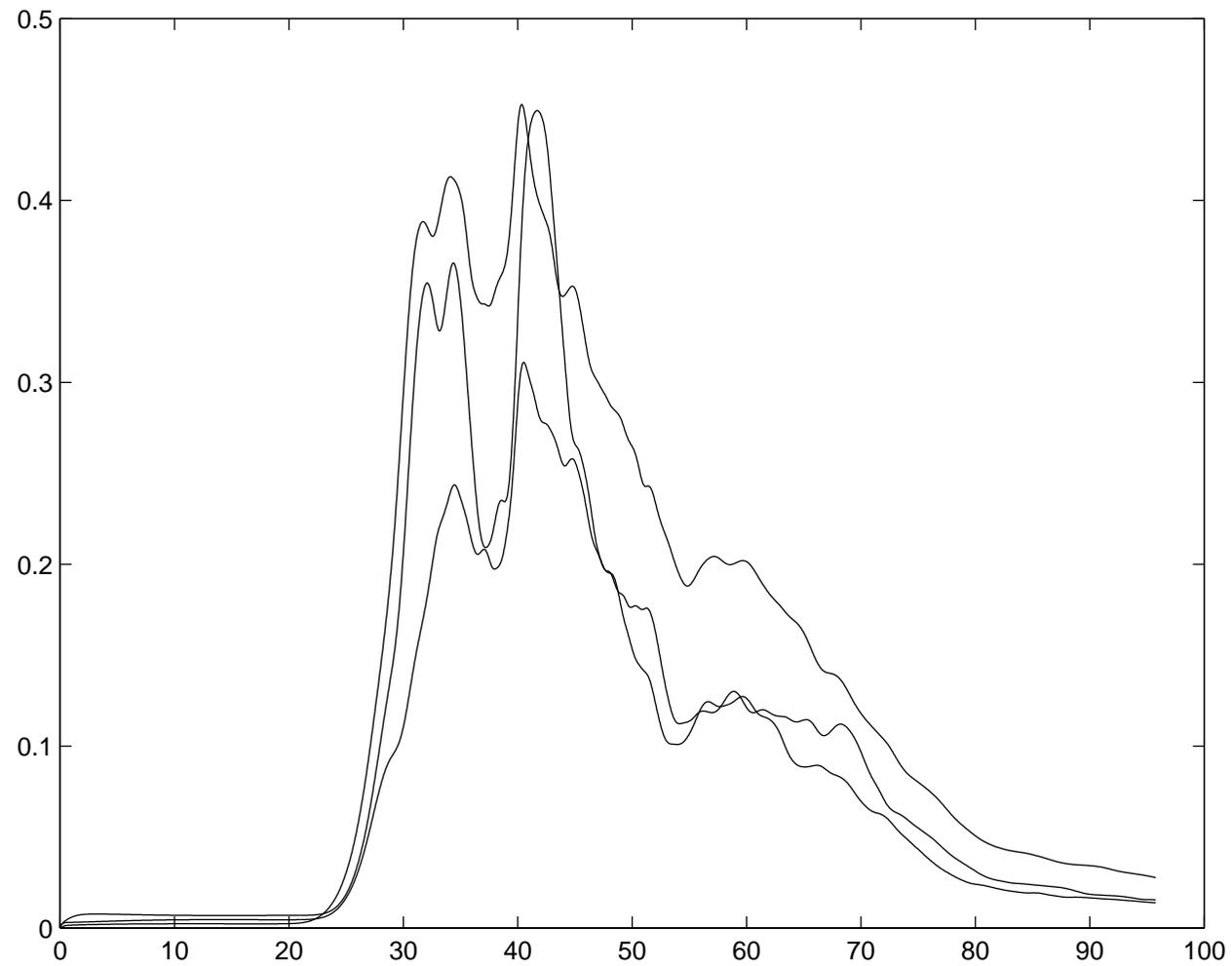
Couette flow driven by ± 1 on the top and bottom

- rectangular cross section 1×1
- slip b.c. at spanwise walls
- periodic b.c. in streamwise direction
- cG(1)cG(1) method, regular tetrahedral mesh with $h = 1/64$

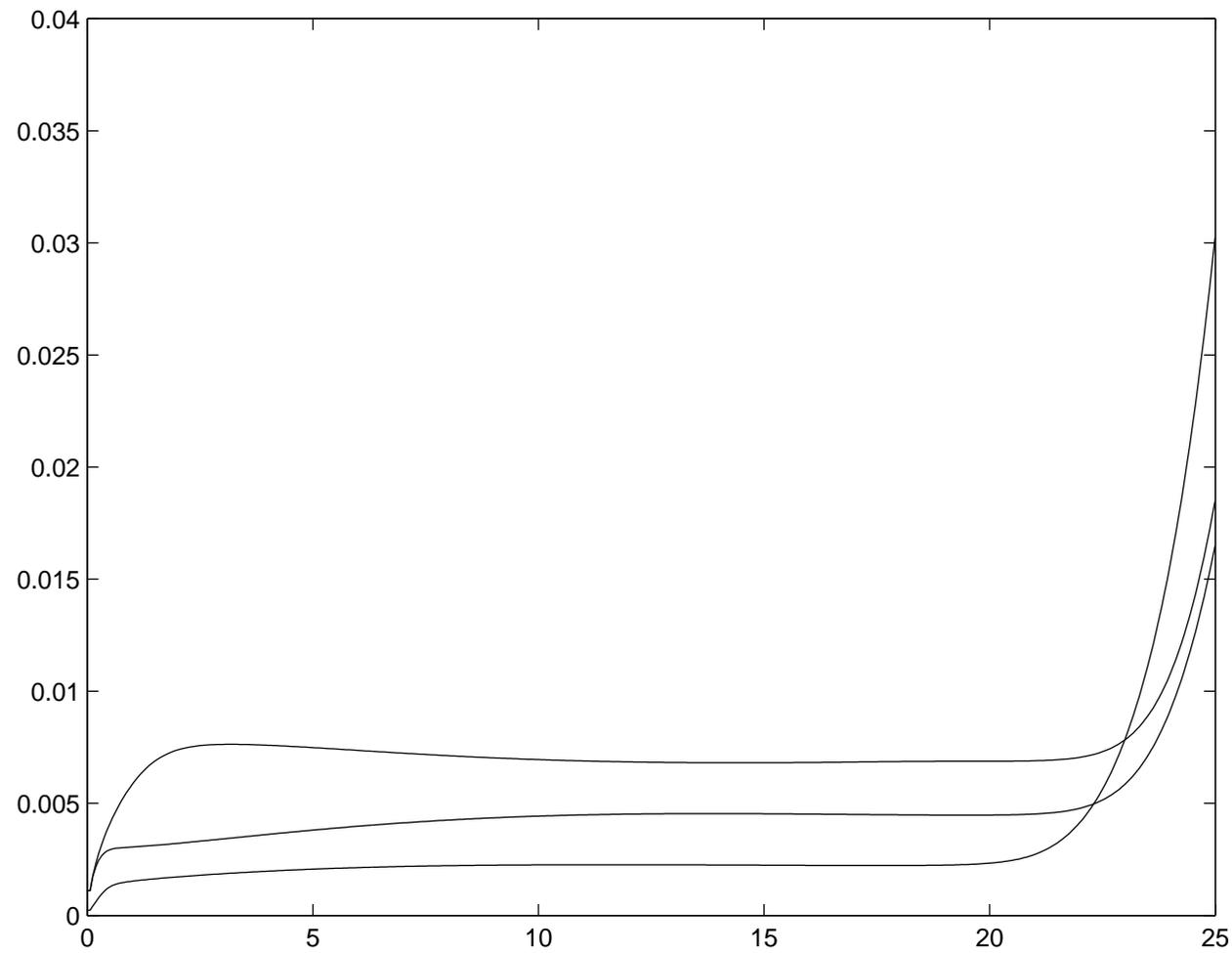
Computational experiment 2

- small initial perturbation $\bar{\varphi}(x_2, x_3)$ of order 0.1
- very small x_1 -dependent driving force of order 10^{-3} creating and sustaining very small streamwise variation

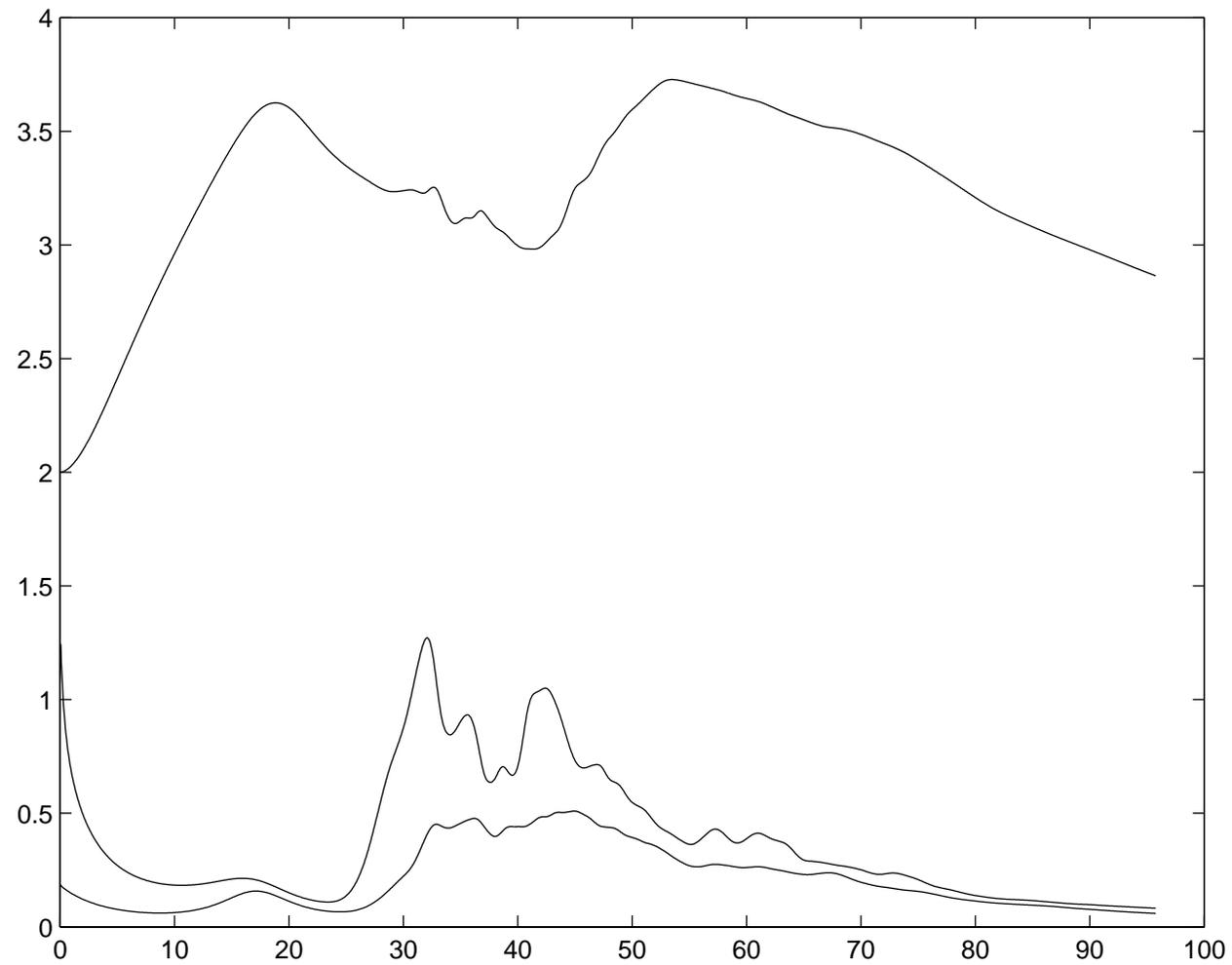
$$\|du_i/dx_1\|$$



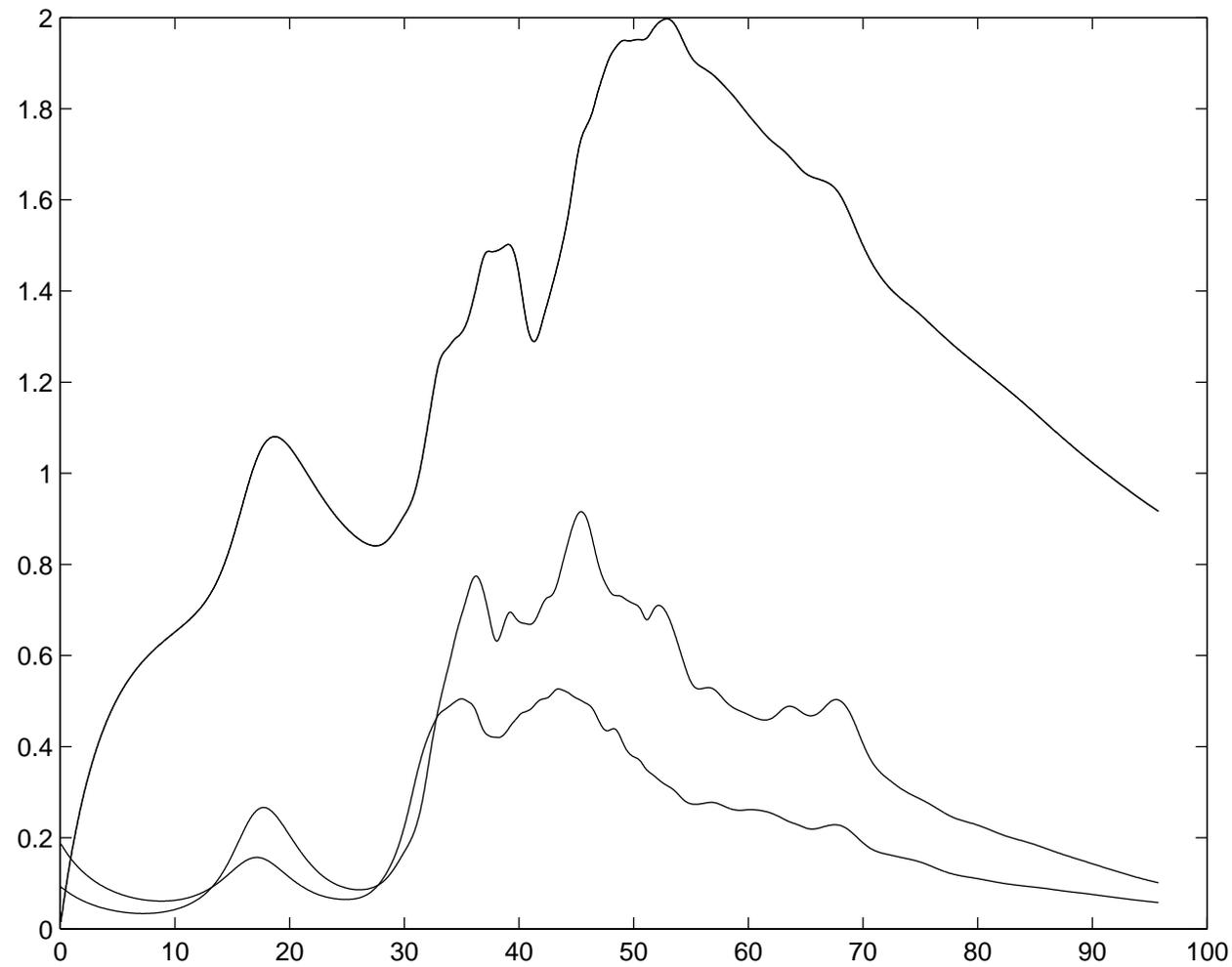
$$\|du_i/dx_1\|$$



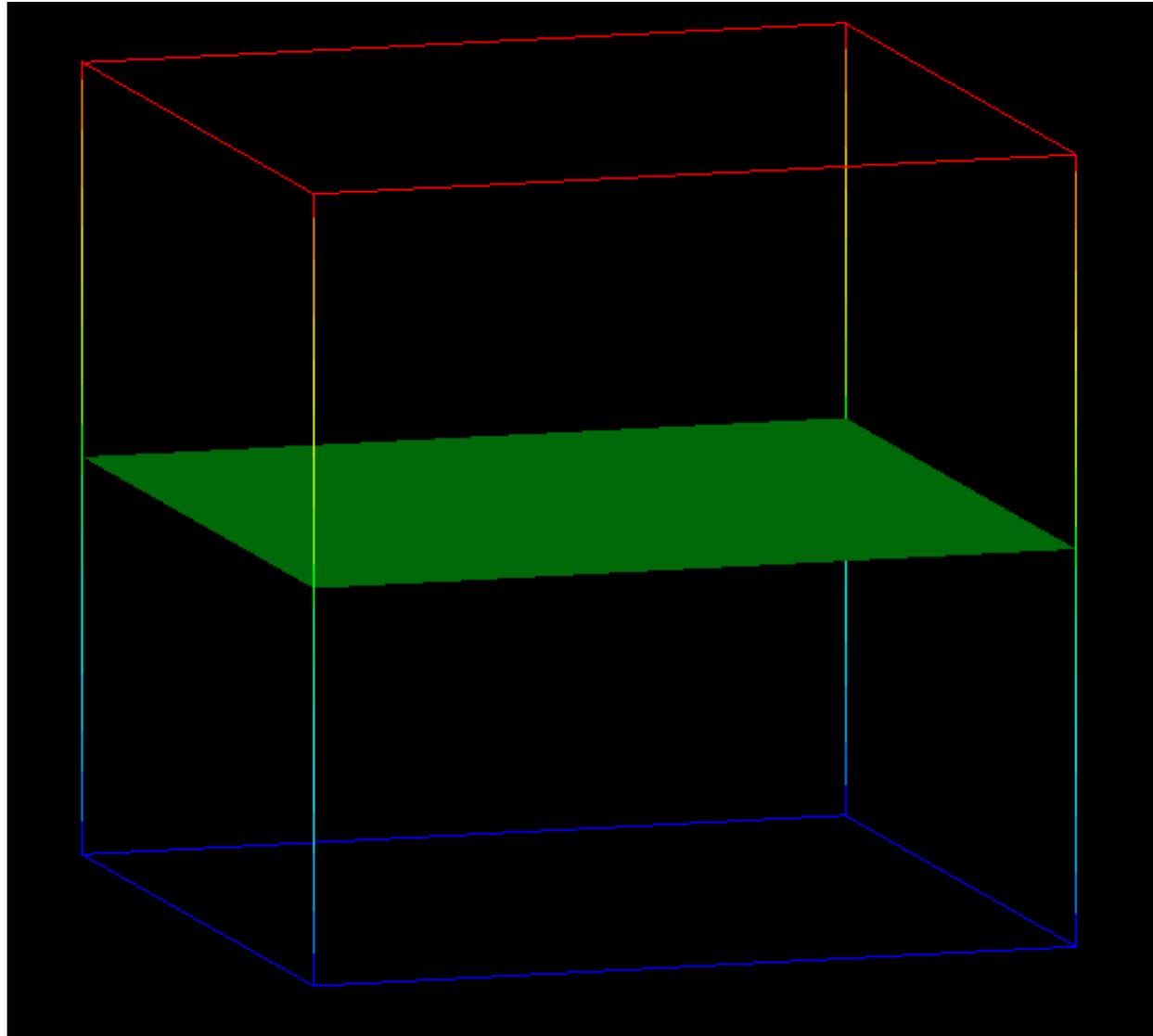
$$\|du_i/dx_2\|$$



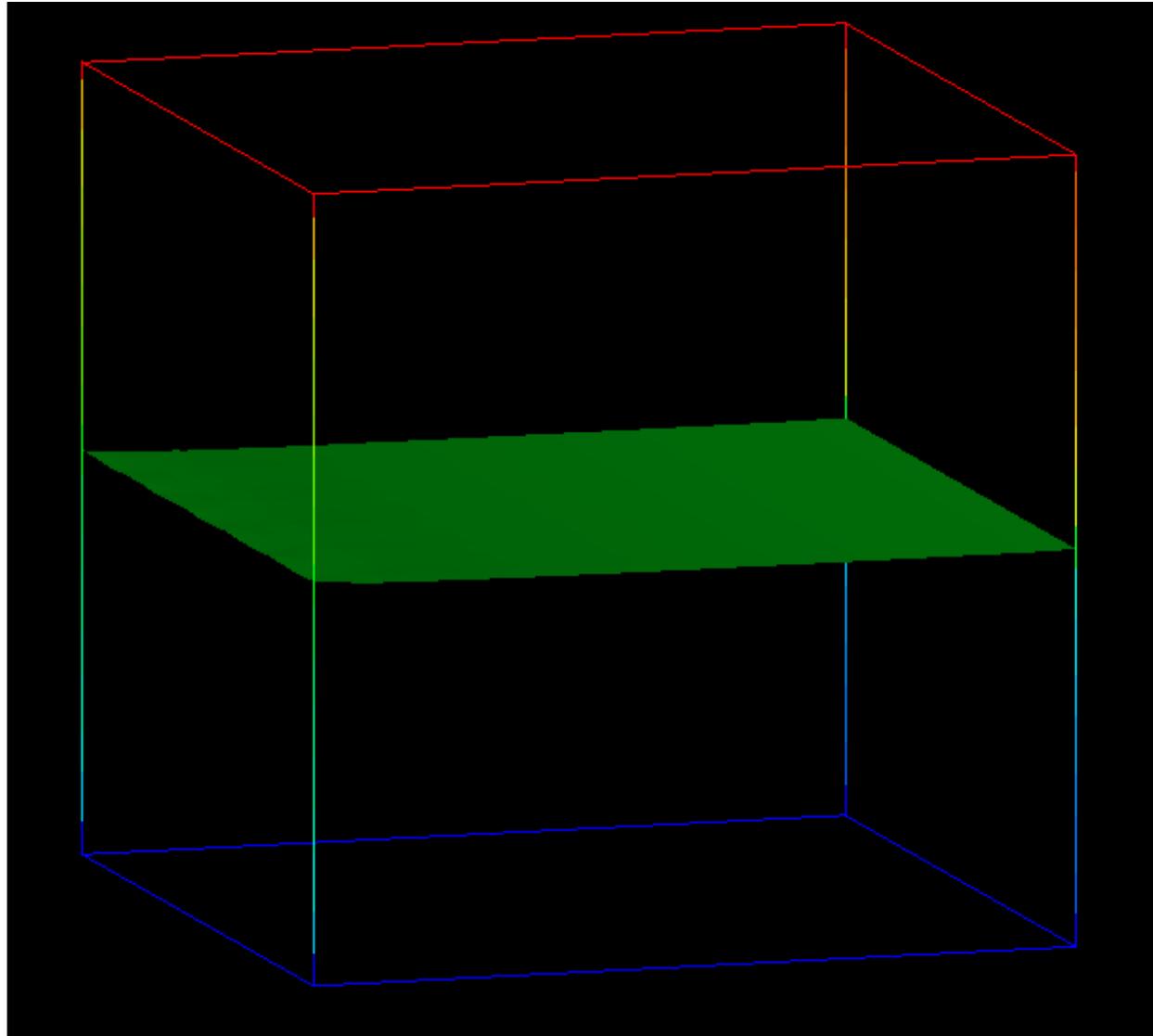
$$\|du_i/dx_3\|$$



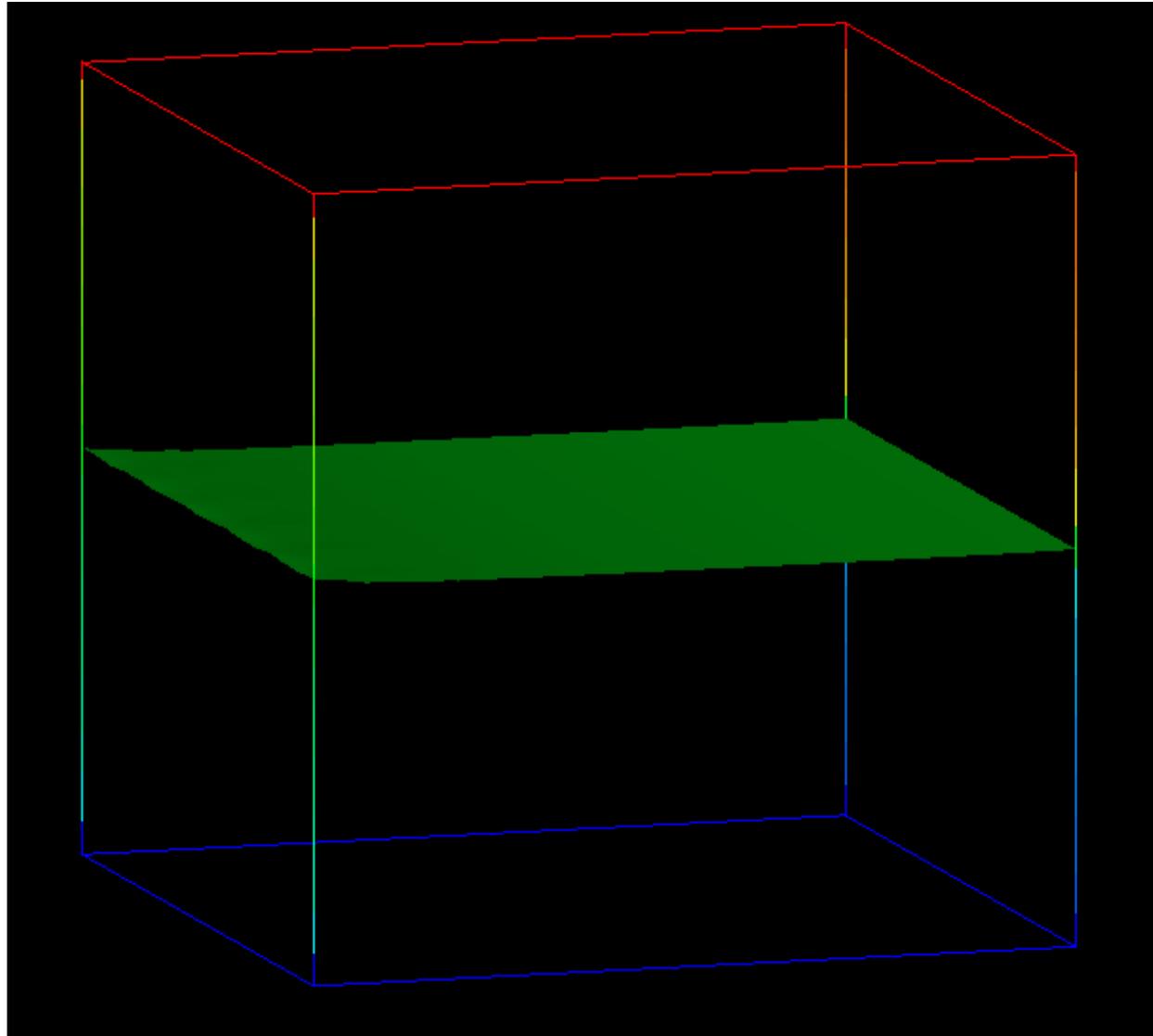
$\varphi_1, \quad t = 0, \quad \text{isosurface for } u_1 = 0$



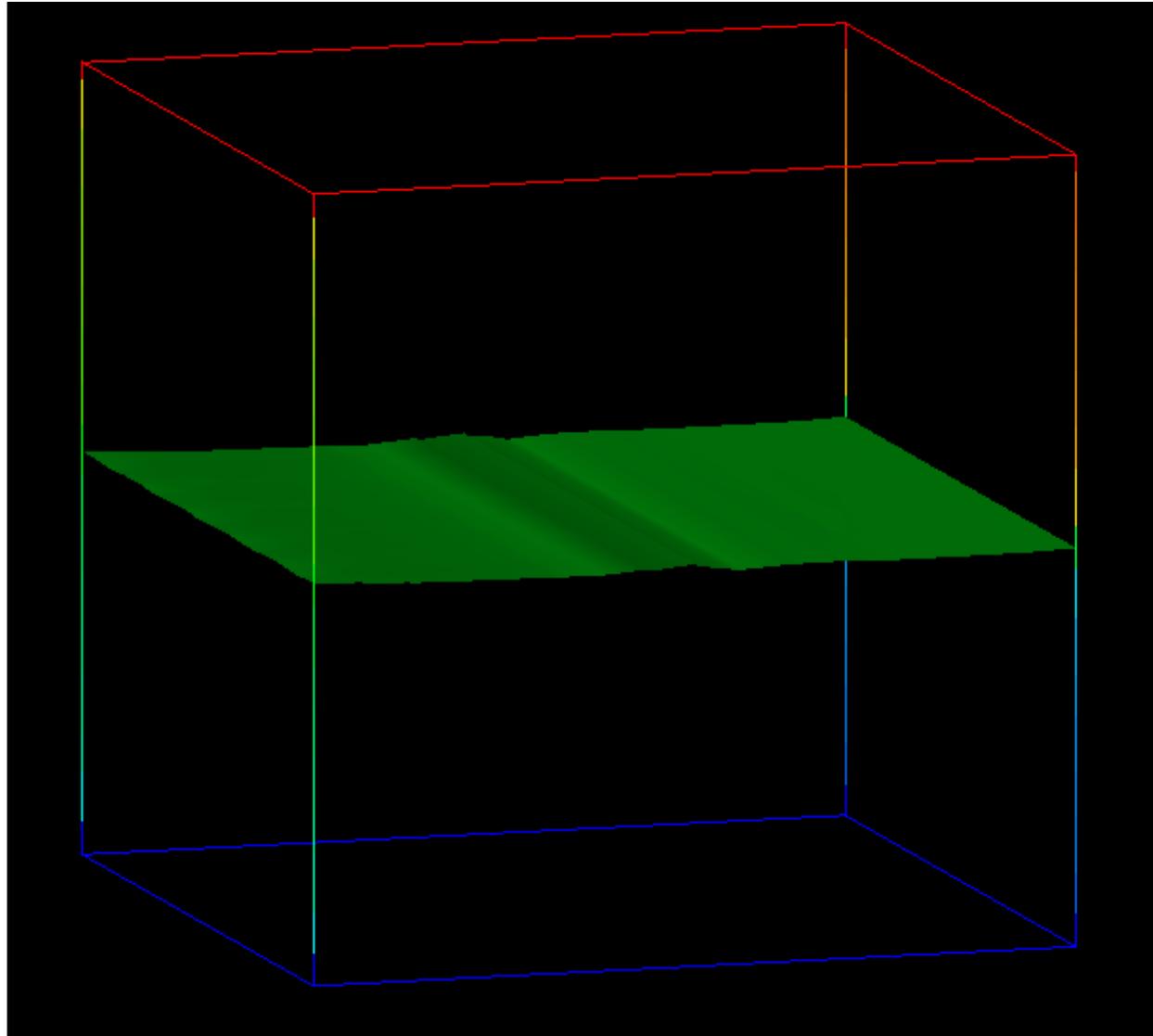
•
•
•
 $\varphi_1, \quad t = 5, \quad \text{isosurface for } u_1 = 0$



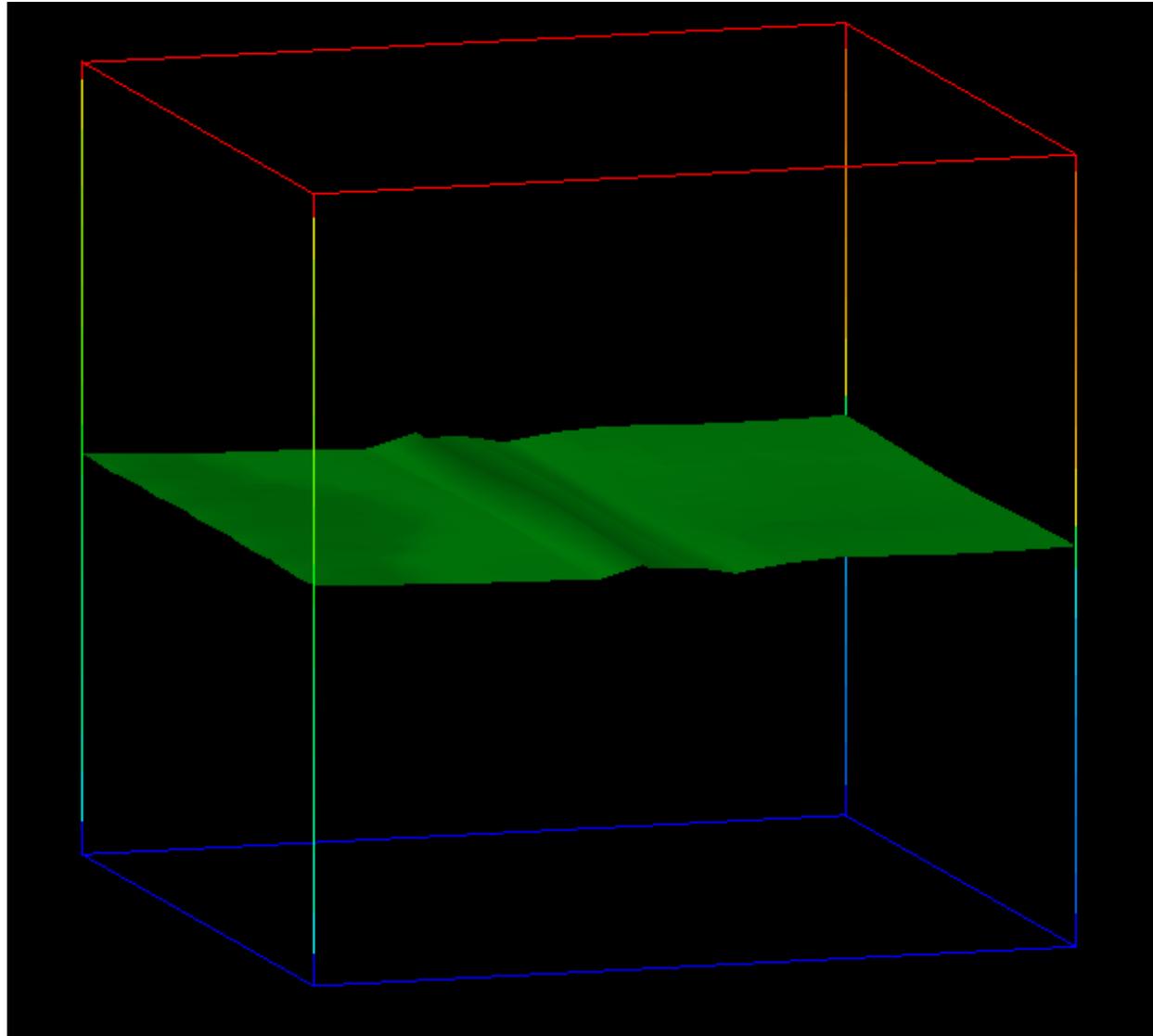
φ_1 , $t = 10$, **isosurface for $u_1 = 0$**



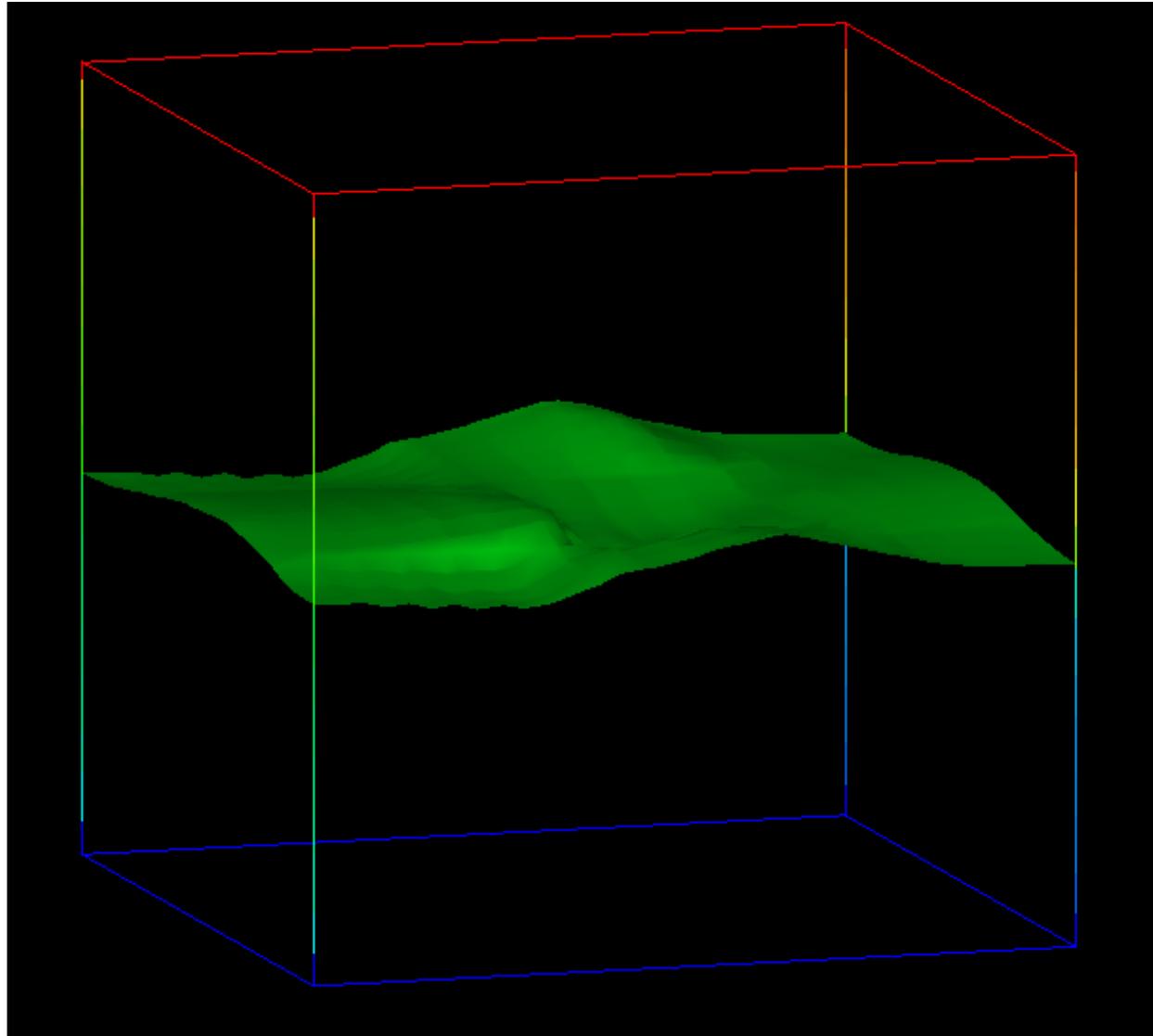
φ_1 , $t = 20$, **isosurface for $u_1 = 0$**



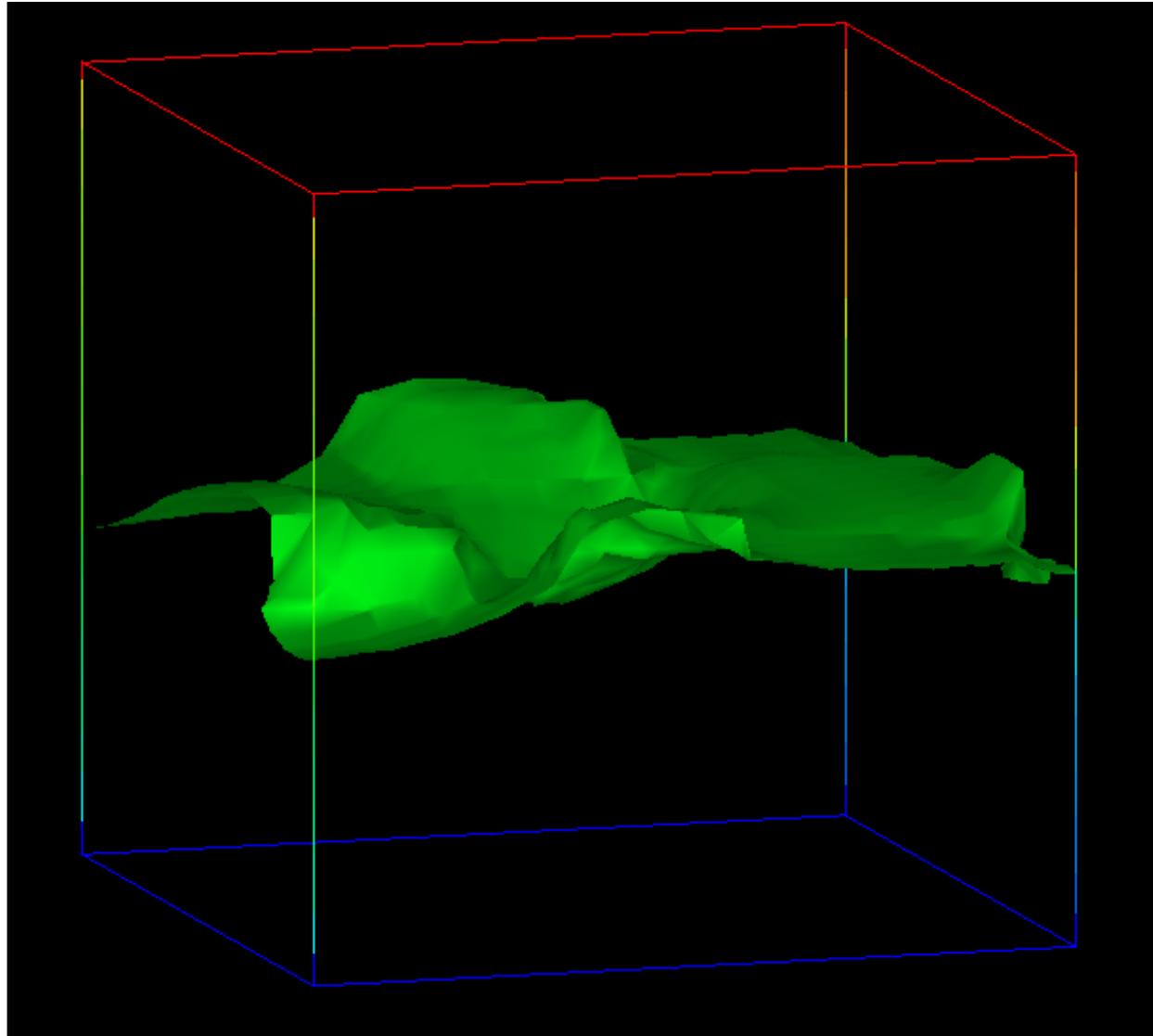
φ_1 , $t = 25$, **isosurface for $u_1 = 0$**



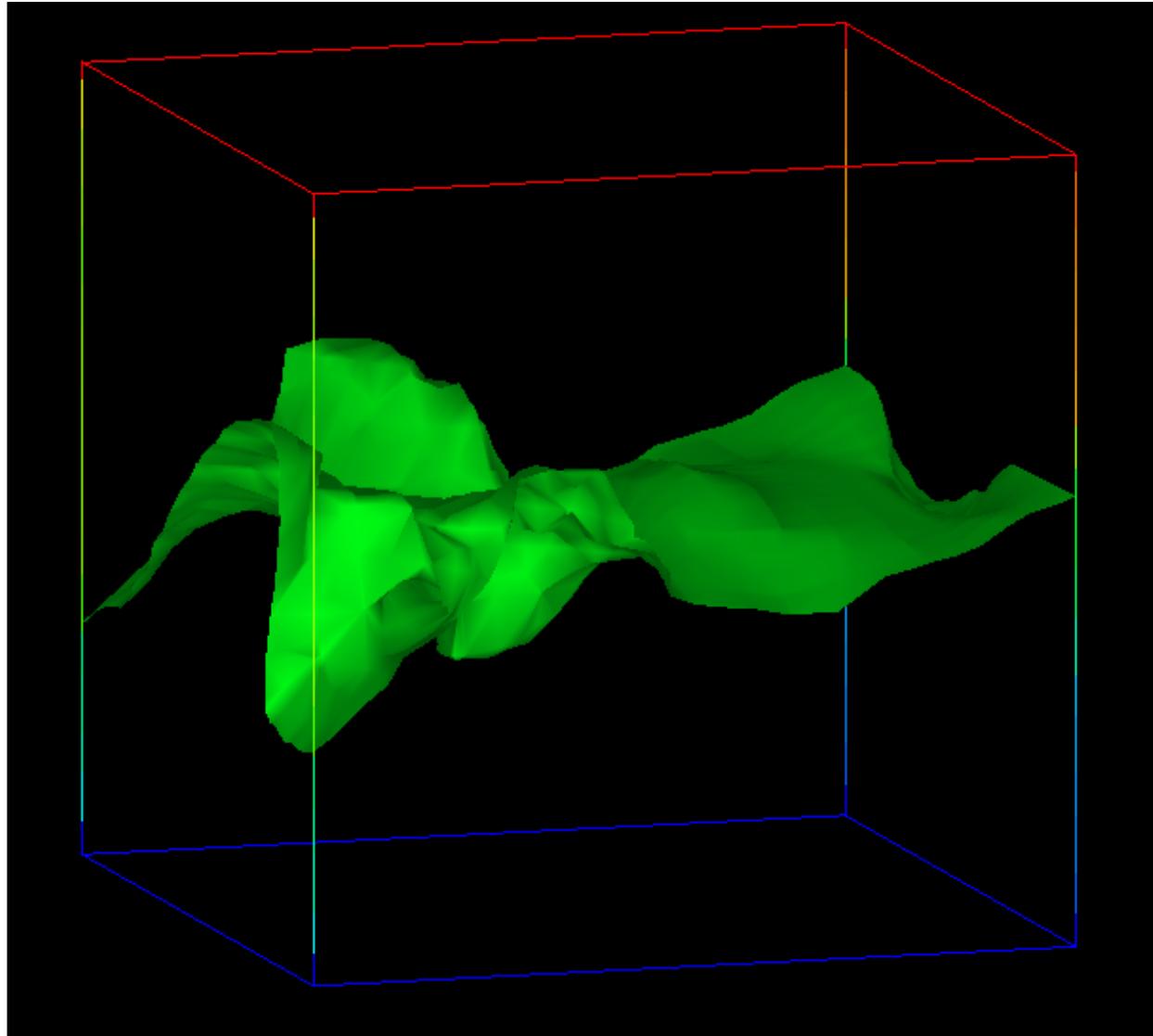
•
•
•
 $\varphi_1, \quad t = 30, \quad \text{isosurface for } u_1 = 0$



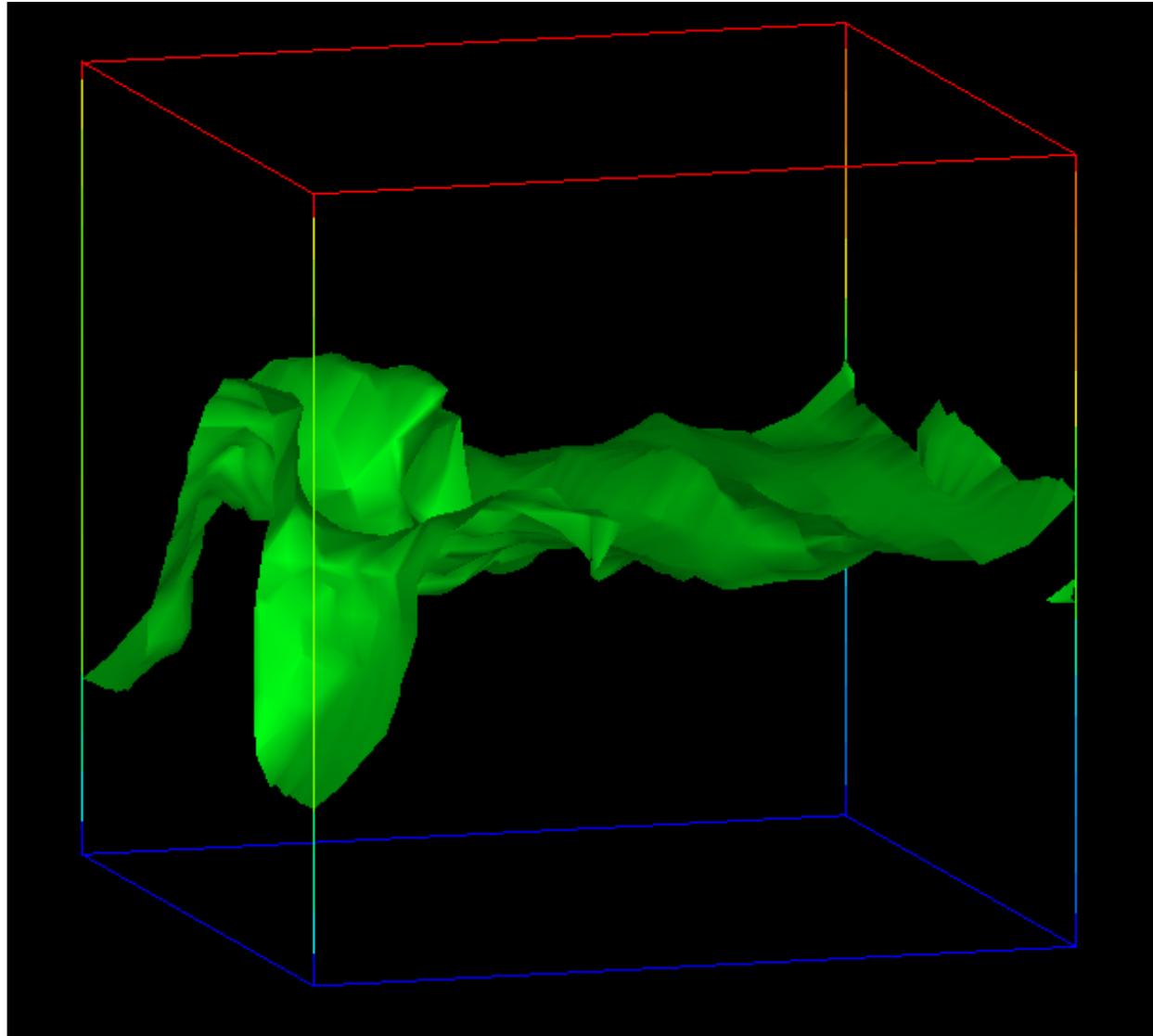
•
•
•
 $\varphi_1, \quad t = 32, \quad \text{isosurface for } u_1 = 0$



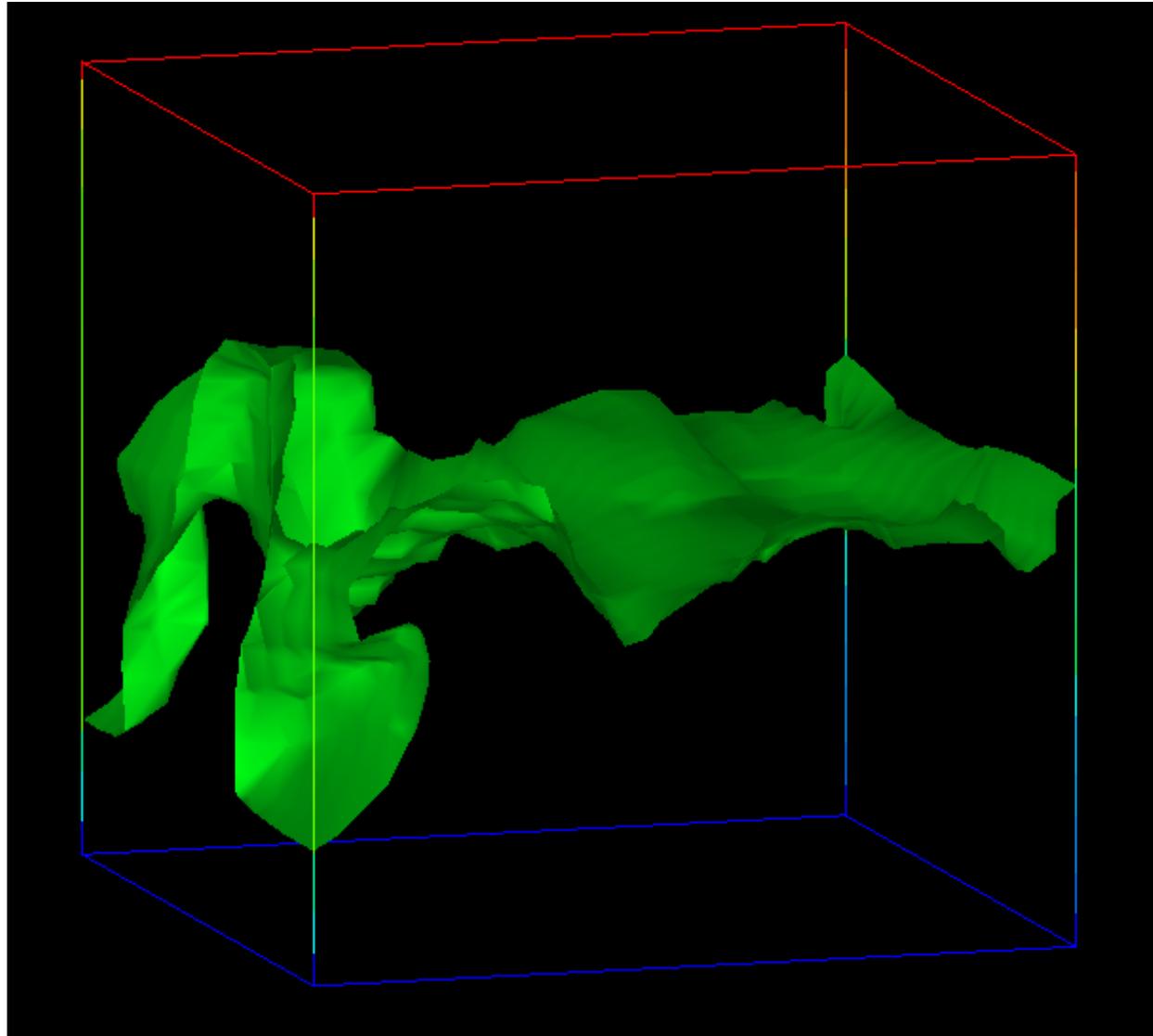
•
•
•
 $\varphi_1, \quad t = 34, \quad \text{isosurface for } u_1 = 0$



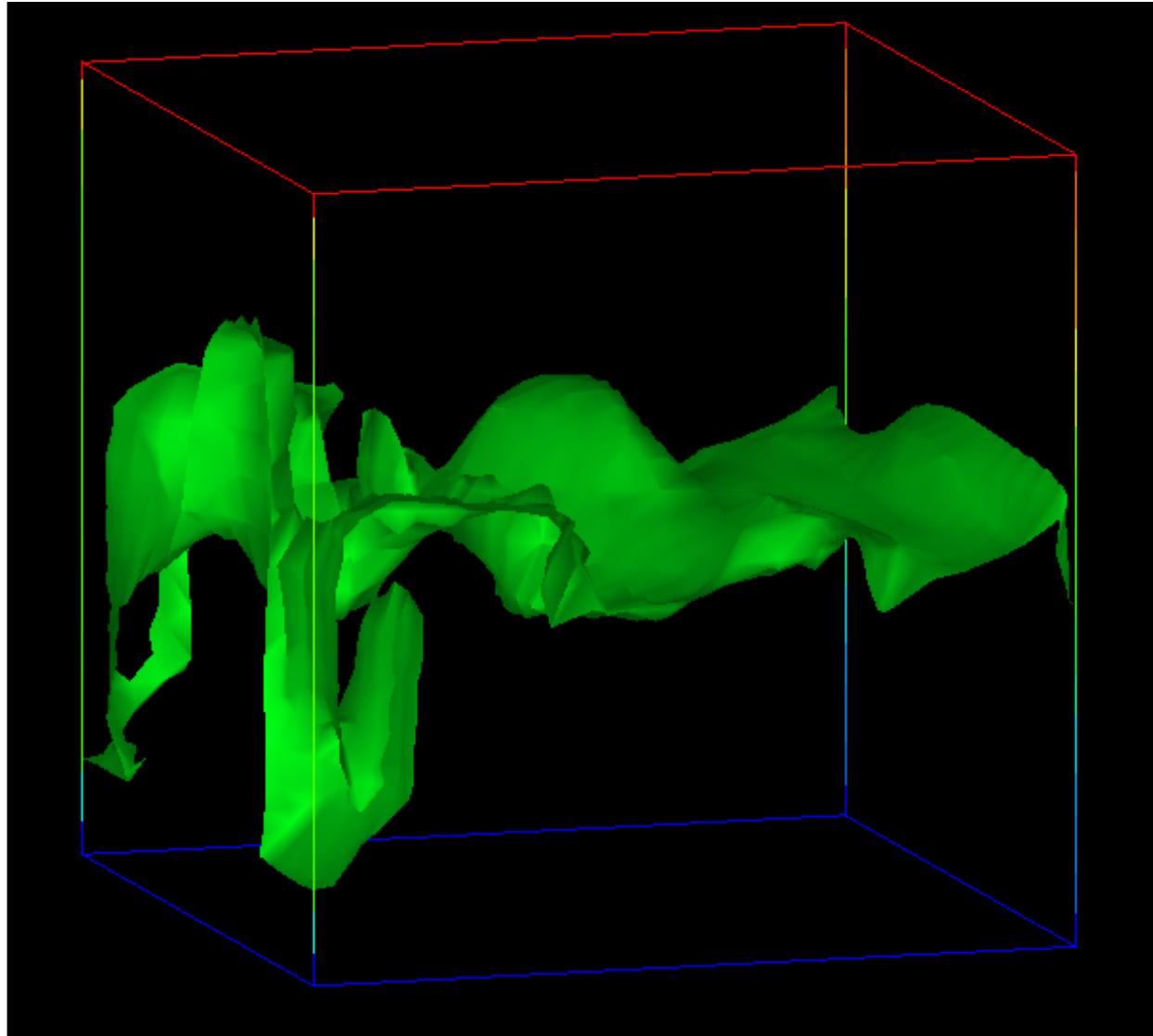
•
•
•
 $\varphi_1, \quad t = 36, \quad \text{isosurface for } u_1 = 0$



φ_1 , $t = 38$, **isosurface for $u_1 = 0$**



•
•
•
 $\varphi_1, \quad t = 40, \quad \text{isosurface for } u_1 = 0$



Transition scenario

1. Lin. growth in φ_1 (Taylor-Görtler mechanism),
 du_1/dx_2 and du_1/dx_3
2. Initial decrease in φ_2, φ_3 , and du_i/dx_j for
 $i, j = 1, 2$
3. Suddenly (Couette $t \approx 22$, Poiseuille $t \approx 6$) all
derivatives grows exponentially
(x_1 -derivatives increases by a factor 100)

Comments

- The predictions of the ODE-model are verified by the numerical experiments
- Both computational experiments are questionable after the transition, due to coarse meshes and large stability factors

Summary, lecture 2

- Linearized dual problems contain information about the error propagation for different error measures
- In general are global quantities easier to compute than local quantities
- Even for dual problems linearized at a very irregular primal solution, global quantities may be computable (due to cancelations in the dual solution)

Summary, lecture 2

- Linear perturbation growth in streamwise velocity possible from small initial transversal perturbations (Taylor-Görtler mechanism)
- ODE-model explaining transition to turbulence from small initial perturbations